

Standard electronic Multiturn, optical

Sendix F5863 / F5883 (Shaft / Hollow shaft)

SSI / BiSS-C



The Sendix F58 Multiturn with patented Intelligent Scan Technology™ is a particularly high resolution optical multiturn encoder without gears and with 100 percent magnetic insensitivity.

41 bits total resolution, through hollow shaft up to 15 mm and versions with additional SinCos or RS422 incremental track.

































Multiturn Resolution

High rotational

resistant

Reverse polarity

version on request

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors
- · Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +85°C
- Patented Intelligent Scan Technology[™] with all singleturn and multiturn functions on one single OptoASIC - offering the highest reliability, a high resolution up to 41 bits and 100% magnetic field insensitivity.

Versatile

- · Available with SSI or BiSS-C interface and combined with SinCos incremental signals
- . The right fixing solution or type of connection available for every application
- · SET button and LED for simple start-up
- · High resolution feedback in real-time via incremental outputs SinCos and RS422
- Short control cycles, clock frequency with SSI up to 2 MHz / with BiSS-C up to 10 MHz

Order code **Shaft version**

8.F5863

8000



If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Ots. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

1 = clamping flange, IP65 ø 58 mm [2.28"]

3 = clamping flange, IP67 ø 58 mm [2.28"]

2 = synchro flange, IP65 ø 58 mm [2.28"]

4 = synchro flange, IP67 ø 58 mm [2.28"]

b Shaft (ø x L), with flat

 $1 = 6 \times 10 \text{ mm} [0.24 \times 0.39"]^{1}$

 $2 = 10 \times 20 \text{ mm} [0.39 \times 0.79"]^{2}$

3 = 1/4" x 7/8"

4 = 3/8" x 7/8"

© Interface / Power supply

1 = SSI or BiSS-C / 5 V DC

2 = SSI or BiSS-C / 10 ... 30 V DC

3 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC

4 = SSI or BiSS-C, 2048 ppr SinCos / 10 ... 30 V DC

5 = SSI or BiSS-C / 5 V DC, with sensor output for monitoring the voltage on the encoder

6 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC, with sensor output for monitoring the voltage on the encoder

7 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC

8 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC

1 Type of connection

1 = axial cable, 1 m [3.28'] PVC

2 = radial cable, 1 m [3.28'] PVC

3 = M23 connector, 12-pin, axial

4 = M23 connector, 12-pin, radial

5 = M12 connector, 8-pin, axial 3) 6 = M12 connector, 8-pin, radial 3) Code

B = SSI, Binary

C = BiSS-C, Binary

G = SSI, Gray

Resolution

(Singleturn) 1)

A = 10 bit

1 = 11 bit2 = 12 hit

3 = 13 bit

4 = 14 bit7 = 17 bit

¶ Resolution (Multiturn)

2 = 12 bit MT

6 = 16 bit MT

4 = 24 bit MT

Options (Service)

1 = no option

2 = Status LED

3 = SET button and **Status LED**

optional on request

- Fx 2/22

- seawater-resistant

- special cable length

¹⁾ Preferred type only in conjunction with flange type 2

²⁾ Preferred type only in conjunction with flange type 1

³⁾ Can be combined only with interface 1 and 2

⁴⁾ Resolution, preset value and counting direction factory-programmable



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Order code **Hollow shaft**

|X|X|X|X||X|X|X|X8.F5883 **8000** 0000 If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. ${\tt Qts.}$ up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

- 1 = with spring element long, IP65
- 2 = with spring element long, IP67
- 3 = with stator coupling, IP65 ø 65 mm [2.56"]
- 4 = with stator coupling, IP67 ø 65 mm [2.56"]
- 5 = with stator coupling, IP65 ø 63 mm [2.48"]
- 6 = with stator coupling, IP67 ø 63 mm [2.48"]

Hollow shaft

- $3 = \emptyset 10 \text{ mm} [0.39"]$
- 4 = ø 12 mm [0.47"]
- $5 = \emptyset 14 \text{ mm } [0.55"]$
- $6 = \emptyset 15 \text{ mm } [0.59''] \text{blind hollow shaft}$
- $8 = \emptyset 3/8"$
- 9 = 0.01/2"

Interface / Power supply

- 1 = SSI or BiSS-C / 5 V DC
- 2 = SSI or BiSS-C / 10 ... 30 V DC
- 3 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC
- 4 = SSI or BiSS-C, 2048 ppr SinCos / 10 ... 30 V DC
- 5 = SSI or BiSS-C / 5 V DC, with sensor output
- for monitoring the voltage on the encoder
- 6 = SSI or BiSS-C, 2048 ppr SinCos / 5 V DC, with sensor output for monitoring the voltage on the encoder
- SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC
- 8 = SSI or BiSS-C and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC

d Type of connection

- 2 = radial cable, 1 m [3.28'] PVC
- 4 = M23 connector, 12-pin, radial
- 6 = M12 connector, 8-pin, radial 2)
- E = tangential cable, 1 m [3.28'] PVC

Code

- B = SSI, Binary
- C = BiSS-C, Binary
- G = SSI, Gray

Resolution (Singleturn) 1)

- A = 10 bit
- 1 = 11 bit2 = 12 bit
- 3 = 13 bit
- 4 = 14 bit
- 7 = 17 bit

Resolution (Multiturn)

- 2 = 12 bit MT
- 6 = 16 bit MT
- 4 = 24 bit MT

Options (Service)

- 1 = no option
- 2 = Status LED
- 3 = SET button and **Status LED**

optional on request

- Ex 2/22
- seawater-resistant
- special cable length

Mounting accessory	for shaft encoders		Order No.
Coupling		Bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1101.0606 8.0000.1101.1010
Mounting accessory	for hollow shaft encoders		
Cylindrical pin, long for torque stops	8[0,31] 5[0,2] SW7 [0,28] 9 10 10 10 10 10 10 10 10 10 10	With fixing thread	8.0010.4700.0000
Connection technolog	gy		
Connector, self-assem	ıbly (straight)	M12 female connector with coupling nut M23 female connector with coupling nut	05.CMB 8181-0 8.0000.5012.0000
Cordset, pre-assemble	ed	M12 female connector with coupling nut, 2 m [6.56'] PVC cable M23 female connector with coupling nut, 2 m [6.56'] PVC cable	05.00.6041.8211.002M 8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology

¹⁾ Resolution, preset value and counting direction factory-programmable

²⁾ Can be combined only with Interface 1 and 2



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Technical data

Mechanical	characteristics	
Max. speed, shaft version	IP65 up to 70°C [158°F] IP65 up to T _{max} IP67 up to 70°C [158°F] IP67 up to T _{max}	12 000 min ⁻¹ , 10 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous) 11 000 min ⁻¹ , 9 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous)
Max. speed, hollow shaft version	IP65 up to 70°C [158°F] IP65 up to T _{max} IP67 up to 70°C [158°F] IP67 up to T _{max}	9 000 min ⁻¹ , 6 000 min ⁻¹ (continuous) 6 000 min ⁻¹ , 3 000 min ⁻¹ (continuous) 8 000 min ⁻¹ , 4 000 min ⁻¹ (continuous) 4 000 min ⁻¹ , 2 000 min ⁻¹ (continuous)
Starting torque at 20°C [68°F]	IP65 IP67	< 0.01 Nm < 0.05 Nm
Moment of iner	tia shaft version hollow shaft version	3.0 x 10 ⁻⁶ kgm ² 6.0 x 10 ⁻⁶ kgm ²
Load capacity of shaft radial axial		80 N 40 N
Weight		approx. 0.45 kg [15.87 oz]
Protection acc. to EN 6052	housing side 9 shaft side	IP67 IP65, opt. IP67
EX approval for	hazardous areas	optional Zone 2 and 22
Working tempe	rature range	-40°C +85°C [-40°F +185°F] 1)
Material shaft/hollow shaft flange housing cable		stainless steel aluminium zinc die-cast housing PVC
Shock resistan	ce acc. EN 60068-2-27	2500 m/s², 6 ms
Vibration resist	ance acc. EN 60068-2-6	100 m/s ² , 55 2000 Hz

Electrical characteristics	S	
Power supply		5 V DC + 5% or 10 30 V DC
Current consumption (no load) 5 V DC		max. 60 mA
10 .	30 V DC	max. 30 mA
Reverse polarity protection of the power supply (+V)		yes (at 10 30 V DC)
Short circuit proof outputs		yes ²⁾
CE compliant acc. to		EMC guideline 2004/108/EC
RoHS compliant acc. to		guideline 2011/65/EU

SSI interface								
Output driver	RS485 transceiver type							
Permissible load / channel	max. ± 30 mA							
Signal level HIGH	typ 3.8 V							
LOW at I _{Load} = 20 mA	typ 1.3 V							
Short circuit proof outputs	yes ²⁾							
Singleturn resolution	10 17 bit							
Number of revolutions	max. 24 bit							
Code	Binary or Gray							
SSI clock rate	50 kHz 2 MHz							
Monoflop time	≤ 15 µs							
No. 10 de la								

Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.

Data refresh rate	ST resolution ≤ 14 bit ST resolution ≥ 15 bit	
Status and parity	bit	on request

BiSS-C interface						
Singleturn resolution	10 17 bit					
Number of revolutions	max. 24 bit					
Code	Binary					
BiSS-C clock rate	50 kHz 10 MHz					
Max. update rate	$<$ 10 μs , depends on the clock rate and the data length					
Data refresh rate	≤ 1 µs					
	rogrammable parameters are: tion, alarms and warnings					

SET input		
Input		active HIGH
Input type		comparator
Signal level	HIGH	min. 60 % of +V, max: +V
(+V = power supply)	LOW	max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input Delay		1 ms
New position data readable after		1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS-C. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the power supply must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

Option incremental outputs (A/B), 2048 ppr										
SinCos RS422 TTL-compatible										
Max. frequency -3dB	400 kHz	400 kHz								
Signal level	1 Vpp (± 20%)	HIGH: min. 2.5 V								
		LOW: max. 0.5 V								
Short circuit proof	yes ²⁾	yes ²⁾								

Status output and LED	
Output driver	Open Collector, internal pull up resistor 22 kOhm
Permissible load	max. 20 mA
Signal level	HIGH: +V / LOW: < 1 V
Active	LOW

The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (Open Collector with int. pull-up 22k).

An active status output (LOW) displays:

- Sensor error, singleturn or multiturn (soiling, glass breakage etc.)
- LED fault (failure or ageing)
- over- or under-temperature

In the SSI mode, the fault indication can only be reset by switching off the power-supply to the device.

¹⁾ Cable version: -30°C ... + 75°C [-22°F ... +167°F]

²⁾ Short circuit to 0 V or to output; if power supply correctly applied



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DIR input

A HIGH signal switches the direction of rotation from the default CW to CCW. This inverted function can also be factory-programmed. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The status output will switch to LOW.

Response time (DIR input)

1 ms

Power-ON delay

After Power-ON the device requires a time of approx. 150 ms before valid data can be read. Hot plugging of the encoder should be avoided.

Terminal assignment

Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
1.0	1.0.5	OFT DID Otation	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	Ť
1, 2 1, 2, E	SET, DIR, Status	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	ВК	-	-	-	shield	
Interface	Type of connection	Features	M23 connector													
1, 2	3, 4	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	Ť
1,2	0, 4	OL1, DI11, Otatas	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ılly befo	re initia	l start-u	ıp)						
5	1, 2, E	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0 Vsens	+Vsens	Ť
J	1, 2, L	sensor output	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
5	3, 4	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0 Vsens	+Vsens	Ť
J	3, 4	sensor output	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ılly befo	re initia	l start-u	ıp)						
3, 4, 7, 8	1, 2, E	SET, DIR, SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Α	Ā	В	B	Ť
3, 4, 7, 8 1, 2, E	1, 2, E	or incr. RS422	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
3, 4, 7, 8	3, 4	SET, DIR, SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Α	Ā	В	B	Ť
3, 4, 7, 0	3, 4	or incr. RS422	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (Isolate	unused	wires i	ndividua	ılly befo	re initia	l start-u	ıp)						
6	1, 2, E	SinCos o. incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	Α	Ā	В	B	0 Vsens	+Vsens	Ŧ
0	1, 2, E	sensor output	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	ВК	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connecto	r												
6	3, 4	SinCos o. incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	Α	Ā	В	B	0 Vsens	+Vsens	Ť
U	3, 4	sensor output	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	M12 connector													
1 2	5.6	SET DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR		Ť			
1, 2 5, 6	5, 6 SEI, DIK -	Pin:	1	2	3	4	5	6	7	8		PH				

+V: Encoder power supply +V DC

0 V: Encoder power supply ground GND (0 V)

0 V_{sens} / + V_{sens} : Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.

C+, C-: Clock signal D+, D-: Data signal

 $\begin{array}{ll} A,\,\overline{A} \colon & \text{Incremental output channel A (cosine)} \\ B,\,\overline{B} \colon & \text{Incremental output channel B (sine)} \end{array}$

SET: Set input. The current position becomes defined as position zero.

DIR: Direction input: If this input is active, output values are counted

backwards (decrease) when the shaft is turning clockwise.

Stat: Status output

PH \pm : Plug connector housing (Shield)

Top view of mating side, male contact base





M12 connector, 8-pin

M23 connector, 12-pin



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Dimensions shaft version

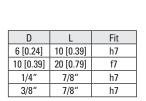
Dimensions in mm [inch]

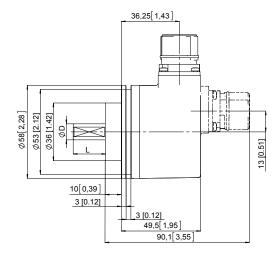
Clamping flange, ø 58 [2.28] Flange type 1 and 3

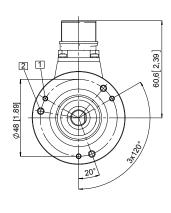
(Drawing with M23 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep







Synchro flange, ø 58 [2.28] Flange type 2 and 4

(Drawing with M12 connector)

Fit

h7

f7

h7

h7

1 M4, 6 [0.24] deep

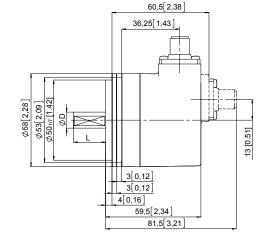
D

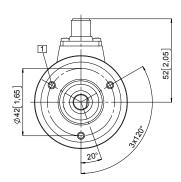
6 [0.24]

10 [0.39]

1/4"

3/8"





10 [0.39]

20 [0.79]

7/8"

7/8"



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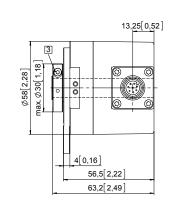
Dimensions hollow shaft version

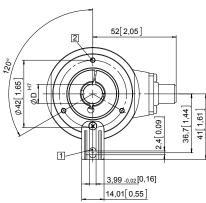
Dimensions in mm [inch]

Flange with spring element long Flange type 1 and 2

(drawing with M12 connector)

- 1 Torque stop slot, Recommendation: Cylindrical pin DIN 7, ø 4 [0.16]
- 2 M3, 6 [0.24] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

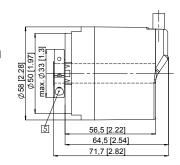


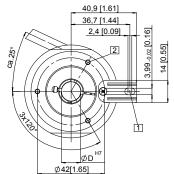


Flange with spring element long Flange type 1 and 2

(drawing with tangential cable)

- 1 Torque stop slot, Recommendation: Cylindrical pin DIN 7, Ø 4 [0.16]
- 2 M3, 5.5 [0.21] deep
- 3 Status-LED
- 4 SET button
- 5 Recommended torque for the clamping ring 0.6 Nm

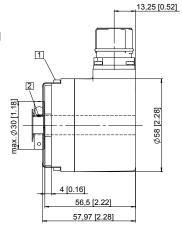


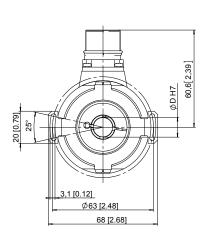


Flange with stator coupling, ø 63 [2.48] Flange type 5 and 6

Pitch circle diameter for fixing screws 63 mm [2.48] (Drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8 (Washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm





Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4 $\,$

Pitch circle diameter for fixing screws 65 [2.56] (Drawing with cable)

1 Recommended torque for the clamping ring 0.6 Nm

