

Bearingless encoders

Incremental, standard zero pulse, magnetic

RLI50 (hollow shaft)

Push-pull / RS422



Thanks to its installation depth of only 16 mm, the bearingless magnetic rotary encoder RLI50, comprising a magnetic ring and sensor head, is ideally suited for plants and machinery where space is very tight. The non-contact measuring principle allows for error-free use even under harsh environmental conditions, as well as ensuring a long service life. In contrast to our measuring system RLI20, a single zero pulse is also implemented here.

IP68 / IP69k protection, special encapsulation technology and tested resistance to cyclic humidity and damp heat offer the highest levels of reliability, even in exposed outdoor use.

This bearingless encoder can be mounted on shafts with a diameter up to max. 35 mm.









High rotational High speed

High protection level

Shock / vibration

Reverse polarity protection

Hard-wearing and robust

- · High shock and vibration resistance.
- Sturdy housing with IP67 protection. Option: special housing for maximum resistance against condensation (IP68 / IP69k, resistance to cyclic humidity acc. to EN 60068-3-38 as well as damp heat acc. to EN 60068-3-78).
- Non-contact measuring system, free from wear, ensures a long service life.

Fast start-up

- Function display via LED.
- Large mounting tolerance between magnetic band and sensor head.
- Requires very little installation space.
- · Slotted hole fixing ensures simple alignment.

Order code RLI50



1 = IP67, standard

2 = IP68 / IP69k and humidity tested acc. to EN 60068-3-38, EN 60068-3-78

b Output circuit / Power supply

1 = RS422 / 4.8 ... 26 V DC

2 = Push-pull / 4.8 ... 30 V DC

C Type of connection

1 = radial cable, 2 m [6.56'] PUR

A = radial cable, special length PUR *)

*) Available special lengths (connection type A): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.RLI50.111A.2000.0080.0030 (for cable length 3 m)

Pulses per revolution 1) 1000, 1024, 2000, 2048, 3600 Bore diameter

0060 = 6 mm [0.24"] 0158 = 5/8"

 $0254 = 1"^{2}$

0080 = 8 mm [0.32"]

0100 = 10 mm [0.39"]

0120 = 12 mm [0.47"]

0150 = 15 mm [0.59"]

0200 = 20 mm [0.79"]

0250 = 25 mm [0.98"] ²⁾

0300 = 30 mm [1.18"] ²⁾

 $0350 = 35 \text{ mm} [1.34"]^{3}$

1) Other pulse rates on request.

Only possible for pulse rates 1024, 2048 and 3600.

3) Only possible for pulse rate 3600.



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Accessories / Display type 572		Order no.
Position display, 6-digit	with 4 fast switch outputs and serial interface with 4 fast switch outputs and serial interface and scalable analog output	6.572.0116.D05 6.572.0116.D95
Position display, 8-digit	with 4 fast switch outputs and serial interface	6.572.0118.D05
	with 4 fast switch outputs and serial interface and scalable analog output	6.572.0118.D95

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology

Technical data

Mechanical characteristics						
Maximum speed		12000 min ⁻¹				
	nodel 1 nodel 2	IP67 acc. to EN 60529 IP68 / IP69k acc. to EN 60529, DIN 40050-9 and humidity tested acc. to EN 60068-3-38, EN 60068-3-78				
Working temperature		-20°C +80°C [-4°F +176°F]				
Shock resistance		5000 m/s ² , 1 ms				
Vibration resistan	ice	300 m/s², 10 2000 Hz				
Pole gap		5 mm from pole to pole				
Housing (sensor h	nead)	aluminum				
Cable		2 m [6.56'] long, PUR 8 x 0.14 mm ² [AWG 26], shielded, may be used in trailing cable installations				
Status LED	green red	pulse index error; speed too high or magnetic fields too weak				
CE compliant acc. to		EMC guideline 2014/30/EU RoHS guideline 2011/65/EU				

Electrical charact	eristics	;						
Output circuit		RS422		Pusl	Push-pull			
Power supply		4.8 26 V DC		4.8	. 30 V DC			
Power consumption (no load)		typ. 25 max. 60			typ. 25 mA max. 60 mA			
Permissible load/chai	nel	120 oh	m	+/- 2	0 mA			
Min. pulse edge interv	/al	1 µs		1 µs	1 µs			
Signal level	HIGH LOW	min. 2.5 V max. 0.5 V			+V - 2.0 \ . 0.5 V	1		
Reference signal		1 x per revolution						
System accuracy		typ. 0.3° with shaft tolerance g6						
Pulse rate [ppr] 1)		1000	1024	2000	2048	3600		
max. speed min ⁻¹ without using zero pulse		9000	9000	4000	4000	2500		
max. spee using zer		3000	2000	3000	2000	1700		

Terminal assignment

Output circuit	Type of connection	Cable (isolate unused wires individually before initial start-up)								
1, 2 1, A	Signal:	0 V	+V	Α	Ā	В	B	0	ō	Ŧ
	Cable color:	WH	BN	GN	YE	GY	PK	BU	RD	shield ²⁾

Encoder power supply +V DC +V:

0 V: Encoder power supply ground GND (0 V) A, $\overline{\mathsf{A}}$: Incremental output channel A / sine signal B, <u>B</u>: Incremental output channel B / cosine signal

0, $\overline{0}$: Reference signal

Plug connector housing (shield)

With an input frequency of the evaluation unit of 250 kHz.
 Shield is attached to connector housing.



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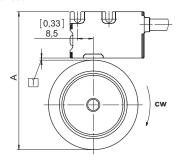
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Mounting orientation and permissible mounting tolerances

Distances



① Distance sensor head / magnetic ring: 0.1 ... 1.5 [0.004 ... 0.06] (1 [0.04] recommended)

Pulse rate	A for distance sensor head / magnetic ring = 1 [0.04]
1000, 2000	57.0 [2.24]
1024, 2048	74.3 [2.93]
3600	80.7 [3.18]

Torsion



Offset



Tilting

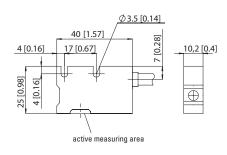


Warning: When mounting the sensor head, please ensure its correct orientation to the magnetic ring!

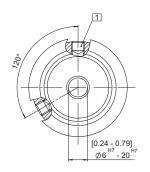
Dimensions

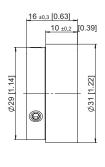
Dimensions in mm [inch]

Sensor head

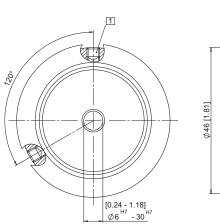


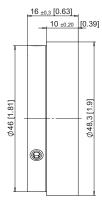
Magnetic ring for pulse rate 1000 or 2000



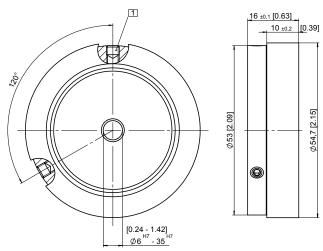


Magnetic ring for pulse rate 1024 or 2048





Magnetic ring for pulse rate 3600



1 M4 set screw