

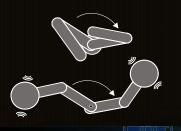


Inheriting State-of-the-Art Technology for Robot Control — Robust Control

The SD3 Servo Amplifier is equipped with servo control which takes advantage of our expertise in LCD and semiconductor robotics. Decoupling command responsiveness and disturbance compensation using observerbased model matching and feedforward, our Servo Amplifier offers control for two degrees of freedom.

Even under load fluctuations, you can expect smooth motion without needing to change tuning parameters. This control method is ideal for applications with high rigidity such as ball drives, where you will experience excellent command responsiveness.





[Robust Control]

Robust Control is a control method which maintains expected robustness and stability even when the actual specifications of robots are slightly different from the initially intended control model.

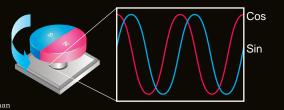


Ultimate Toughness and Low Current Consumption — Magnetic Absolute Encoder

No other type of encoder matches the ultimate toughness of the magnetic rotary encoder - which is its greatest advantage. Magnetic rotary encoders are resistant to oil and dust, and exhibit robust power in harsh production environments. SD3 original 1 pole magnetic absolute encoder has a straightforward, hard-to-break structure, and its resolution is comparable to optical encoders. Our new encoder is your one-stop solution for the ever-challenging threesome of goals: "toughness in harsh environments", "resolution", and "cost".

Also, our encoder features battery-free single-turn absolute position detection. Furthermore, its current consumption upon battery backup is among the lowest in the industry.

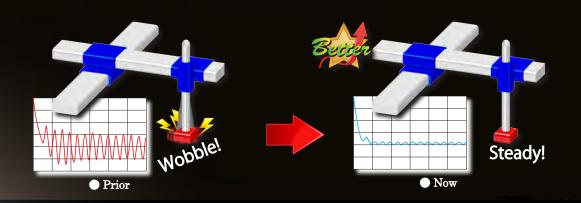






Learning in the Field and Constantly Evolving — Amplifier Performance

Our new stronger damping filter helps your machine better suppress machine tip wobbles. With the newly developed " γ -notch" filter, you may flexibly set responsiveness in frequency ranges higher than the notch frequency. Our new Servo offers shorter settling time for positioning, while maintaining the same damping features as before.





Specialized Tool Based on Ergonomics — Servo Studio

Servo studio is a powerful Software that eases setup, tuning, state monitoring, and effective use of SD3 Servo Amplifier. Now with its enhanced features, Servo studio is even more user-friendly and powerful.

With the greatly enhanced functionality, you can now setup our new damping filter from the intuitive interface, use an additional function "vibration noise frequency measurement (FFT)", and get a log of the amplifier alarm.

In addition, smooth startup of your machine is facilitated through an amplifier point table (that can be set up to 16 points), and the test run features.

D

MODELS

Amplifiers



Rated output



Rated output





Rated output



Model Number

SD3 01	0 C	Ζ	*	*		
			L	Specificati	ons	
Series				Code	Specificati	ions
				11	Standard	
				12	Standard	
				Le Master		
				le Motor		
			ode N	lodel		Rated Output
		Y	N	1 005C		50 W
		Z	Ν	10010C		100 W
		1	Ν	1□□020C□	**	200 W
		2	Ν	10040C	 **	400 W
		3	Ν	1□□075C□	**	750 W
		4	Ν	100C	**	1000 W
		6	N	100150C	*	1500W
		8	Ν	100200C	**	2000W
		nput Powe	or Cuppl			
		· · · · · · · · · · · · · · · · · · ·	· · ·			
		ode		Circuit Power		rol Power
			AC200	V to 240 V ^(*)	DC24	V
				option depends	on compatible r	notor.
		50 W to 750 1 kW		gle-phase gle-phase / Thre	e-phase	
		1.5 kW, 2 kW		ee-phase		
L			<u>с і</u>			
	Main Circu	1				
	Code	Supply				
	005		W			
	010	100				
	020	200	W			
	040	400	W			

750 W

1000W

1500W

2000W

Amplifier / Motor Combinations

080 100

150

200

Rated Output	Amplifier Model	Motor Model
50 W	SD3005CY**	M005C **
100 W	SD3010CZ**	M010C **
200 W	SD3020C1**	M020C **
400 W	SD3040C2**	M040C **
750 W	SD3075C3**	M075C **
1000W	SD3100C4**	M100C **
1500W	SD3150C6**	M150C **
2000W	SD3200C8**	M200C **



5 AMPLIFIER SPECIFICATIONS

Basic Specifications

Dasic Spo	ecifications											
	ltem		Specifications SD3005CY** SD3010CZ** SD3020C1** SD3040C2** SD3080C3** SD3100C4** SD3150C6** SD3200C8**									
	Model	SD3005CY**	SD3010CZ**	SD3020C1**	SD3040C2**	SD3080C3**	SD310	00C4**	SD3150C6**	SD3200C8**		
Compatible Motor		M□□005	M□□010	M□□020	M□□040	M□□075	MD	100	M□□150	M□□200		
External dimens	sions			(50	ee "Dimensic	ons" beginnin	ig on page 2	8.)				
Weight (Kg)			0	.7		0.8	1	.0	1	.6		
	Main circuit power			ohase AC200 10 % 50 / 6			Т	•	AC200 V to 24 50 / 60 Hz	10 V		
	Control power				E	DC24V ±10 9	6					
lnput power	Input current (Arms typ)	0.8	1.3	2.4	3.6	7.2		ohase : 9.7 ohase : 5.1	6.1	9.0		
	Control power		170		210	260	24	40	3	50		
	Current Consumption (mA Typ.)				(Rush c	urrent apprp	x.1.4 A)					
Control of main	circuit			Thr	ee-phase PW	/M inverter si	ine-wave dri	ven				
Output	Rated current (A)	0.7	1.0	1.7	2.7	4.3	5.8	5.6	9.9	12.2		
Rating	Output frequencies (Hz)		0 to 500 0 to 250									
Encoder feedba	ck	17 bit single-turn absolute (The product can function as a multi-turn absolute type when batteries are added.)										
Controlational	Input	8-point (24 mode	8-point (24 VDC system, photo-coupler input insulation) inputs whose functions are switched by the control mode									
Control signal	Output	8-point (24 mode	8-point (24 VDC system, open-collector output insulation) outputs whose functions are switched by the control mode									
Analog signal	Input	1-point (±	10 V) input v	vhose functio	ons can be sw	vitched by th	e control mo	ode				
Dulas signal	Input	RS-422 differential Open-collector										
Pulse signal	Output	Encoder feedback pulse (A-/B-/Z-phase), RS-422 differential output Z-phase pulse through open-collector as well										
Communication	function	USB : connection to PC with "Servo Studio" installed RS-485 : host remote control communication (multi-drop compatible)										
Amplifier status display function		Amplifier status display function 6 digits of seven-segment display on Setup Panel Normal/Error display on STATUS LED Green light when Power ON Normal, Red light when Power ON Error, Dim when Power OFF										
Regeneration fu	inction	A regenerative resistor may be installed externally										
Dynamic brake		None Optional dynamic brake unit "SP03101" or "SP03102" is available for 50 W to 1 kW. Building your own dynamic brake unit for 1.5 kW to 2 kW. (See "Dynamic Brake Circuit" on page 34)										
Control mode		Position Co	ntrol, Veloci	ty Control, To	orque Contro							

Environmental Specification

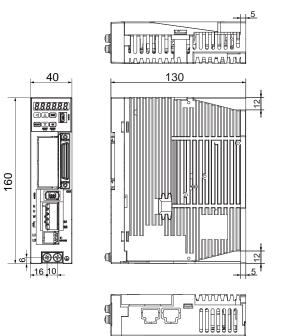
ltem		Specifications					
For operation		0 to 55 ℃					
Ambient temperature	For storage	−20 to 65 °C					
For operation		20 to 85 % RH (non-condensing)					
Ambient humidity	For storage						
Atmosphere for operation and storage		Indoors(not subject to direct sunlight), Free from corrosive gases, flammable gases, oil mist, dust, flammables, grinding fluid					
Altitude		≤ 1,000 m					
Vibration		≤ 5.8 m/s ² (0.6 G) 10 to 60 Hz (no continuous operation allowed at frequency of resonance)					
Dielectric strength		AC 1,500 V for one minute across the primary and FG					
Electric shock protection		Class I (mandatory grounding)					
Overvoltage category		Ш					
Installation environment		Pollution degree 2					

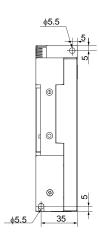
Functions Specifications

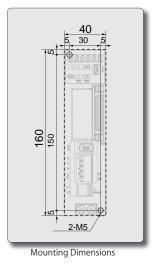
		ltem		Specifications					
		Control input		Servo ON, alarm reset, command input not allowed, emergency stop, deviation counter clear, 2-stage torque limit, CCW/CW run not allowed, ABS data demand, homing start					
	Pu	Control output		under torque limitAlarm status, servo status, servo ready, under torque limit, brake release, positioning complete, motion complete, alarm, dynamic brake release, ABS data transmitting, homing complete					
				RS-422 differential:4 Mpps Open-collector:200 kpps					
Posit	-	Input pulse signal	form	Pulse + Direction, A-/B-phase quadrature encoder pulse, CW + CCW pulse					
ion Con		Electronic gear		ratio A/B 1/1,000 < A/B < 1,000 Setting range A:1 to 65,535 B:1 to 65,535					
Position Control Mode	Intei	Control input		Servo ON, alarm reset, deviation counter clear, motion start point selection 16, home position sensor input, homing start					
le	Internal Position	Control output		Alarm status, servo status, servo ready, uunder torque limit, brake release, homing complete, motion complete					
	tion	Operation mode		Point table, communication operation					
	Smo	oothing filter		FIR Filter					
	Dar	nping control		Enabled					
	Ana	Control input		Servo ON, alarm reset, command input inhibit (zero torque command), 2-stage torque limit, CCW/CW run prohibited					
Vel	Control output Control output			Alarm status, servo status, servo ready, under torque limit, brake release					
Velocity Control Mode	ocity	Speed command i	input	Input voltage -10 V to +10 V (max speed is reached at \pm 10 V)					
ntrol Mo	Internal	Control input		Servo ON, alarm reset, start 1 (CCW), start 2 (CW), 8-stage speed command 2-stage torque limit					
de	l Velocity	Control output		Alarm status, servo status, servo ready, under torque limit, brake release					
	Smo	oothing filter		IIR Filter, FIR Filter					
Tor	Ana	Control input		Servo ON, alarm reset, command input not allowed (zero clamp command) 2-stage torque limit, CCW/CW run prohibited					
Torque Control Mode	alog Torque	Control output		Alarm status, servo status, servo ready, under torque limit, brake release					
itrol Mo	que	Torque command	input	Input voltage, -10 V to $+10$ V (max speed is reached at \pm 10 V)					
de	Smo	oothing filter		IIR Filter					
	Spe	ed observer		Available					
	Auto-tuning			Available					
Comr	Encoder output Division/Multiplication		n/Multiplication	Available					
Common Features	Tun	ing & Function Setu	р	Available through the SD3 setup software "Servo Studio" Tuning with the setup panel on the amplifier front side					
atures	Pro	tective functions	By hardware	Overvoltage, low voltage, Overcurrent, Abnormal temperature, Overload, Encoder error					
	101		By software	Overspeed, Position deviation too high, Parameter errors					
	Alaı	rm Log		Can be referenced with the setup software Servo Studio					

Specification









(mm)

Figure 2		50W 100W	200W	400W 750W	1.5KW	2KW
			11.5			
	48	130	+ 	φ5.5	48	
			<i>y</i>		150	
			<u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u></u>	()5.5 + 35 +	ut	
					Mounting Dimensions	(mm)

(mm)



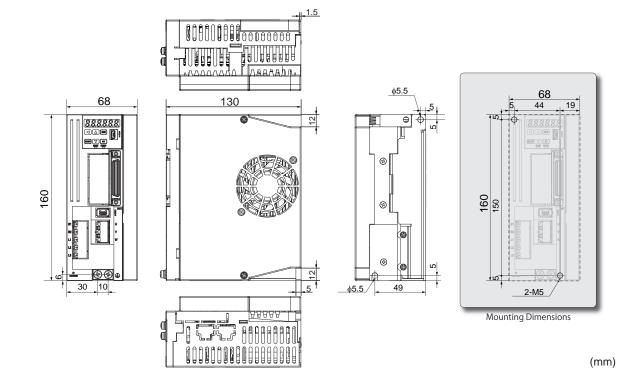
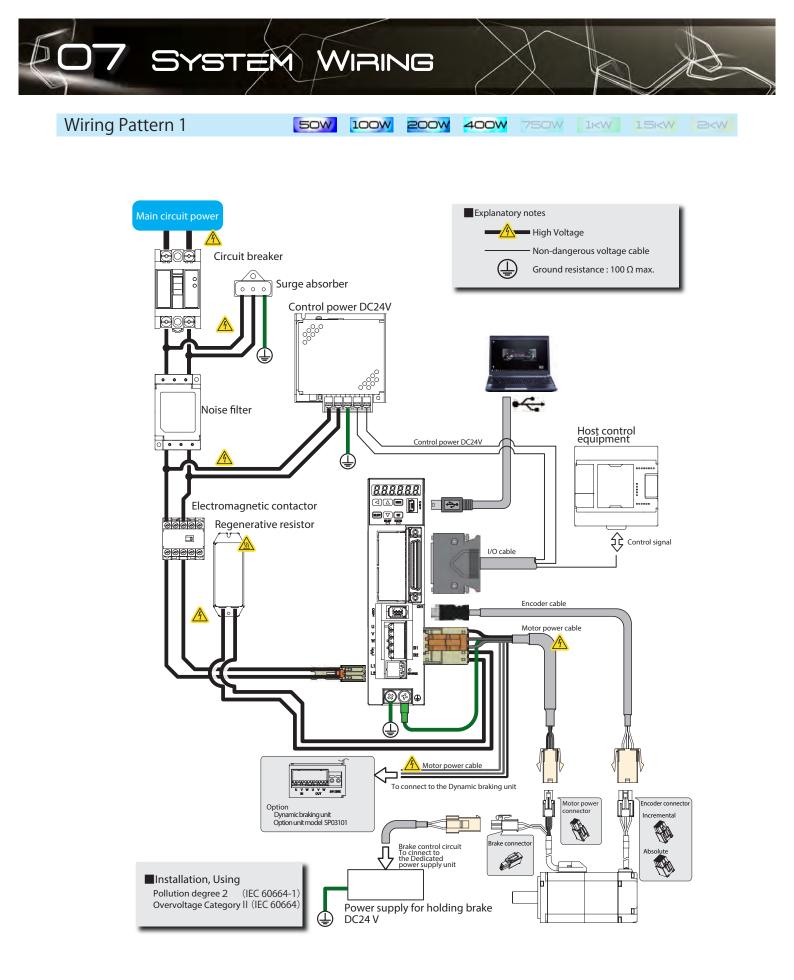
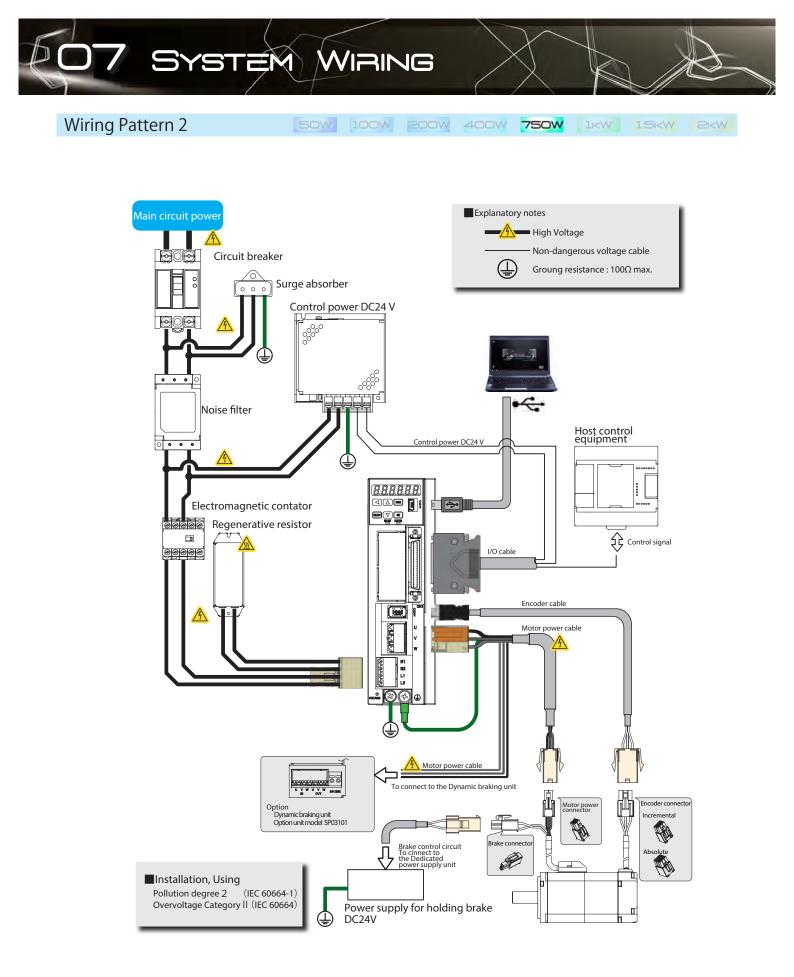
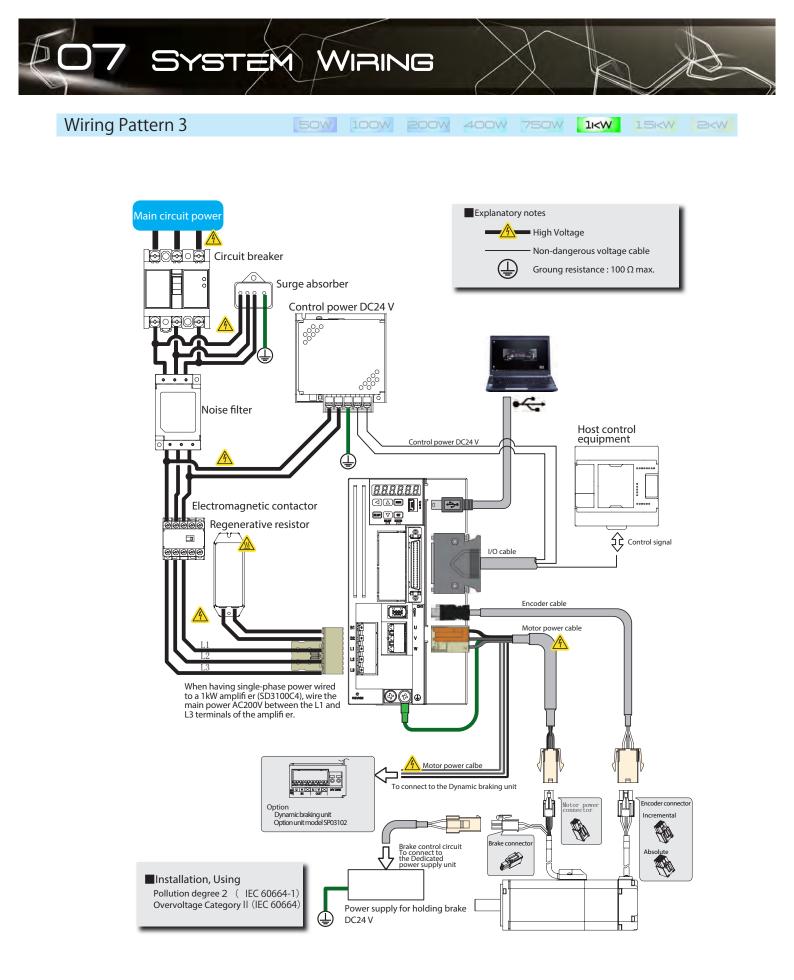
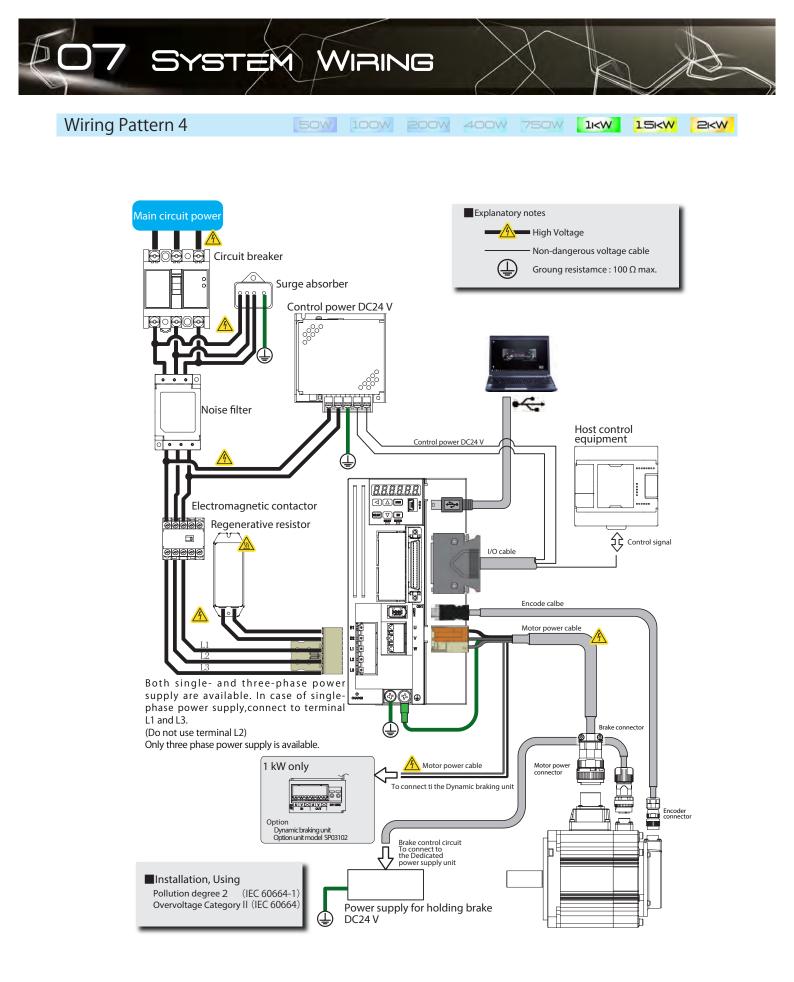


Figure 4 200W 400W 750W 1.5KW 2KW 1.5 0 ┥┝┥┝┥┝┪┝┥┝ ╡╡┙┙╛┇ φ5.5 φ5.5 84 61.7 84 130 7.3 10 61.7 <u>5</u> ð UÍ ŧЮ 10 448888 440 [] Ċ 0 Ð Ð ഹ \odot 0 160 160 150 B 000 0 0 (4) 12 Ю L# 74 S 30 10 5 φ5.5 3-M5 Mounting Dimensions 15 ſ (mm)









Peripherals

To make your applications of our product comply with the European EC directives, select devices that meet each applicable standard and install them observing the wiring diagram.

ltem	Description							
Main circuit power	 Please use this product in the power supply environment of Over-Voltage Category II defined by IEC60664-1. This is the primary circuit power for amplifiers. 50 W to 750 W Amplifiers : Single-phase AC200 V – 10% to AC240 V +10% 1 kW to 2 kW Amplifiers : Three-phase AC200 V – 10% to AC240 V +10% Using a overvoltage protection relay is recommended. When having single-phase power wired to a 1 kW amplifier, wire the primary circuit AC200 V between the L1 and L3 terminals of the amplifier. To avoid unbalance of the three-phase AC200 V wiring in your factory, we recommend that you consider balance of currencies in your three-phase wirings. Confirm that your contract with the electric power company is not limited to use of three-phase. 							
Control power	This is power supply of DC24 V \pm 10 % for amplifier control power, I/O power and motor brake release power. Use a SELV (Safety Extra Low Voltage) power supply with reinforced insulation against hazardous voltages. Be sure to connect a varistor to the motor braking release power supply.							
Cables	Use of UL wires and cables suitable for motor rated output are recommended. High-voltage cables and FG cables AWG18 / 600 V breakdown voltage or equivalent for 50 W to 750 W AWG14 / 600 V breakdown voltage or equivalent for 1 kW to 2 kW Motor power cables AWG18 / 300 V breakdown voltage or equivalent for 50 W to 750 W AWG14 / 300 V breakdown voltage or equivalent for 1 kW to 2 kW Encoder cables • AWG22 and AWG24 compound / 30 V breakdown voltage or equivalent • shielded cables with twisted pair wires • length not exceeding 20 m User I/O cable • AWG26 / 300 V breakdown voltage or equivalent • shielded cables with twisted pair wires • length not exceeding 2 m							
Circuit breaker	To protect the power supply line, circuit breakers shut the circuit down in the event of over-current. Be sure to use an IEC standard and UL-certified circuit breaker between the power supply and the noise filter. To ensure compliance with EMC, use an earth leakage circuit breaker that we recommend.							
Noise filter	Noise filters prevent ingress of external noise from the power supply line. To ensure compliance with EMC, use the recommended noise filter.							
Electromagnetic contactor	This is an on/off switch for the main power supply. Use a surge absorber on the input side of the primary circuit power supply.							
Surge absorber	To ensure compliance with EMC, connect the recommended surge absorber to the primary side of primary circuit power supply.							
Signal line noise filter/ ferrite core	To ensure compliance with EMC, use the recommended signal line noise filter/ferrite core.							
Regenerative resistor	This product is not equipped with regenerative resistor. If the smoothing capacitor inside the servo amplifier cannot absorb regenerative power, an external regenerative resistor is required. As a guideline, check the regeneration state on the settings panel, and use a regenerative resistor if the regenerative voltage warning is ON. Build an overheating prevention circuit using a resistor which has built-in thermostat. If the temperature of generated heat becomes high, you can suppress the heat by installing a cooling device, or selecting a resistor whose allowable power is 5 to 10 times larger than regenerative voltage.							
Dynamic brake	This product is not equipped with a dynamic brake feature. Use our optional product for 50 W to 1 kW Model AP03101 (50 W to 750 W), Model AP03102 (1 kW). See Optional manual Dynamic brake unit Use the circuit example on the right side when building a dynamic brake circuit. Select a cement resistor of 6.8 Ω 10 W. Select coil surge protection relays with diode. For wiring with the motor power line, UL wires (AWG18 / 600 V or equivalent) are recommended.							
Grounding	Since this product is Class I device, protective grounding is mandatory. (Type D grounding: grounding resistance of up to 100 Ω) Properly ground the product using protective grounding terminals through EMC-compatible casing and control panel.							

Recommended Peripheral Devices

Device	Manufacturer	Model	Note
Circuit breaker	Fuji Electric Co Ltd	Single-phase : EW32AAG-2P020B Three-phase : EW32AAG-3P020B	20 A for single-phase or three-phase 200 V ^(*) Leakage current of 30 mA, Equivalent products are acceptable.
Noise filter	OKAYA Electric Industries Co Ltd	Single-phase : SUPF-EX □□ -ER-6 Three-phase : 3SUPF-BE □□ -ER-6- □	Was used in the EMC testing for our product ${}^{\scriptscriptstyle(*)}$
Magnetic contactor	Fuji Electric Co Ltd	SK06G-E10	Or equivalent alternatives.
Surge absorber	OKAYA Electric Industries Co Ltd	Single-phase : LV275DI-Q4 Three-phase : LV275DI-U4	Was used in the EMC testing for our product
Signal line noise filter /ferrite core	SEIWA ELECTRIC MFG. CO., LTD. (Misumi Corporation)	E04SR401938 (ATCK-1130)	Was used in the EMC testing for our product
Regenerative resistor	Chiba Techno Co., Ltd.	For 50 W to 750 W : CAN100S 47 Ω J For 1 kW, 1.5 kW : CAN400S 30 Ω J For 2 kW : CAN750S 20 Ω J	-

*) Select a product whose ratings are suitable for your system configuration.

Regenerative Resistor

When considering a regenerative resistor other than the recommended above, use the following as a guideline.

Amplifier Model	SD3005CY**	SD3010CZ**	SD3020C1**	SD3040C2**	SD3080C3**	SD3100C4**	SD3150C6**	SD3200C8**
Compatible Motor	M 🗌 🗌 005	M 🗌 🗌 010	M □□ 020	M □□ 040	M 🗌 🗌 075	M □□ 100	M 🗌 🗌 150	M 🗌 🗌 200
Rated output	50 W	100 W	200 W	400 W	750 W	1 kW	1.5 kW	2 kW
Regeneration resistance	40 Ω to 50 Ω 30 Ω							20 Ω
Regeneration allowable voltage	20 W 40 W 60 W						60 W	

The regeneration resistance values do not guarantee the optimal performance. Regeneration allowable voltages above are minimum values as a point of reference.

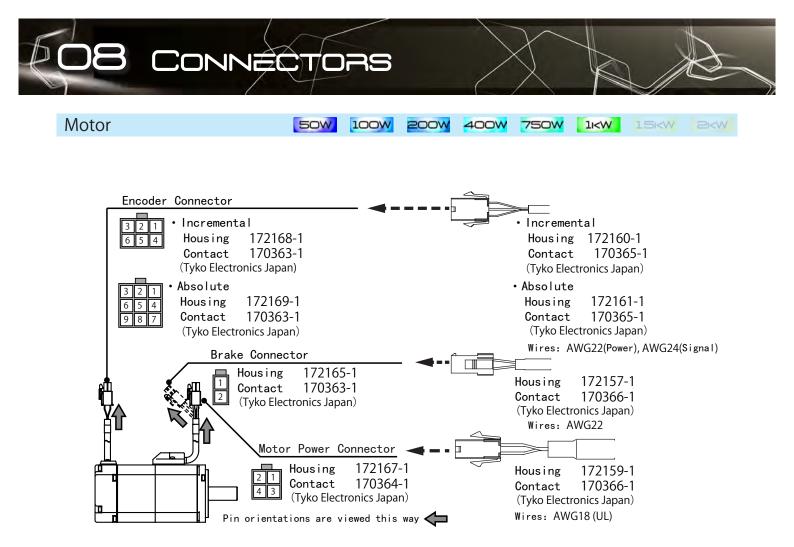
The regeneration resistor may become very hot. It requires sufficient margin of regeneration allowable power.

Recommended Cables

Connection cables required for this product are sold separately. Those can be purchased at the Misumi Corporation online store. Follow the link at our website:

Use our recommendations below to select cables based on your actual usage. (Equivalent alternatives are also good)

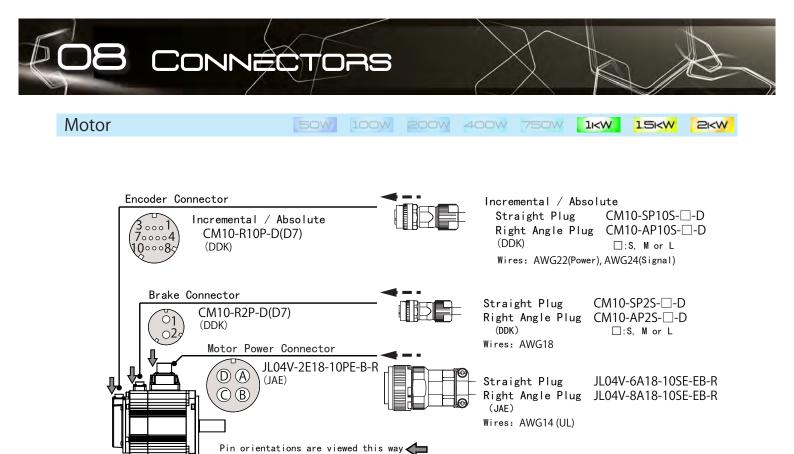
					5		
Cable Name	AWG	UL	Temperature Rating	Voltage Rating	Note		
Motor power (≤ 750 W)	18	2517	105 ℃	300 V			
Motor power (≥ 1 kW)	14	2517	105 ℃	300 V	AWG16 wires can be used only for 1 kW motors		
Main circuit power (≤ 750 W) (Including FG cable)	18	1015	105 ℃	600 V			
Main circuit power (≥ 1 kW) (Including FG cable)	14	1015	105 ℃	600 V	AWG16 wires can be used only for 1 kW motors.		
Encoder	Power: 22 Signal: 24	20276	80 ℃	30 V	Shielded twisted pair cables of length no exceeding 20 m		
User I/O	26	1007	80 ℃	300 V	Shielded twisted pair cables Length not exceeding 2 m is recommended		
Regenerative resistor	18	1015	105 ℃	600 V			
Dynamic brake	18	1015	105 ℃	600 V			
Brake	18	2517	105 ℃	300 V	1 pair (2 cores)		



Name	Pin No.	Signal	Description
	1	U	Motor power U-phase
Motor Power	2	V	Motor power V-phase
	3	W	Motor power W-phase
	4	FG	Motor frame ground
Brake ^(*1)	1	BRK+	Brake power supply DC24 V
DIAKe	2	BRK-	Brake power supply GND
	1	-	(No Connect)
	2	+D	Serial communication data + Data
Encoder	3	—D	Serial communication data – Data
(Incremental)	4	VCC	Encoder power supply +5 V
	5	SG	Signal ground
	6	SHIELD	Shield
	1	BAT	External battery (*2)
	2	-	(No Connect)
	3	SHIELD	Shield
	4	+ D	Serial communication data + Data
Encoder (Absolute)	5	-D	Serial communication data – Data
(Absolute)	6	-	(No Connect)
	7	VCC	Encoder power supply +5 V
	8	SG	Signal ground
	9	-	(No Connect)

*1) Only for a motor equipped with a brake

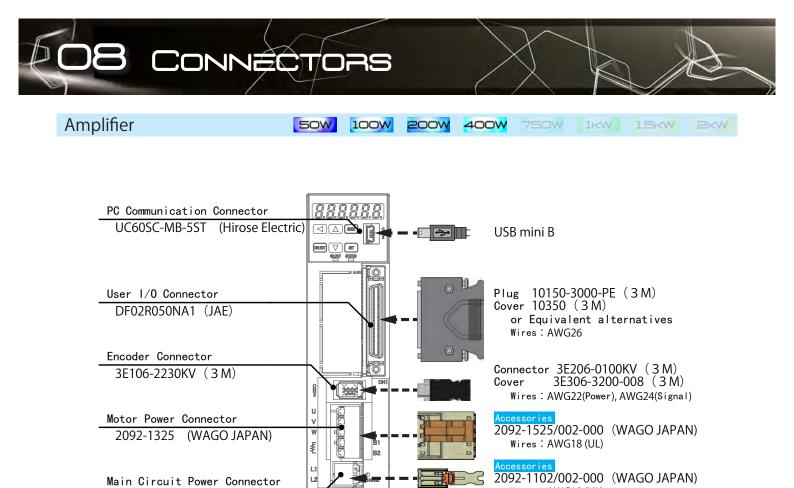
*2) Connect the negative pole of the battery to SG (Signal Ground).



Name	Pin No.	Signal	Description
	A	U	Motor power U-phase
Motor Power	B V		Motor power V-phase
Motor Power	С	W	Motor power W-phase
	D	FG	Motor frame ground
Brake ^(*1)	1	BRK+	Brake power supply DC24 V
DIdke	2	BRK-	Brake power supply GND
	1	VCC	Encoder power supply +5 V
	2	SG	Signal ground
	3, 4	-	(No Connect)
Encoder (Incremental)	5	+ D	Serial communication data + Data
(incremental)	6	-D	Serial communication data – Data
	7, 8, 9	_	(No Connect)
	10	SHIELD	Shield
	1	VCC	Encoder power supply +5 V
	2	SG	Signal ground
	3	_	(No Connect)
	4	BAT	External battery (*2)
Encoder (Absolute)	5	+ D	Serial communication data + Data
(Absolute)	6	-D	Serial communication data – Data
	7, 8	-	(No Connect)
	9	SG	Signal ground
	10	SHIELD	Shield

*1) Only for a motor equipped with a brake

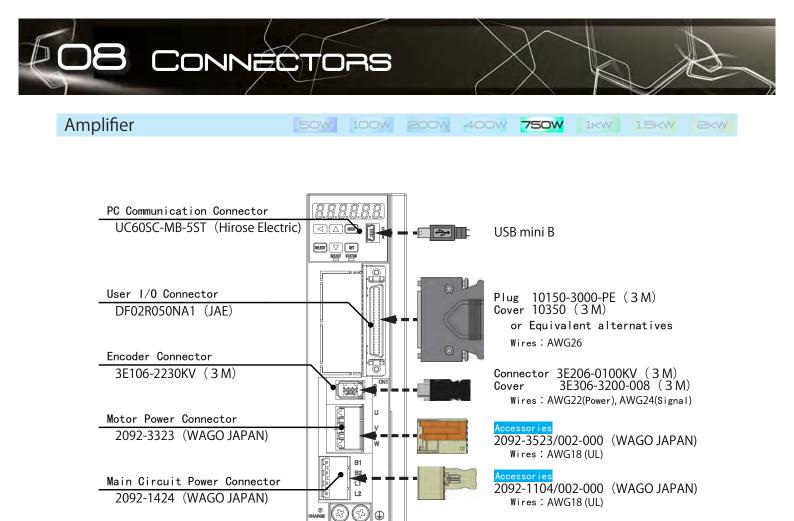
*2) Connect the negative pole of the battery to SG (Signal Ground).



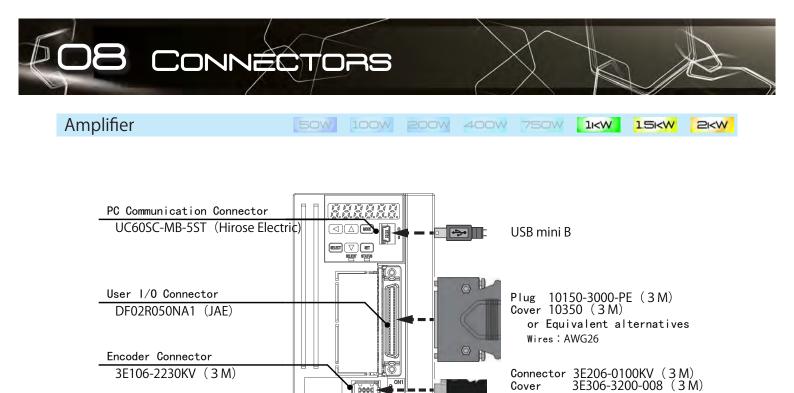
Name	Code	Pin No.	Signal	Description		
		1	L1	Main power cable 1		
Main Circuit Power	L1L2	2	L2	Main power cable 2		
		1	U	Motor power U-phase		
	UVW / B1B2	2	V	Motor power V-phase		
Motor Power		3	W	Motor power W-phase		
		4	B1	Regenerative resistor connection (+)		
		5	B2	Regenerative resistor connection (-)		
		1	VCC	Encoder power supply +5 V		
		2	GND	Signal ground		
Encoder	CN2	3, 4	-	(No Connect)		
Elicodel	CINZ	5	+ D	Serial communication data + Data		
		6	-D	Serial communication data – Data		
		-	FG	SHIELD wired to the connector casing		
		1	VBUS	USB power supply +5 V		
		2	D-	USB data –		
PC Communication	CN3	3	D+	USB data +		
		4	-	(No Connect)		
		5	GND	USB signal ground		
		Boute power and signal wiring suitable for your operation mode				

2092-1422 (WAGO JAPAN)

Wires : AWG18 (UL)



Name	Code	Pin No.	Signal	Description	
		1	B1	Regenerative resistor connection (+)	
Main Circuit Power	L1L2 /	2	B2	Regenerative resistor connection (-)	
Main Circuit Fower	B1B2	3	L1	Main power cable 1	
		4	L2	Main power cable 2	
		1	U	Motor power U-phase	
Motor Power	UVW	2	V	Motor power V-phase	
		3	W	Motor power W-phase	
	CN2	1	VCC	Encoder power supply +5 V	
		2	GND	Signal ground	
Encoder		3, 4	-	(No Connect)	
Encoder		5	+ D	Serial communication data + Data	
		6	-D	Serial communication data – Data	
		-	FG	SHIELD wired to the connector casing	
		1	VBUS	USB power supply +5 V	
		2	D-	USB data –	
PC Communication	CN3	3	D+	USB data +	
		4	-	(No Connect)	
		5	GND	USB signal ground	
User I/O	CN1	Route power and signal wiring suitable for your operation mode. (See "Example of I/O Wiring")			



L 📈

L7) (7)

B1

Ľ 12 1.2

(D) CHARGE

Motor Power Connector

2092-3323 (WAGO JAPAN)

Main Circuit Power Connector

2092-3425 (WAGO JAPAN)

Name	Code	Pin No.	Signal	Description
		1	B1	Regenerative resistor connection (+)
		2	B2	Regenerative resistor connection (-)
Main Circuit Power	L1L2L3 / B1B2	3	L1	Main power cable 1 (*1)
	0102	4	L2	Main power cable 2 (*2)
		5	L3	Main power cable 3 ^(*1)
		1	U	Motor power U-phase
Motor Power	UVW	2	V	Motor power V-phase
		3	W	Motor power W-phase
	CN2	1	VCC	Encoder power supply +5 V
		2	GND	Signal ground
Encoder		3, 4	-	(No Connect)
Encoder		5	+ D	Serial communication data + Data
		6	-D	Serial communication data – Data
		-	FG	SHIELD wired to the connector casing
		1	VBUS	USB power supply +5 V
		2	D-	USB data –
PC Communication	CN3	3	D+	USB data +
		4	-	(No Connect)
		5	GND	USB signal ground
User I/O	CN1	Route power and signal wiring suitable for your operation mode. (See "Example of I/O Wiring")		

*1) When having single-phase power wired to 1kW amplifiers (DA24A22), connect the primary circuit power to L1 and L3.

 $\ast 2)~$ Do not connect when using with single-phase power.

Wires: AWG22(Power), AWG24(Signal)

2092-3523/002-000 (WAGO JAPAN)

2092-3105/002-000 (WAGO JAPAN)

Wires: AWG18(UL)

Wires: AWG14(UL)

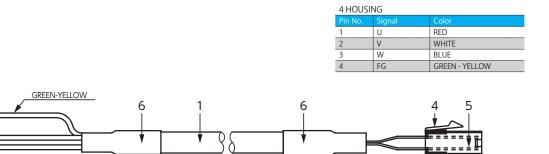


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_3

50W 100W 200W 400W 750W 1KW 1.5kW 2kW



No.	Item Model !		Supplier
1	CABLE	NA3CT-18-4(for fixed wiring) NA3CTR-18-4 (for movable wiring)	MISUMI Group Ink
2	RING TONGUE TERMINAL	R2-4	J.S.T. Mfg. Co.,Ltd.
3	FERRULE	216-143	WAGO JAPAN
4	HOUSING	172159-1	Tyco Electronics JAPAN
5	TERMINAL	170366-1	Tyco Electronics JAPAN
6	SUMITUBE	F(Z) 11x0.25	Sumitomo Electric Industries
7	(MARKER TUBE)	(arbitrary)	(arbitrary)

Motor Power Cable	SOW	100W	200W	400W	750W	1KW	1.5KW	2KW
					4 PLUG Pin No.	Signal	Color	
					1	U	RED	
					2	V W	WHITE BLUE	
					4	FG	GREEN - YELLOW	
2 7					5	4		
Z / <u>GREEN-YELLOW</u>	6	1		6	¥	+		
Ó L	0						P h	
_3								
			Y&					

No.	Item	Model	Supplier
1		NA6CT-14-4 (for fixed wiring) NA6CTR-14-4 (for movable wiring)	MISUMI Group Ink
2	RING TONGUE TERMINAL	R2-4	J.S.T. Mfg. Co.,Ltd.
3	FERRULE	216-106	WAGO JAPAN
4	PLUG	JL04V-6A18-10SE-EB-R	JAE
5	CABLE CLAMP	JL04V-18CK13-CR-R	JAE
6	SUMITUBE	F(Z) 14x0.3	Sumitomo Electric Industries
7	(MARKER TUBE)	(arbitrary)	(arbitrary)



200W

400W

750W

1.5KW 2KW

Encoder Cable

(Incremental)

2 HOUS	ING	1 Shield		
Pin No.	Signal	AWG22	4 HOUSI	NG
1	VCC	AWG22	Pin No.	Signal
2	GND		1	-
3	-	√ AWG24	2	+D
4	-	/ AWG24	- 3	—D
5	+D		- 4	VCC
6	—D		5	GND
7	SHIELD		6	SHIELD
		Soldering		

100W

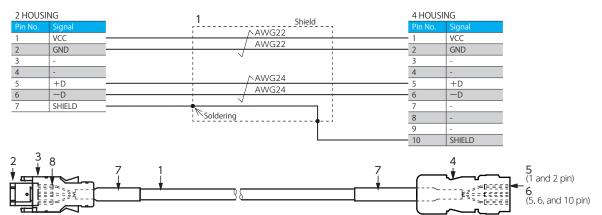
50W



No.	Item	Model	Supplier
1	CABLE	NA20276TSB-C (for fixed wiring) NA20276RRSB-C (for movable wiring)	MISUMI Group Ink
2	HOUSING	3E206-0100KV	3M
3	COVER	3E306-3200-008	3M
4	HOUSING	172160-1	Tyco Electronics JAPAN
5	TERMINAL	170365-1	Tyco Electronics JAPAN
6	SUMITUBE	F(Z) 7x0.25	Sumitomo Electric Industries
7	SUMITUBE	F(Z) 3/64 or 1.5x0.2	Sumitomo Electric Industries

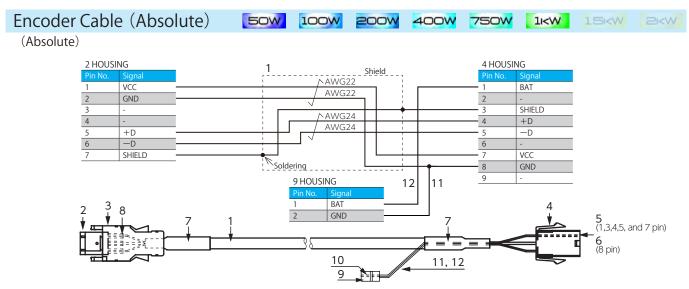
Encoder Cable 500 1000 2000 4000 7500 1KW 15KW 2KW

(Incremental)



No.	Item	Model	Supplier
1		NA20276TSB-C (for fixed wiring) NA20276RRSB-C (for movable wiring)	MISUMI Group Ink
2	HOUSING	3E206-0100KV	3M
3	COVER	3E306-3200-008	3M
4	HOUSING	CM10-SP10S-M	DDK
5	TERMINAL	CM10-#22SC(C1)(D8)	DDK
6	TERMINAL	CM10-#22SC(C2)(D8)	DDK
7	SUMITUBE	F(Z) 7x0.25	Sumitomo Electric Industries
8	SUMITUBE	F(Z) 3/64 or 1.5x0.2	Sumitomo Electric Industries

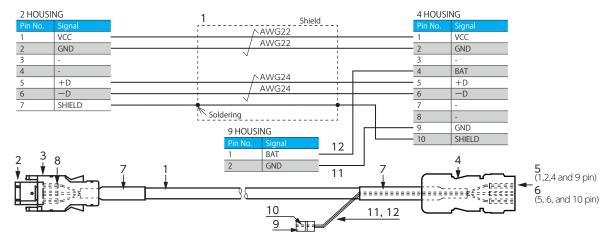




No.	Item	Model	Supplier
1	CABLE	NA20276TSB-C (for fixed wiring) NA20276RRSB-C (for movable wiring)	MISUMI Group Ink
2	HOUSING	3E206-0100KV	3M
3	COVER	3E306-3200-008	3M
4	HOUSING	172161-1	Tyco Electronics JAPAN
5	TERMINAL	170365-1	Tyco Electronics JAPAN
6	TERMINAL	170366-1	Tyco Electronics JAPAN
7	SUMITUBE	F(Z) 7x0.25	Sumitomo Electric Industries
8	SUMITUBE	F(Z) 3/64 or 1.5x0.2	Sumitomo Electric Industries
9	HOUSING	DF3-2EP-2C	Hirose Electric
10	TERMINAL	DF3-EP2428PCFA	Hirose Electric
11	CABLE	NAUL1007-24-BK	MISUMI Group Ink
12	CABLE	NAUL1007-24-R	MISUMI Group Ink

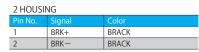
Encoder Cable (Absolute) 500 1000 2000 4000 7500 1KW 2KW 2KW

(Absolute)



No.	Item	Model	Supplier
1	CABLE	NA20276TSB-C (for fixed wiring) NA20276RRSB-C (for movable wiring)	MISUMI Group Ink
2	HOUSING	3E206-0100KV	3M
3	COVER	3E306-3200-008	3M
4	HOUSING	CM10-SP10S-M	DDK
5	TERMINAL	CM10-#22SC(C1)(D8)	DDK
6	TERMINAL	CM10-#22SC(C2)(D8)	DDK
7	SUMITUBE	F(Z) 7x0.25	Sumitomo Electric Industries
8	SUMITUBE	F(Z) 3/64 or 1.5x0.2	Sumitomo Electric Industries
9	HOUSING	DF3-2EP-2C	Hirose Electric
10	TERMINAL	DF3-EP2428PCFA	Hirose Electric
11	CABLE	NAUL1007-24-BK	MISUMI Group Ink
12	CABLE	NAUL1007-24-R	MISUMI Group Ink







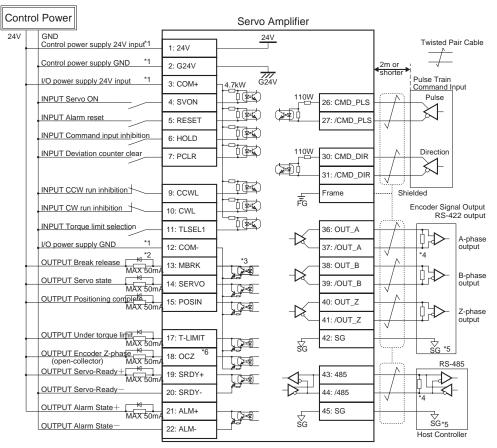
No.	Item	Model	Supplier
1		MAST-UL2517-19-2(for fixed wiring) NA3UCR-18-2 (for movable wiring)	MISUMI Group Ink
2	HOUSING	172157-1	Tyco Electronics JAPAN
3	TERMINAL	170366-1 or 170639-1	Tyco Electronics JAPAN
4	SUMITUBE	F(Z) 8x0.25 Sumitomo Electric Industries	

Brake Cable	50W	100W	200W	400W	750W	1KW	1.5KW	2KW
					2 PLUG Pin No.	Signal	Color	
					1	BRK+ BRK-	BRACK BRACK	
4	1))	4			3 ≈[=]_≝ ≣	
		((_{: ``} `` روست	≈[=]=] = =	

No.	Item	Model	Supplier
1		MAST-UL2517-19-2(for fixed wiring) NA3UCR-18-2 (for movable wiring)	MISUMI Group Ink
2	PLUG	CM10-SP2S-M-D	DDK
3	CONTACT	CM10-#22SC(S2)(D8)-100	DDK
4	SUMITUBE	F(Z) 8x0.25	Sumitomo Electric Industries



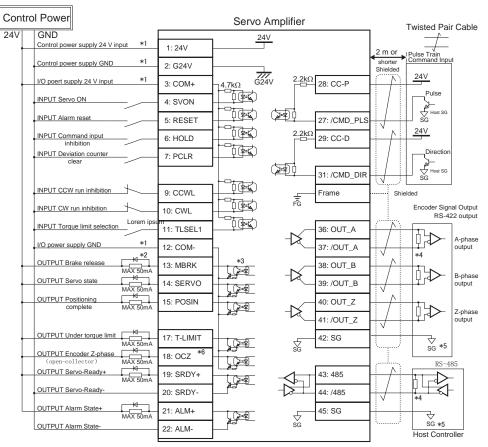
Pulse Input Command | Differential Input (Standard I/O)



Pulse Input Command | Differential Input (Optional I/O)

Contro	ol Power		Servo Amplifier
24V	GND Control power supply 24 V input *1	- 1: 24V	24V Twisted Pair Cable
	Control power supply GND *1	2: G24V	4 ^{2 m or} →
+	I/O power supplu 24 V input *1	- 3: COM+	-4.7kΩ G24V -4.7kΩ G24V Command Input
	INPUT Servo ON	4: SVON	1100 26: CMD_PLS Pulse
	INPUT Alarm reset	5: RESET	
	INPUT Command input inhibition INPUT Deviation counter	- 6: HOLD	
	clear INPUT Homing start	- 7: PCLR	
	INPUT CCW run inhibition	- 8: HOME - 9: CCWL	31: /CMD_DIR
	INPUT CW run inhihbition	10: CWL	FG Encoder Signal Output
	INPUT Torque limit selection	- 11: TLSEL1	RS-422 output
	I/O power supply GND *1	12: COM-	37: /OUT_A
+	OUTPUT Brake release MAX 50mA	13: MBRK	
+	OUTPUT Servo state	14: SERVO	39: /OUT_B
+	OUTPUT Positioning A complete MAX 50mA	15: POSIN	40: OUT_Z
-	complete MAX 50mA	- 16: HEND	41: /OUT_Z output
+	/Under torque limit MAX 50mA	- 17: MEND/T-LIMIT	
	(open-collector) MAX 50mA OUTPUT Servo-Ready+	- 18: OCZ *0	RS-485
	MAX 50mA OUTPUT Servo-Ready-	20: SRDY-	
	OUTPUT Alarm State+	- 21: ALM+	45: SG +*4
	MAX 50mA OUTPUT Alarm State-	22: ALM-	G sG s5 Host Controller

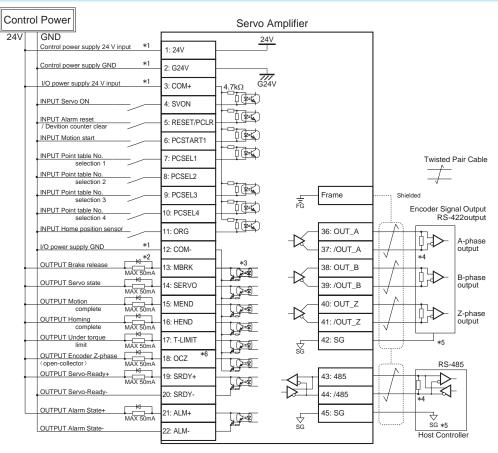
Pulse Input Command | 24V Open Collector Input



Pulse Input Command | 5V Open Collector Input

Contro	ol Power			Servo	Amplifier		Twisted Pai	r Cable
24V	GND			24	1V			-
+	Control power supply 24 V in	nput *1	1: 24V	<u> </u>	<u> </u>		2 m or 1	-
	Control power supply GND	*1	2: G24V	<u> </u>	<u> </u>		shorter	
-	I/O power supply 24 V input	*1	3: COM+	_4.7kΩ G2	4V			and Input
	INPUT Servo ON		4: SVON		390Ω □□□ 49: CC	C-P_5V	<u>5V</u>	
	INPUT Alarm reset		5: RESET		27: /CI	MD_PLS		ulse
	INPUT Command input inhibition		6: HOLD					ost SG
	INPUT Deviation counter clear		7: PCLR		390Ω □□□ 50: CC	-D_5V		
	uldar -	-		1	31: /Cl	MD_DIR	Dire	ction
	INPUT CCW run inhibition		9: CCWL		Frame		Shielded	ost SG
	INPUT CW run inhibition		10: CWL		FG FG		Encoder Sig	
	INPUT Torque limit selection	<u> </u>	11: TLSEL1		36: OL	JT_A		422 output
	I/O power supply GND	*1	12: COM-		37: /0	UT_A		A-phase output
	OUTPUT Brake release	*2 MAX 50mA	13: MBRK	*3	38: OL	ЛТ_В	*4	
	OUTPUT Servo state	MAX 50mA MAX 50mA	14: SERVO		39: /01	UT_B		B-phase output
	OUTPUT Positioning complete		15: POSIN		40: OL	JT_Z		
	complete	MAX 50mA			41: /0	UT_Z -		Z-phase output
	OUTPUT Under torque		17: T-LIMIT		42: SG	; –		
	OUTPUT Encoder Z-phase	MAX 50mA	18: OCZ *6		sG 42.30		SG *5	
	(open-collector) OUTPUT Servo-Ready+		19: SRDY+		43: 48	5	RS-	485
	OUTPUT Servo-Ready-	MAX 50mA	20: SRDY-		44: /48	35		1
	OUTPUT Alarm State+		21: ALM+		45: SG	;	√ *4	
	OUTPUT Alarm State-	MAX 50mA	22: ALM-		43. 30 SG			
				J			Host Con	troller

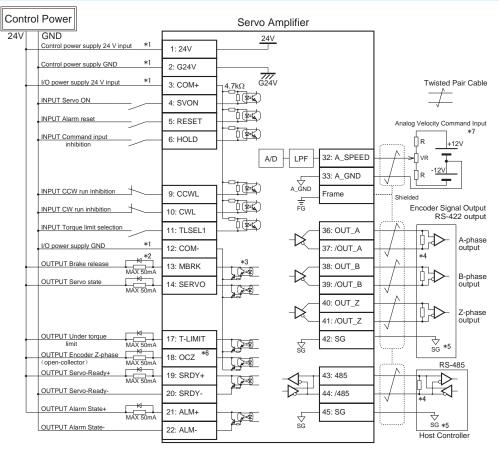
Internal Position Command | Standard I/O



Internal Position Command | Optional I/O

Con	trol Power		Servo Am	plifier	
24V	GND		24V		
•	Control power supply 24V input ¹	1: 24V			
	Control power supply GND *1	2: G24V			
	I/O power supply 24V input *1	3: COM+	4.7kW G24V		
	INPUT Servo ON	4: SVON			
	INPUT Alarm reset/ Deviation counter clear	5: RESET/PCLR			
	INPUT Motion start	6: PCSTART1			
	INPUT Point table No. section 1	7: PCSEL1			Twisted Pair Cable
	INPUT Point table No. section 2	8: PCSEL2			
	INPUT Point table No. section 3	9: PCSEL3		Frame	······· Shielded
	INPUT Homing start	10: HOME		FG Frame	Encoder Signal Output RS-422 output
	INPUT Torque limit selection	11: TLSEL1		36: OUT_A	
	I/O power supply GND *1	12: COM-		37: /OUT_A	A-phase output
	OUTPUT Point table No.bit code MAX 50mA	13: PM1	*3 ∫∫⊒≠⊽ि	38: OUT_B	
	OUTPUT Point table No. bit code	14: PM2	<u></u>	39: /OUT_B	B-phase output
	OUTPUT Point table No. bit cpde	15: PM3		40: OUT_Z	
	OUTPUT Homing complete	16: HEND		41: /OUT_Z	Z-phase output
	OUTPUT Motion complete /Under torque limit MAX 50mA	17: MEND/T-LIMIT		42: SG	*5
	OUTPUT Encoder Z-phase	18: OCZ *6		sĞ	RS-485
	OUTPUT Servo-Ready	19: SERVO+		43: 485	
	OUTPUT Servo-Ready-	20: SERVO-		44: /485	
	OUTPUT Alarm State+	21: ALM+	. [ə=v]	45: SG	
	OUTPUT Alarm State-	22: ALM-		√ 43. 30 SG	SG *5 Host Controller
		'			1

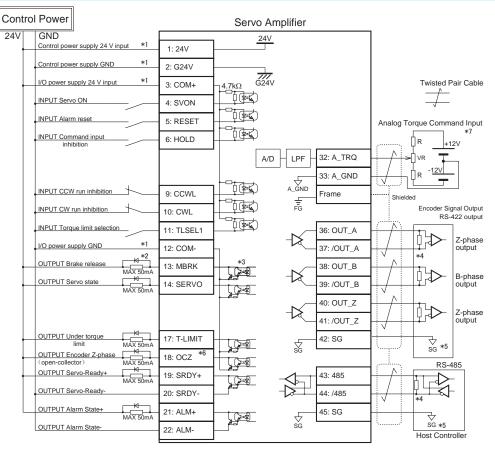
Analog Velocity Command



Internal Velocity Command

Cont	rol Power	Servo Amplifier	
24V	GND	24V	
	Control power supply 24 V input *1	1: 24V	
	Control power supply GND *1	2: G24V	
	I/O power supply 24 V input *1	3: COM+ 14.7kΩ G24V	
	INPUT Servo ON	4: SVON	
	INPUT Alarm reset	5: RESET	
	INPUT CCW run inhibition	6: VCRUN1	Twisted Pair Cable
	INPUT CW run inhibition	7: VCRUN2	
	INPUT Internal velocity command selection 1	8: VCSEL1	V
	INPUT Internal velocity command selection 2	9: VCSEL2	Shielded
	INPUT Internal velocity command selection 3		Encoder Signal Output RS-422 output
	INPUT Torque limit selection	11: TLSEL1 36: OUT_A	
	I/O power supply GND *1	12: COM- 37: /OUT_A	A-phase output
	OUTPUT Brake release	13: MBRK *3 38: OUT_B	
	OUTPUT Servo state	14: SERVO	B-phase output
		40: OUT_Z	
		41: /OUT_Z	Z-phase output
	OUTPUT Under torque	17: T-LIMIT 42: SG	
	OUTPUT Encoder Z-phase	18: OCZ *6 SG SG	SG *3 RS-485
	OUTPUT Servo-Ready+	19: SRDY+	
	OUTPUT Servo-Ready-	20: SRDY-	
	OUTPUT Alarm State+	21: ALM+ 45: SG	
	OUTPUT Alarm State-	21: ALM+ 43: SG 22: ALM- SG	SG *5 Host Controller
			riost controllel

Analog Torque Command



Notes:

- *1) Have only one power supply for both the control power (24 V, G24 V) and I/O power (COM+, COM–).
- *2) When driving a load which contains inductance element (e.g. relay), connect a protection diode. Motor brake can not be directly engaged. Be sure to use a relay with a protection diode in the circuit.
- *3) The output circuit structure is open connector and Darlington connection transistor output and connects to relay or photocoupler. Note that when Transistor ON, connector-emitter voltage V_{CE} (SAT) is approximately 1 V, which does not satisfy V_{IL} of regular TTL IC. Hence, the output circuit structure must not be connected directly.
- *4) Be sure to connect a terminating resistor of around 220 Ω .
- *5) Connect to the communication I/O signal ground of the host controller which outputs amplifier encoder output signal. Connecting the signal ground to the amplifier control power GND might result in malfunction.
- *6) When Z-phase pulse width is too narrow to be recognized by the host controller accurately, decrease the paired-pulse ratio "Encoder pulse output Division and multiplication" with parameters No. 276.0 and No. 278.0, or reduce the number of rotations, so that the pulse width becomes wider. Pulse width ms = Pulse width ms = 2 / (the number of rotations) / (the paired-pulse ratio x 2^{17}) × 60 × 1,000
- *7) When building a command circuit with a variable resistor (VR) and a resistor (R), in order to have the range of command input voltage to be -10 V to +10 V, VR should be at least $2 k\Omega 1/4$ W and R should be at least 100Ω to $200 \Omega 1/4$ W. When the host analog velocity command circuit is isolated from the 24 V control power, connect A_GND to the host SG, not to the control power GND. If not isolated, connect A_GND to the control power GND.

Signs below indicate two severity levels of bodily injury/loss, or property damage that could be caused by failure to observe the precautions and improper use of this product.		Symbols below indicate two types of precautions that users must follow.		
A DANGER	Identifies information about imminent hazards that are likely to cause death or serious injury.	\otimes	Safety Precautions - Don'ts	
	Identifies information about hazards that could cause injury or property damage.		Safety Precautions - Dos	

The follo	he following signs identify information about anticipated hazards.					
	Danger and Caution Causes unexpected motions, unstable motions, or uncontrollable motions Hampers optimal performance of the product, or shortens its service life		<u>Fire hazard</u>			
4	Electric shock hazard		Injury hazard			
	Burns hazard		Failure and damage hazard			

mbol	Precautions (Dos and Don'ts)	Anticipated Hazar
	Installation & Wiring	
\circ	Never connect your SD3 motor directly to commercial power supply.	
y	No flammables away near your SD3 motor and amplifier.	
	Be sure to protect the amplifier with a protective enclosure and allow the required clearance around the amplifier (as specified in the SD3 instruction manual) from the enclosure or any devices.	
	Install your SD3 in a location with little dust, and free from water or oil splash.	$\land \land $
	Mount the motor or amplifier on nonflammable surface such as metal.	
	Be sure to have any wiring work carried out by an electrician.	<u>A</u>
	Always ground the FG terminals of the motors and amplifiers.	<u>A</u>
	When working with wires, always turn off the circuit breakers first, carry out the work properly and methodically.	<u>A</u>
	Be sure to connect all cables properly and insulate all conductors with insulating material.	<u>A</u>
	Handling & Operation	
	Never touch the inside of amplifier.	
	Cables must not be damaged, stressed, loaded, or pinched.	
	Never touch the revolving component of the motor while it is in motion.	
	Do not use this product near flammable materials or where it could be subjected to water sprays, a corrosive atmosphere, or an atmosphere of flammable gases.	
	Do not use the product at a location which is subjected to severe vibrations or impact forces.	
>	Do not use the product with any of cables being immersed in oil or water.	
	Do not carry out any wiring work or operations with wet hands.	
	When handling a shaft end key-grooved motor, do not touch the key groove with unprotected hands.	
	Do not touch the motor or the sink of amplifier as they become hot.	
	Do not have the motor driven by external force.	
	Other Precautions	
_	Be sure to verify safety after an earthquake.	
	Carry out mounting and installation securely, in order to prevent fire or personal injury during an earthquake.	
	Install an external emergency stop circuit so that operations can be stopped and power supplies shut down immediately upon occurrence of an emergency.	
	Maintenance & Inspection	
	Never dismantle the SD3 product.	
	The amplifier has components with dangerously high voltage. Prior to each wiring or inspection work, allow more than 5 minutes (after power shuts off) for complete discharge of internal voltage.	A

	A CAUTION	
Symbol	Precautions (Dos and Don'ts)	Anticipated Hazards
	Installation & Wiring	
	Do not touch the connector terminals directly with hands.	
	Do not cover the vent holes of the amplifier. Do not allow ingress of foreign matter.	
	Observe the specifications of motor/amplifier combinations.	A
	For test runs, be sure to check motor movement with the motor being fixed in place and not attached to your mechanical system first, and then install the motor in the mechanical system.	
	Follow the specified mounting method and orientations.	
	Use the right mounting method that is suitable to the main body weight and the rated output of this product.	

ETY PRECAUTIONS

ymbol	Precautions (Dos and Don'ts)	Anticipated Hazards				
	Handling & Operations					
	Do not step on this product or place any heavy object on it.					
	To avoid unstable motions, never make drastic changes in tuning.					
	Do not approach your machine after power restoration following power outage. It may restart unexpectedly. Configure your machine to ensure safety of your personnel against its unexpected restarts.					
	Do not use the product where it could be exposed to direct sunlight.					
	Do not apply impact load to the product.					
	Never operate or stop the motor using the electromagnetic contactor installed on the main power supply side.					
	The brake installed in the motor is only for holding. Do not use it as a decelerating device.					
	Do not use if the motor or amplifier is malfunctioning, broken, or damaged.					
	Confirm that your power supply specifications comply with this product's.					
	The holdong brake is not a stopping device to secure machine safety. To ensure safety, prepare a stopping device for your machinery.					
J [Upon occurrence of an alarm, eliminate the cause and secure safety before resetting the alarm and restarting your machine.					
	Connect the brake control relay and the emergency stop relay in series.					
	Transportation & Storage					
	Do not store the product where it could be subjected to water, moisture, toxic gases, or liquids.					
	Do not hold the cables or the motor shaft when transporting.					
	Do not let the product fall off or fall over during transportation or installation.					
	If the product was stored away for an extended period of time, check with our distributor.					
	Store the product in a location that meets the requirement of storage environments described in the instruction manual.					
	Disposal					
	Prior to disposal of batteries, insulate them with tape or other material. Dispose of them following the local laws and regulations.					
J [When disposing of the SD3 product, treat it as industrial waste.					
	Maintenance & Inspection					
	Overhauls must not be done by anyone but FATEK Automation Corporation.					
	Do not turn the power supply on and off too frequently.					
	Your motor, heat sink of the amplifier, or regenerative resistor may become dangerously hot. Do not touch any of them with hands when power is on or for a while after power shutdown.					
	If your amplifier or motor fails, shut down both of the control power supply and the main circuit power supply.					
	When not using the product for an extended period of time, be sure to turn the power off.	$\overline{\mathbf{A}}$				

Other Considerations and Precautions

Export of this product or its applications

If the end user or application of the product assumes to be involved in military activities or weapons, its export may be subject to "Foreign Exchange and Foreign Trade Law (Japan)" (or equivalent in your country). Have adequate legal reviews and follow any required export procedures.

Medical applications

Do not attempt to use this product or its application for human life related field. This product has been designed and manufactured for general industrial use and its medical applications are not allowed.

Applications for special environments or purposes such as nuclear power, aerospace and transportation

Please contact us in advance.

Applications that could cause serious accidents or damages due to our product failures Be sure to have safety device or protection device installed before using your equipment.

Applying voltage over the rated power supply of this product

Could become fire or smoke hazard to the amplifier. Be sure to check and confirm proper wiring before turning the power on. Be particularly careful in a location such as clean room.

Operations with the motor shaft not grounded electrically

Depending on the device or installation environment, bearing noise might get increased by galvanic corrosion of the motor bearings. Carry out careful check and test on grounding.

Operations in environment under significant influences of external noise and static electricity

This product has been designed and manufactured along with extensive noise tests. However, there is a possibility of unexpected behaviors, depending on user's environment. Practice a fail-safe design and also take adequate measures to ensure safety within the range of machine motion.

Use of this product in a manner not specified by the manufacture

Such use shall void the manufacture warranty. Be mindful before you attempt to do so.

Maintenance and Inspection

Perform regular maintenance and inspections for safe use of this product. Ensure the safety before each inspection work. This product assumes the following operation conditions.

- Ambient temperature : Average annual temperature of 30 °C (not exceeding the rated temperature range)
- Maximum load factor: 80%
- Maximum operating hours: 20 hours a day

Daily Inspection : Check the following before each operation.

- Check ambient temperature, humidity and atmosphere.
- No foreign objects or dust, especially nothing is blocking the vent holes.
- No over bent or damages of the wires.
- Power supply voltage is within the specifications.
- No foreign objects in mobile components of the device and the range of motions.
- When the power is on, there is no unusual noise or smell right after the machinery starts.

Periodic Inspection : Check for the following at least once a year.

- No loose clamp screw problems in the amplifier and motor.
- No deformation or no discoloration in the amplifier, motor, cables, and terminal blocks due to overheat
- No looseness in wiring fixings and terminal block screws

Warranty Information

Terms of Warranty

The term of warranty for this product is twelve (12) months after the date of product manufacture. However, brake equipped motors whose number of axis accelerations and decelerations exceeded the rated maximum shall not be covered by the warranty.

Conditions of Warranty

Should any failure develop during the warranty period under normal operations following the SD3 instruction manual.

- However, even during the warranty period, Manufacture makes only fee-based repair if the failure is due to the following reasons:
 - Misuse, improper repair, or alternation of the product
 - Dropped after the purchase or damaged during transportation
 - Use of this product in a manner not specified by Manufacture
 - Fire, earthquake, lightning, storm and flood damage, salt damage, abnormal voltage, or any other acts of God or natural disasters
 - · Ingress of foreign matter such as water, oil or metal chips.
- This warranty does not apply to parts or accessories that have been used longer than each rated service life.

The warranty applies to delivered products only and Manufacture shall not be liable for any indirect, incidental or consequential damage caused by the product failure or damage.

Contact to :