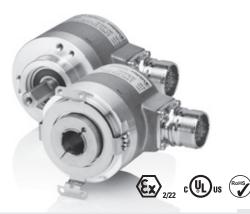


Standard SIL2/PLd, mech. Multiturn, optical

Sendix SIL 5863FS2 / 5883FS2 (Shaft / Hollow shaft) SSI/BiSS-C+SinCos





The absolute multiturn encoders 5863FS2 and 5883FS2 of the Sendix SIL family are suited for use in safety-related applications up to SIL2 according to EN 61800-5-2 or PLd to EN ISO 13849-1.

The extra strong Safety-Lock™ Design interlocked bearings, the high integration density of the components based on OptoASIC technology and the rugged die-cast housing make these devices ideal also for demanding applications outdoors up to IP67.

































Temperature range

resistant

Magnetic field

Reverse polarity

Functional Safety

- Encoder with individual certificate from IFA / TÜV
- Suitable for applications up to SIL2 acc. to EN 61800-5-2
- Suitable for applications up to PLd acc. to EN ISO 13849-1
- . SSI or BiSS-C interface with incremental SinCos tracks with 2048 ppr
- · Certified mechanical mounting + electronic

Flexible

- · Shaft and hollow shaft versions
- Cable and connector variants
- · Various mounting options available

Order code Shaft version

8.5863FS2 Type

0000



If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Ω ts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

1 = clamping flange, IP65, ø 58 mm [2.28"]

Shaft (ø x L)

 $2 = 10 \times 20 \text{ mm} [0.39 \times 0.79]$, with flat

 $A = 10 \times 20 \text{ mm} [0.39 \times 0.79''], \text{ with feather key}$

C Interface / Power supply

3 = SSI or BiSS-C + 2048 ppr SinCos / 5 V DC

4 = SSI or BiSS-C + 2048 ppr SinCos / 10 ... 30 V DC

Type of connection 1 = axial cable, 1 m [3.28'] PVC

2 = radial cable, 1 m [3.28'] PVC

3 = M23 connector, 12 pin, axial

4 = M23 connector, 12 pin, radial

Code

B = SSI, Binary

C = BiSS-C, Binary

G = SSI, Gray

Resolution 1)

A = 10 bit ST + 12 bit MT

1 = 11 bit ST + 12 bit MT 2 = 12 bit ST + 12 bit MT

3 = 13 bit ST + 12 bit MT

4 = 14 bit ST + 12 bit MT

7 = 17 bit ST + 12 bit MT

Inputs / outputs 1) 2 = SET, DIR inputs

Options (Service)

1 = no option

2 = Status LED

3 = SET button and Status LED

optional on request

- special cable length

- Ex 2/22

Order code Hollow shaft

8.5883FS2

X|X|2|X**a** 0 **a** 0 0000 If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Ots. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

A = with torque stop set, IP65

B = with stator coupling, IP65, ø 63 mm [2.48"]

b Hollow shaft

 $3 = \emptyset 10 \text{ mm} [0.39"]$

4 = ø 12 mm [0.47"]

 $5 = \emptyset 14 \text{ mm } [0.55"]$ $K = \emptyset$ 10 mm [0.39"], tapered shaft

Interface / Power supply

3 = SSI or BiSS-C + 2048 ppr SinCos / 5 V DC 4 = SSI or BiSS-C + 2048 ppr SinCos / 10 ... 30 V DC Type of connection

2 = radial cable, 1 m [3.28'] PVC

E = tangential cable, 1 m [3.28'] PVC

4 = M23 connector, 12 pin, radial

Code

B = SSI, Binary

C = BiSS-C, Binary

G = SSI, Gray

Resolution 1)

A = 10 bit ST + 12 bit MT

1 = 11 bit ST + 12 bit MT

2 = 12 hit ST + 12 hit MT

3 = 13 bit ST + 12 bit MT 4 = 14 bit ST + 12 bit MT7 = 17 bit ST + 12 bit MT

 Inputs / outputs 1) 2 = SET, DIR inputs

Options (Service)

1 = no option

2 = Status LED

3 = SET button and Status LED

optional on request

- special cable length

- Ex 2/22

¹⁾ Resolution, preset value and count direction are factory-programmable



Standard SIL2/PLd, mech. Multiturn, optical Sendix SIL 5863FS2 / 5883FS2 (Shaft / Hollow shaft) SSI/BiSS-C+SinCos

Accessory safety technology		Order No.
Safety-M, basic modules	speed / position monitoring for 1 axis speed / position monitoring for 2 axes (analogue inputs optional)	8.MSP1.000 8.MSP2.XXX
Connection technology		
Connector, self-assembly (straight)	M23 female connector with coupling M23 female connector with coupling, Ex zone 2/22	8.0000.5012.0000 8.0000.5012.0000.Ex
Cordset, pre-assembled	M23 female connector with coupling nut, 2 m [2.19'] PVC cable	8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology You will find an overview of our systems and components for functional safety under www.kuebler.com/safety

Technical data

Notes regarding "Functional Safety"

These encoders are suitable for use in safety-related systems up to SIL2 acc. to EN 61800-5-2 and PLd to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality.

Additional functions can be found in the operating manual.

Safety characteristics	
Relevant standards	EN ISO 13849-1 /
	EN 61800-5-2, EN 61508
Classifiction	PLd / SIL2
System structure	2 channel (Cat. 3 / HFT = 1)
PFH _d value 1)	2.16 x 10 ⁻⁸ h ⁻¹
Proof-test interval	20 years

Mechanical characteristics						
Max. speed, shaft version						
up to 70°C [158°F	⁻] 12 000 min ⁻¹ , 10 000 min ⁻¹ (continuous)					
up to Tma	x 8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous)					
Max. speed, hollow shaft version						
up to 70°C [158°F	⁻] 9 000 min ⁻¹ , 6 000 min ⁻¹ (continuous)					
up to Tma	6 000 min ⁻¹ , 3 000 min ⁻¹ (continuous)					
Starting torque - at 20°C [68°F]						
shaft versio	n < 0.01 Nm					
hollow shaft versio	n < 0.03 Nm					
Moment of inertia shaft versio	n 4.0 x 10 ⁻⁶ kgm ²					
hollow shaft versio	n 7.0 x 10 ⁻⁶ kgm ²					
Load capacity of shaft radia	ıl 80 N					
axia	1 40 N					
Weight	approx. 0.45 kg [15.87 oz]					
Protection acc. to EN 60529						
housing sid	e IP67					
shaft sid	e IP65					
Hazardous area approval	optional zone 2 and 22					
Working temperature range	-40°C +90°C ²)					
	[-40°F +194°F] ²)					
Material shaft / hollow shaft	ft stainless steel					
flang	e aluminium					
housin	3					
cabl	e PVC					
Shock resistance acc. EN 60068-2-27	500 m/s ² , 11 ms					
Vibration resistance acc. EN 60068-2-6	200 m/s ² , 10 150 Hz					

Electrical characte	ristics					
Power supply		5 V DC ± 5% or 10 30 V DC				
Current consumption	5 V DC	max. 80 mA				
(no output load)	10 30 V DC	max. 50 mA				
Reverse polarity protec	tion	yes				
of the power supply (+V)						
Short circuit proof outp	uts	yes 3)				
UL approval		File 224618				
CE compliant acc. to		EMC guideline 2004/108/EC				
·		Machinery directive 2006/42/EC				
RoHS compliant acc. to)	guideline 2002/95/EC				

¹⁾ The specified value is based on a diagnostic coverage of 90%, that must be achieved with an $\,$ encoder evaluation unit.

encoder evaluation unit.

The encoder evaluation unit must meet at least the requirements for SIL2.

Cable version: -30 °C...+90°C [-22°F...+194°F]

Short circuit to 0 V or to output, one channel at a time, power supply correctly applied



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SSI interface		
Output driver		RS485 transceiver type
Permissible loa	d / channel	max. ±20 mA
Signal level	HIGH	typ 3.8 V
	LOW at $I_{Load} = 20 \text{ mA}$	typ 1.3 V
Singleturn resolution		10 14 bit and 17 bit 1)
Number of revol	utions	4096 (12 bit)
Code		Binary or Gray
SSI clock rate resolution ST ≤ 14 bit		50 kHz 2 MHz
resolution ST ≥ 15 bit		50 kHz 125 kHz
Monoflop time		≤ 15 µs

Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.

Data refresh	resolution ST ≤ 14 bit	•
rate	resolution ST \geq 15 bit	4 μS
Status and parit	y bit	on request

BiSS-C interface	
Singleturn resolution	10 14 bit and 17 bit 1)
Number of revolutions	4096 (12 bit)
Code	Binary
Clock rate	up to 10 MHz
Max. update rate	$<$ 10 μs , depends on the clock rate and the data length
Data refresh rate	≤ 1 µs
Note: - Bidirectional, factory p	rogrammable parameters are:

	· · · · · · · · · · · · · · · · · · ·
Note:	 Bidirectional, factory programmable parameters are:
	resolution, code, direction, alarms and warnings
	 CRC data verification

SinCos interface	
Max. frequency -3dB	400 kHz
Signal level	1 Vpp (± 10%)
Short circuit proof	yes
Pulse rate	2048 ppr

SET input or SET button		
Input		active HIGH
Input type		comparator
Signal level	HIGH LOW	min: 60 % of +V, max: +V max: 25 % of +V (power supply)
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Timeout after SET signal		14 ms
Reaction time (DIR input)		1 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal delay time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the LED is ON.

DIR input

A HIGH signal switches the direction of rotation from the default CW to CCW. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The LED will come ON and the status output will switch to LOW.

Power-on delay

After Power-ON the encoder requires a time of approx. 150 ms before valid data can be read.

LED

The optional LED (red) serves to display various alarm or error messages. In normal operation the LED is OFF.

If the LED is ON (status output LOW) this indicates:

- Sensor error, singleturn or multiturn (soiling, glass breakage etc.)
- LED error, failure or ageing
- Over- or under-temperature

In the SSI mode, the fault indication can only be reset by switching off the power supply to the device.

Terminal assignment

Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)													
3, 4 1, 2, E	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Α	Ā	В	\overline{B}	Ţ	
	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield	
Interface	Type of connection	M23 connecto	M23 connector, 12-pin												
3, 4 3, 4	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	А	Ā	В	B	Ť	
	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH	

+V: Encoder power supply +V DC

0 V: Encoder power supply ground GND (0 V)

C+, C-: Clock signal D+, D-:

SET: Set input. The current position becomes defined as position zero. DIR: Direction input: If this input is active, output values are counted backwards (decrease) when the shaft is turning clockwise.

A, \overline{A} : cosine signal B, \overline{B} : sine signal

PH ±: Plug connector housing (shield)

Top view of mating side, male contact base



M23 connector, 12-pin



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Dimensions shaft version

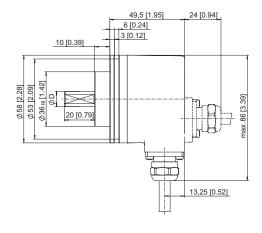
Dimensions in mm [inch]

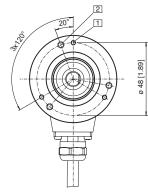
Clamping flange, ø 58 [2.28] Flange type 1 with shaft type 2 (Drawing with cable)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep

 $D = 10^{f7} [0.39]$





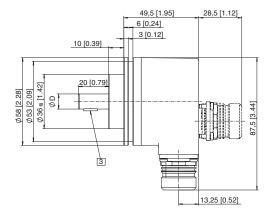
Clamping flange, ø 58 [2.28] Flange type 1 with shaft type A (Drawing with M23 connector)

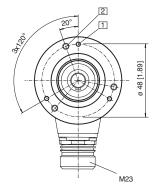
1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep

3 Feather key DIN 6885 - A - 3x3x6

 $D = 10^{h7} [0.39]$







Standard

SIL2/PLd, mech. Multiturn, optical

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Dimensions hollow shaft version

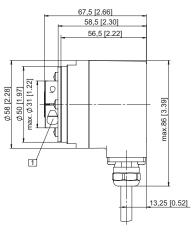
Dimensions in mm [inch]

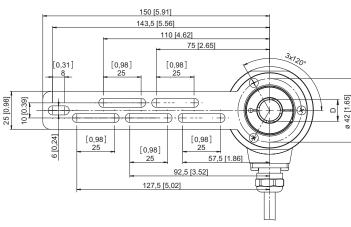
Flange with torque stop set Flange type A

(Drawing with cable)

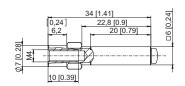
1 SW 3, recommended torque for the clamping ring 2.5 Nm

 $D = \emptyset 10^{H7} [0.39]$ ø 12 ^{H7} [0.47] ø 14 ^{H7} [0.55]





Torque pin with rectangular sleeve with M4 thread, 10 [0.39] deep





Flange with stator coupling, ø 63 [2.48] and hollow shaft

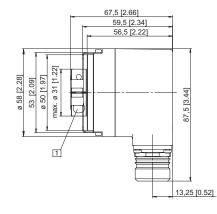
Flange type B

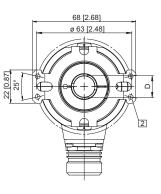
(Drawing with M23 connector)

1 SW 3, recommended torque for the clamping ring 2.5 Nm

2 for (4x) M3 screw

 $D = \emptyset 10^{H7} [0.39]$ ø 12 H7 [0.47] ø 14 ^{H7} [0.55]





Flange with stator coupling, ø 63 [2.48]

and tapered shaft

Flange type B

(Drawing with tangential cable outlet)

1 for (4x) M3 screw

2 Status LED

3 SET button

4 SW 4

