Standard mechanical Multiturn, optical

Sendix 5863 / 5883 (Shaft / Hollow shaft)

SSI / BiSS-C



The Sendix 5863 and 5883 multiturn encoders with SSI or BiSS-C interface and optical sensor technology can achieve a resolution of max. 29 bits.

A through hollow shaft up to 14 mm and a blind hollow shaft up to 15 mm are available, as well as versions with additional SinCos or RS422 incremental track.























High rotational

Temperature

resistant

Reliable

- Tried-and-tested in applications with the highest demands, such as in wind energy or mobile automation
- Absolutely reliable operation in areas with strong magnetic fields, thanks to mechanical gear with optical sensor technology
- Rugged die-cast housing, remains sealed even in harsh every-
- -40°C...+90°C: use in wide temperature range and protection IP67

Versatile

- Available with SSI or BiSS-C interface and combined with SinCos incremental signals
- The right fixing solution or type of connection available for every application
- · SET button and LED for simple start-up

Order code **Shaft version**



If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days



a Flange

1 = clamping flange, IP65 ø 58 mm [2.28"]

3 = clamping flange, IP67 ø 58 mm [2.28"]

2 = synchro flange, IP65 ø 58 mm [2.28"]

4 = synchro flange, IP67 ø 58 mm [2.28"]

5 = square flange, IP65 □ 63.5 mm [2.5"]

7 = square flange, IP67 □ 63.5 mm [2.5"]

6 = servo flange, IP65 ø 63.5 mm [2.5"] 1)

8 = servo flange, IP67 ø 63.5 mm [2.5"] 1)

Shaft (ø x L), with flat

 $1 = 6 \times 10 \text{ mm} [0.24 \times 0.39"]^{2}$

 $2 = 10 \times 20 \text{ mm} [0.39 \times 0.79^{\circ}]^{3}$

3 = 1/4" x 7/8"

4 = 3/8" x 7/8"

- Interface / Power supply
- 1 = SSI or BiSS-C / 5 V DC
- 2 = SSI or BiSS-C / 10 ... 30 V DC
- 3 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC
- 4 = SSI or BiSS-C, 2048 ppr SinCos / 10 ... 30 V DC
- 5 = SSI or BiSS-C / 5 V DC, with sensor output for monitoring the voltage on the encoder
- 6 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC, with sensor output for monitoring the voltage on the encoder
- 7 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC
- 8 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC
- 9 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC, with sensor output for monitoring the voltage on the encoder
- Type of connection
- 1 = axial cable, 1 m [3.28'] PVC
- 2 = radial cable, 1 m [3.28'] PVC
- 3 = M23 connector, 12-pin, axial
- 4 = M23 connector, 12-pin, radial
- 6 = M12 connector, 8-pin, radial 4)
- 5 = M12 connector, 8-pin, axial 4)

- Code
- B = SSI, Binary
- C = BiSS-C, Binary
- G = SSI, Gray
- Resolution 5)
- A = 10 bit ST + 12 bit MT
- 1 = 11 bit ST + 12 bit MT 2 = 12 bit ST + 12 bit MT
- 3 = 13 bit ST + 12 bit MT
- 4 = 14 bit ST + 12 bit MT
- 7 = 17 bit ST + 12 bit MT
- Inputs / Outputs 5)
- 2 = SET, DIR input additional status output
- Options (Service)
- 1 = no option
- 2 = Status LED
- 3 = SET button and Status LED

optional on request

- Ex 2/22
- seawater-resistant
- special cable length

Preferred type only in conjunction with flange type 2

³⁾ Preferred type only in conjunction with flange type 1

⁴⁾ Uniquement averc interface 1 et 2

⁵⁾ Resolution, preset value and counting direction factory-programmable



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Order code **Hollow shaft**

XX2X |X|X|X|X|8.5883 **8 0 8 0** 000

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. ${\tt Qts.}\ {\tt up}\ {\tt to}\ {\tt 50}\ {\tt pcs.}\ {\tt of}\ {\tt these}\ {\tt types}\ {\tt generally}\ {\tt have}\ {\tt a}\ {\tt delivery}\ {\tt time}\ {\tt of}\ {\tt 15}\ {\tt working}\ {\tt days}.$



a Flange

1 = with spring element long, IP65

2 = with spring element long, IP67

3 = with stator coupling, IP65 ø 65 mm [2.56"]

4 = with stator coupling, IP67 ø 65 mm [2.56"]

5 = with stator coupling, IP65 ø 63 mm [2.48"]

6 = with stator coupling, IP67 ø 63 mm [2.48"]

b Hollow shaft

3 = Ø 10 mm [0.39"]

4 = ø 12 mm [0.47"]

 $5 = \emptyset 14 \text{ mm } [0.55"]$ 6 = Ø 15 mm [0.59"] - blind hollow shaft

8 = 0.3/8

 $9 = \emptyset 1/2"$

Interface / Power supply

1 = SSI or BiSS-C / 5 V DC

2 = SSI or BiSS-C / 10 ... 30 V DC

3 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC

4 = SSI or BiSS-C, 2048 ppr SinCos / 10 ... 30 V DC

5 = SSI or BiSS-C / 5 V DC, with sensor output

for monitoring the voltage on the encoder 6 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC,

with sensor output for monitoring the voltage on the encoder

7 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC

8 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC

9 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC, with sensor output for monitoring the voltage on the encoder

d Type of connection

2 = radial cable, 1 m [3.28'] PVC

4 = M23 connector, 12-pin, radial

6 = M12 connector, 8-pin, radial 2)

E = tangential cable, 1 m [3.28'] PVC

Code

B = SSI, Binary

C = BiSS-C, Binary

G = SSI, Gray

Resolution 1)

A = 10 bit ST + 12 bit MT

1 = 11 bit ST + 12 bit MT

2 = 12 bit ST + 12 bit MT3 = 13 bit ST + 12 bit MT

4 = 14 bit ST + 12 bit MT

7 = 17 bit ST + 12 bit MT

Inputs / Outputs 1)

2 = SET, DIR input

additional status output

Options (Service)

1 = no option

2 = Status LED

3 = SET button and Status LED

optional on request

- Ex 2/22

- seawater-resistant

- special cable length

Mounting accessory	for shaft encoders		Order No.
Coupling		Bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1101.0606 8.0000.1101.1010
Mounting accessory	for hollow shaft encoders		
Cylindrical pin, long for torque stops	\$\[\frac{8[0,31]}{5[0,2]} \] \[\frac{50}{2} \] \[With fixing thread	8.0010.4700.0000
Connection technolog	gy		
Connector, self-assem	ıbly (straight)	M12 female connector with coupling nut M23 female connector with coupling nut	05.CMB 8181-0 8.0000.5012.0000
Cordset, pre-assemble	ed	M12 female connector with coupling nut, 2 m [6.56'] PVC cable M23 female connector with coupling nut, 2 m [6.56'] PVC cable	05.00.6041.8211.002M 8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology

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¹⁾ Resolution, preset value and counting direction factory-programmable

²⁾ Only in conjunction with interface type 1 and 2 www.kuebler.com



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Technical data

Mechanical	characteristics						
Max. speed, shaft version	IP65 up to 70°C [158°F] IP65 up to T _{max} IP67 up to 70°C [158°F] IP67 up to T _{max}	12 000 min ⁻¹ , 10 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous) 11 000 min ⁻¹ , 9 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous)					
Max. speed, hollow shaft version	IP65 up to 70°C [158°F] IP65 up to T _{max} IP67 up to 70°C [158°F] IP67 up to T _{max}	9 000 min ⁻¹ , 6 000 min ⁻¹ (continuous) 6 000 min ⁻¹ , 3 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 4 000 min ⁻¹ (continuous) 4 000 min ⁻¹ , 2 000 min ⁻¹ (continuous)					
Starting torque at 20°C [68°F]	IP65 IP67	< 0.01 Nm < 0.05 Nm					
Moment of iner	tia shaft version hollow shaft version	4.0 x 10 ⁻⁶ kgm ² 7.0 x 10 ⁻⁶ kgm ²					
Load capacity o	of shaft radial axial	80 N 40 N					
Weight		approx. 0.45 kg [15.87 oz]					
Protection acc.		IDOT					
	housing side shaft side	IP67 IP65, opt. IP67					
EX approval for	hazardous areas	optional Zone 2 and 22					
Working tempe	rature range	-40°C +90°C ¹⁾ [-40°F +194°F] ¹⁾					
Material	shaft/hollow shaft flange housing cable	stainless steel aluminium zinc die-cast housing PVC					
Shock resistan	ce acc. EN 60068-2-27	2500 m/s ² , 6 ms					
Vibration resist	tance acc. EN 60068-2-6	100 m/s ² , 55 2000 Hz					

Electrical characteristics	
Power supply	5 V DC + 5% or 10 30 V DC
Current consumption (no load) 5 V DC 10 30 V DC	max. 80 mA max. 50 mA
Reverse polarity protection of the power supply (+V)	yes (at 10 30 V DC)
Short circuit proof outputs	yes ²⁾
UL approval	File 224618
CE compliant acc. to	EMC guideline 2004/108/EC
RoHS compliant acc. to	guideline 2011/65/EU

SSI interface						
Output driver	RS485 transceiver type					
Permissible load / channel	max. 20 mA					
Signal level HIGH	typ. 3.8 V					
LOW at I _{Load} = 20 mA	typ 1.3 V					
Singleturn resolution	1014 bit and 17 bit ³⁾					
Number of revolutions	4096 (12 bit)					
Code	Binary or Gray					
SSI clock rate	50 kHz 2 MHz					
Monoflop time	≤ 15 µs					

Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the $\,$ data transfer starts with the new values The update rate is dependent on the clock speed, data length and monoflop-time.

Status and paris	tv bit	on request
rate	ST resolution ≥ 15 bit	4 μs
Data refresh	ST resolution ≤ 14 bit	≤ 1 µs

BiSS-C Interface	
Singleturn resolution	10 14 bit and 17 bit ³⁾
Number of revolutions	4096 (12 bit)
Code	Binary
Clock rate	50 kHz 10 MHz
Max. update rate	$<$ 10 $\mu s,$ depends on the clock rate and the data length
Data refresh rate	≤ 1 µs
	rogrammable parameters are: ion, alarms and warnings

 Bidirectional, factory programmable parameters are:
resolution, code, direction, alarms and warnings
CRC data verification

SET input or SET button		
Input		active HIGH
Input type		comparator
Signal level	HIGH	min: 60 % of +V (power supply) max: +V
	LOW	max: 25 % of +V (power supply)
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Timeout after SET signal		14 ms
Response time (DIR input)		1 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point $\,$ pen or similar).

Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the status output is at LOW.

Option incremental outputs (A/B), 2048 ppr									
	RS422 TTL-compatible								
Max. frequency -3dB	400 kHz	400 kHz							
Signal level	1 Vpp (± 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V							
Short circuit proof	yes	yes							

¹⁾ Cable version: -30°C ... +75°C [-22°F ... +167°F]

²⁾ Short circuit to OV or to output, one channel at a time, power supply correctly applied 3) Other options on request



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Status output and LED	
Output driver	Open Collector, internal pull up resistor 22 kOhm
Permissible load	max. 20 mA
Signal level	HIGH: +V / LOW: < 1 V
Active	LOW

The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (Open Collector with int. pull-up 22k).

An active status output (LOW) displays:

- Sensor error, singleturn or multiturn (soiling, glass breakage etc.)
- LED fault (failure or ageing)
- over- or under-temperature

In the SSI mode, the fault indication can only be reset by switching off the power-supply to the device.

DIR input

A HIGH signal switches the direction of rotation from the default CW to CCW. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The LED will come ON and the status output will switch to LOW.

Power-on delay

After Power-ON the encoder requires a time of approx. 150 ms before valid data can be read.

Terminal assignment

Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
1, 2 1, 2, E	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	Ţ	
	SEI, DIN, Status	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	-	-	shield	
Interface	Type of connection	Features	M23 connector													
1, 2	3, 4	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	Ť
1, 2	3, 4	JET, DITT, Status	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ally befo	re initia	ıl start-ı	ıp)						
5	1, 2, E	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0 Vsens	+Vsens	Ŧ
J	1, 2, L	sensor output	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
5	3, 4	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0 Vsens	+Vsens	Ŧ
J	3, 4	sensor output	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ally befo	re initia	ıl start-ı	ıp)						
3, 4, 7, 8	1, 2, E	SET, DIR, SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	А	Ā	В	B	Ţ
3, 4, 7, 0	1, 2, L	or incr. RS422	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
3, 4, 7, 8	3, 4	SET, DIR, SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Α	Ā	В	B	Ţ
3, 4, 7, 0	3, 4	or incr. RS422	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ally befo	re initia	ıl start-ı	ıp)						
6, 9	1, 2, E	SinCos o. incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	Α	Ā	В	B	0 Vsens	+Vsens	Ŧ
0, 5	1, 2, E	sensor output	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	ВК	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
6, 9	3, 4	SinCos o. incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	А	Ā	В	B	0 Vsens	+Vsens	Ť
0, 3	3, 4	sensor output	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	M12 connector													
1, 2	5, 6	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR		Ŧ			
		5, 6	JEI, DIN	Pin:	1	2	3	4	5	6	7	8		PH		

+V: Encoder power supply +V DC

0 V: Encoder power supply ground GND (0 V) 0 Vsens / +Vsens: Using the sensor outputs of the encoder,

the voltage present can be measured and if necessary increased accordingly.

C+, C-: Clock signal D+, D-: Data signal

A, \overline{A} : Incremental output channel A (cosine) B, \overline{B} : Incremental output channel B (sine)

SET: SET input. The current position

DIR: Direction input: If this input is active, output values are counted backwards (decrease) when the

shaft is turning clockwise.

Stat: Status output

PH ±: Plug connector housing (Shield)

Top view of mating side, male contact base





M12 connector, 8-pin

M23 connector, 12-pin



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Dimensions shaft version

Dimensions in mm [inch]

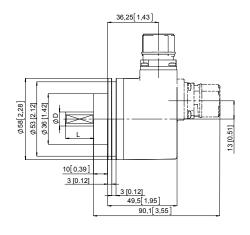
Clamping flange, ø 58 [2.28] Flange type 1 and 3

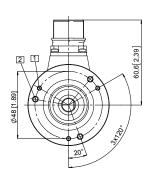
(Drawing with M23 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

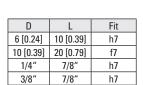


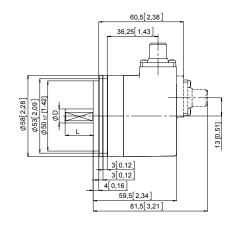


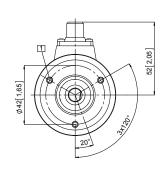
Synchro flange, ø 58 [2.28] Flange type 2 and 4

(Drawing with M12 connector)

1 M4, 6 [0.24] deep



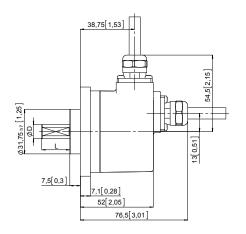


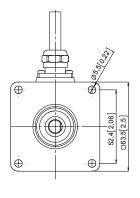


Square flange, \square 63.5 [2.5] Flange type 5 and 7

(Drawing with cable)

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7







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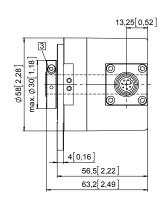
Dimensions hollow shaft version

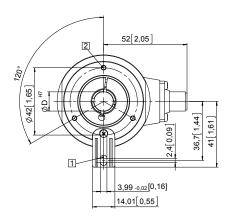
Dimensions in mm [inch]

Flange with spring element long Flange type 1 and 2

(drawing with M12 connector)

- 1 Torque stop slot, Recommendation: Cylindrical pin DIN 7, ø 4 [0.16]
- 2 M3, 6 [0.24] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

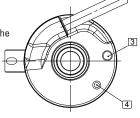


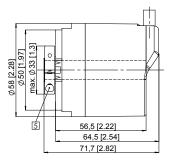


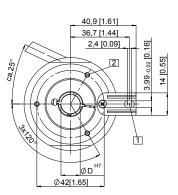
Flange with spring element long Flange type 1 and 2

(drawing with tangential cable)

- 1 Torque stop slot, Recommendation: Cylindrical pin DIN 7, ø 4 [0.16]
- 2 M3, 5.5 [0.21] deep
- 3 Status-LED
- 4 SET button
- 5 Recommended torque for the clamping ring 0.6 Nm









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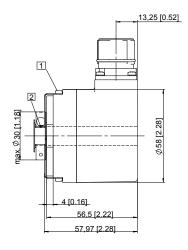
Dimensions hollow shaft version

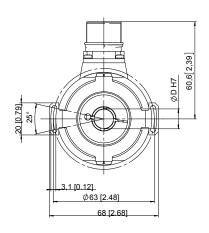
Dimensions in mm [inch]

Flange with stator coupling, ø 63 [2.48] Flange type 5 and 6 $\,$

Pitch circle diameter for fixing screws 63 [2.48] (Drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8 (Washer included in delivery
- 2 Recommended torque for the clamping ring 0.6 Nm





Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4 $\,$

Pitch circle diameter for fixing screws 65 [2.56] (Drawing with cable)

1 Recommended torque for the clamping ring 0.6 Nm

