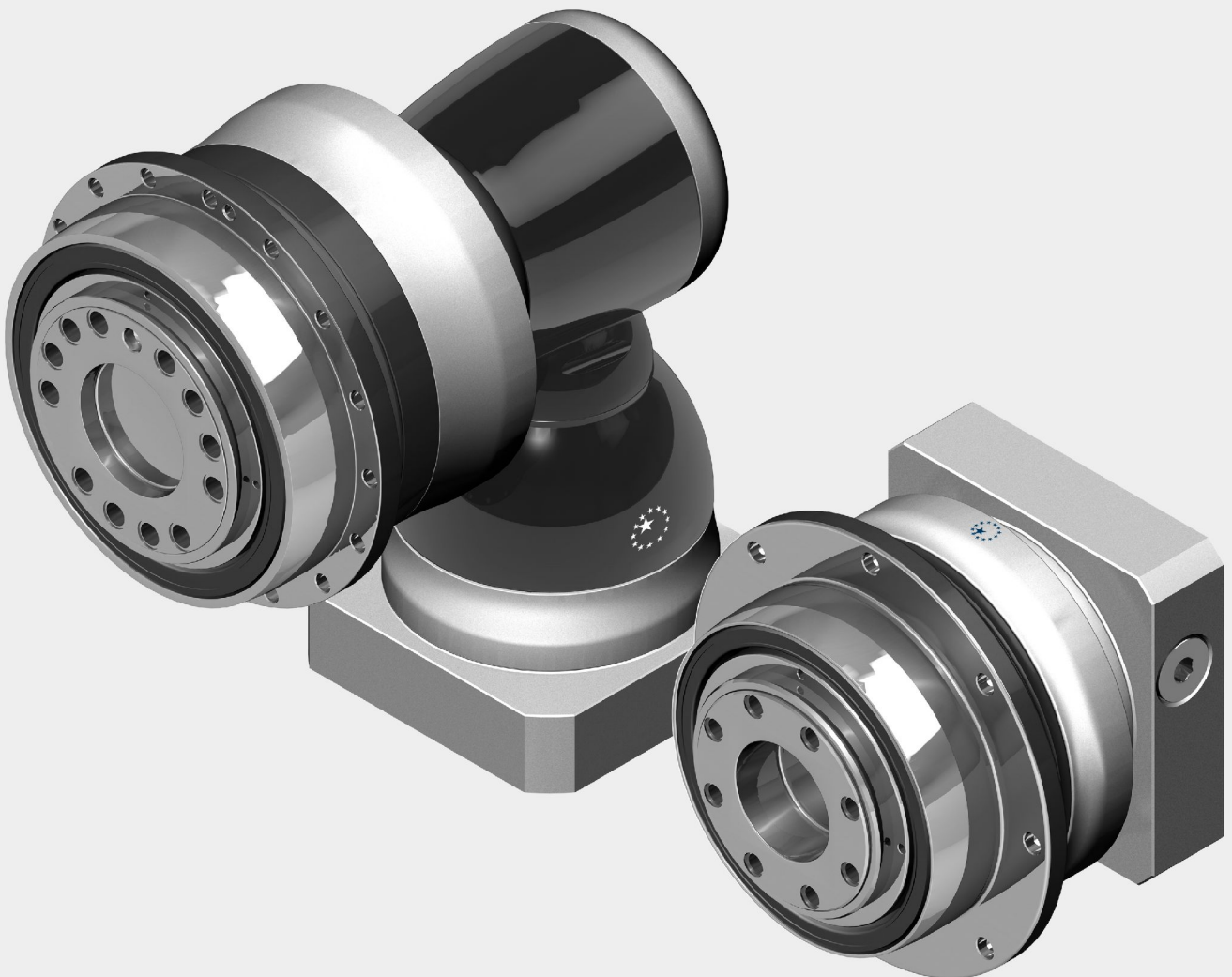# APEX DYNAMICS, INC.

NEW GENERATION PLANETARY GEARBOX

AH / AHK Series

Gearbox Series - AH / AHK

▶ Features:

High Torque

High efficiency

Long-Term persistence of reduced backlash
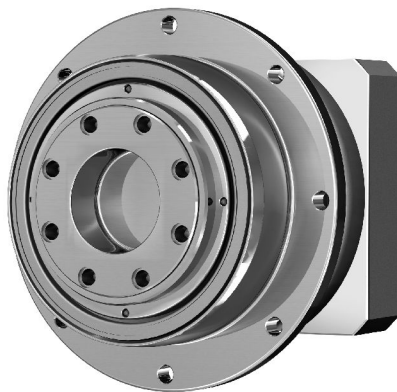
Low noise

Long service life

Limited temperature rise

Optimized output torque

Optimized Inertia moment

Flexible mounting diameters

Ordering Code - AH / AHK Gearbox

AH090	—	005[1]	/	MOTOR
AHK090	—	005[1]	/	MOTOR
AHKA285[3]				Motor Type
AHKB090[3]				Ratio
				Gearbox Size

Gearbox Size

AH   064 / 090 / 110 / 140 / 200 / 255 / 285 / 355 / 450
AHK   064 / 090 / 110 / 140 / 200 / 255 / 285 / 355 / 450

Ratio[2]

AH	4 / 5 / 7 / 10
	16 / 20 / 21 / 25 / 28 / 31 / 35 / 40 / 46 / 50 / 61 / 70 / 91 / 100
AHK (2 Stg.)	12 / 15 / 16 / 20 / 25 / 28 / 35 / 40 / 49 / 50 / 70 / 100
AHKA (3 Stg.)	100 / 125 / 140 / 175 / 200 / 250 / 350 / 500 / 700 / 1,000
AHKB (3 Stg.)	64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1,000
AHK (4 Stg.)	1,225 / 1,400 / 1,750 / 2,000 / 2,800 / 3,500 / 5,000 / 7,000 / 10,000
AHKC	4 / 5 / 7 / 8 / 10 / 21 / 31 / 46 / 61 / 91

Motor Type
Manufacturer and Model

(1) Ratio (i= N_{in} / N_{out}) .
(2) Please refer to the specifications for the ratios provided in each series.
(3) Please refer to page 06.

Performance - AH Gearbox

Model No.		Stage	Ratio[1]	AH064	AH090	AH110	AH140	AH200	AH255	AH285	AH355	AH450
Nominal Output Torque T_{2N}	Nm	1	4	95	195	350	600	1,290	–	–	–	–
			5	80	165	305	525	1,145	1,745	3,285	–	–
			7	60	130	250	435	980	1,495	2,525	–	–
			10	24	55	160	305	700	1,070	1,810	–	–
		2	16	95	195	360	615	1,320	–	–	–	–
			20	95	200	360	615	1,320	1,770	3,325	–	–
			21	80	165	310	535	1,165	1,770	3,330	5,595	10,915
			25	80	165	310	535	1,165	1,770	3,330	–	–
			28	60	200	360	615	1,325	–	–	–	–
			31	60	130	250	440	990	1,510	2,550	4,810	9,565
			35	70	170	310	535	1,165	1,775	3,335	–	–
			40	40	96	220	615	1,215	–	–	–	–
			46	24	55	160	295	660	1,005	1,700	3,400	7,125
			50	50	120	275	535	1,170	1,775	3,340	–	–
			61	60	130	250	440	990	1,510	2,550	4,820	9,585
			70	60	130	250	440	990	1,510	2,550	–	–
			91	24	55	160	295	660	1,005	1,700	3,345	7,000
			100	24	55	160	295	660	1,005	1,700	–	–
Emergency Stop Torque T_{2NOT}	Nm	1,2	4~100	3 times T_{2N}								
Max. Acceleration Torque T_{2B}	Nm	1,2	4~100	1.5 times T_{2N}								
No Load Running Torque[3]	Nm	1	4~10	0.45	0.7	1.4	3.5	7	11	14	–	–
		2	16~100	0.2	0.3	0.6	1.3	2.2	3.5	4.5	13	21
Backlash[2]	arcmin	1	4~10	$\leqq 2$	$\leqq 1$	$\leqq 1$	$\leqq 1$	$\leqq 1$	$\leqq 1$	$\leqq 1$	–	–
		2	16~100	$\leqq 3$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$
Torsional Rigidity	Nm/arcmin	1,2	4~100	8	22	60	115	395	650	1,050	2,850	5,700
Nominal Input Speed n_{IN}	rpm	1	4~10	5,000	3,600	3,600	3,000	2,700	2,400	2,100	–	–
		2	16~100	5,000	4,600	4,600	4,000	3,700	3,400	3,100	2,500	2,000
Max. Input Speed n_{1B}	rpm	1	4~10	7,000	6,000	6,000	5,000	4,500	4,000	3,500	–	–
		2	16~100	7,000	7,000	7,000	6,000	5,500	5,000	4,500	4,000	3,500
Max. Axial Load F_{2a}[4]	N	1,2	4~100	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500	143,700
Max. Tilting Moment M_{2K}[4]	Nm	1,2	4~100	120	280	480	1,310	3,530	5,920	9,230	29,100	63,300
Operating Temp	°C	1,2	4~100	-10° C~ 90° C								
Degree of Gearbox Protection		1,2	4~100	IP65								
Lubrication		1,2	4~100	Synthetic lubrication grease								
Mounting Position		1,2	4~100	All directions								
Running Noise[3]	dB(A)	1	4~10	$\leqq 58$	$\leqq 59$	$\leqq 64$	$\leqq 65$	$\leqq 66$	$\leqq 66$	$\leqq 66$	–	–
		2	16~100	$\leqq 58$	$\leqq 59$	$\leqq 60$	$\leqq 63$	$\leqq 66$	$\leqq 66$	$\leqq 66$	$\leqq 68$	$\leqq 70$
Efficiency η	%	1	4~10	$\geqq 97\%$								
		2	16~100	$\geqq 94\%$								

(1) Ratio ($i = N_{in} / N_{out}$) .

(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(3) The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM
    or at the respective Nominal Input Speed by bigger model size.
    By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

(4) Applied to the output flange center at 100 rpm.

(5) Continuous operation is not recommended.

Inertia - AH Gearbox

Model No.		AH064		AH090		AH110		AH140		AH200		AH255		AH285		AH355	AH450
$\varnothing^{(A)}$ (C3)		1-st.	2-st.	1-st.	2-st.	1-st.	2-st.	1-st.	2-st.	1-st.	2-st.	1-st.	2-st.	1-st.	2-st.	2-st.	2-st.
8	kg.cm^2	-	0.1	-	-	-	-	-	-	-	-	-	-	-	-	-	-
11		0.17	0.16	-	0.17	-	-	-	-	-	-	-	-	-	-	-	-
14		0.21	0.2	0.53	0.21	-	0.53	-	-	-	-	-	-	-	-	-	-
19		0.63	-	0.68	0.63	1.83	0.68	-	1.83	-	-	-	-	-	-	-	-
24		-	-	4.52	-	5.04	4.52	5.63	5.04	-	5.63	-	-	-	-	-	-
28		-	-	-	-	6.33	-	7.18	6.33	-	7.18	-	-	-	-	-	-
32		-	-	-	-	8.73	-	10.1	8.73	12.63	10.1	-	12.63	-	-	-	-
35		-	-	-	-	14.04	-	15.54	14.04	17.75	15.54	17.35	17.75	28.18	20.8	-	-
38		-	-	-	-	19.05	-	21.32	19.05	23.26	21.32	23.61	23.26	28.18	27.05	23.6	-
42		-	-	-	-	-	-	23.2	-	25.4	23.2	25.5	25.4	30.52	28.95	25.37	30.37
48		-	-	-	-	-	-	56.07	-	61.02	56.07	61.22	61.02	66.85	64.66	89.35	96.45
55		-	-	-	-	-	-	-	-	-	-	88.86	-	94.91	-	102	109.06
60		-	-	-	-	-	-	-	-	-	-	-	-	117.73	-	-	117.75

(A) $\varnothing$ = Input shaft diameter.

Flange Shaft - AH
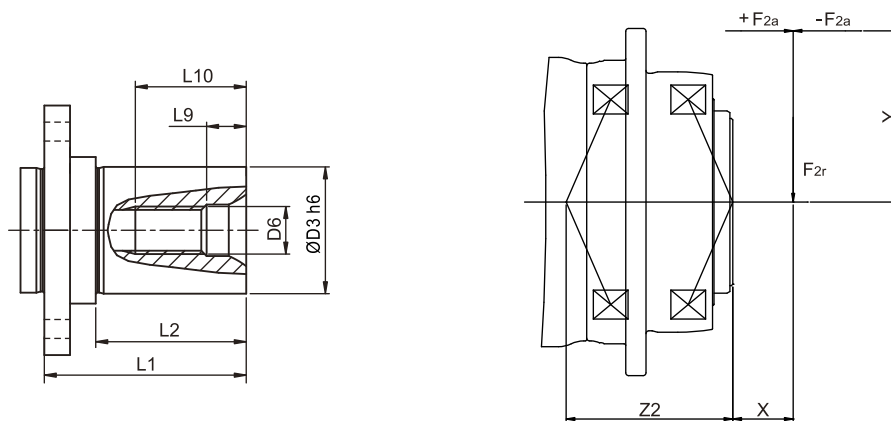
$$M_{2K} = \frac{F_{2a} * Y + F_{2r} * (X + Z2)}{1000}$$

M_{2K} :【Nm】

F_{2a}, F_{2r} :【N】

$X, Y, Z2$:【mm】

Dimension	L1	L2	D3 h6	D6	L9	L10	Order Code
AH064	33	23	16	M5	4.8	12.5	FLS-AH064-S16
			22	M8	7.2	19	FLS-AH064-S22
AH090	41	30	22	M8	7.2	19	FLS-AH090-S22
			32	M12	10	28	FLS-AH090-S32
AH110	51	38	32	M12	10	28	FLS-AH110-S32
			40	M16	12	36	FLS-AH110-S40
AH140	54	38	40	M16	12	36	FLS-AH140-S40
			55	M20	15	42	FLS-AH140-S55
AH200	73	52	55	M20	15	42	FLS-AH200-S55
			75	M20	15	42	FLS-AH200-S75
AH255	150	123	90	M24	18	50	FLS-AH255-S90

Note: Dimensions are related to gearbox flange interface.

M2K

AH / AHK	064	090	110	140	200	255	285	355	450
Z2【mm】	63.7	84.5	106.2	90	122.8	133.2	175.5	220.6	275.3

Note : Applied to the output flange center at 100 rpm

Dimension AH Gearbox

AH 064   AH 090   AH 110   AH 140

AH 200   AH 255   AH 285   AH 355   AH 450
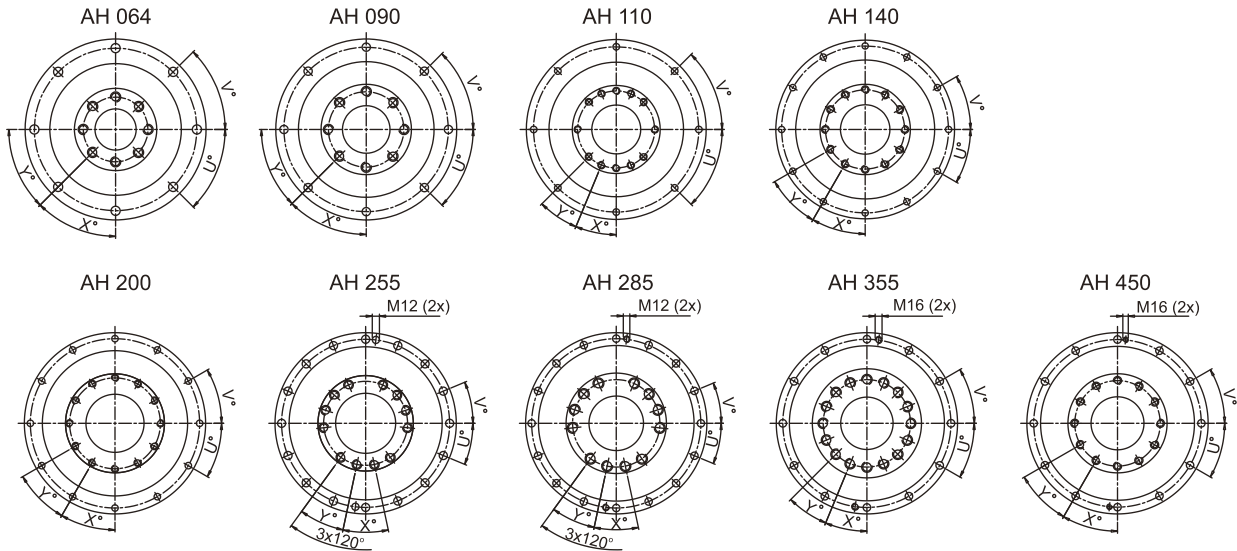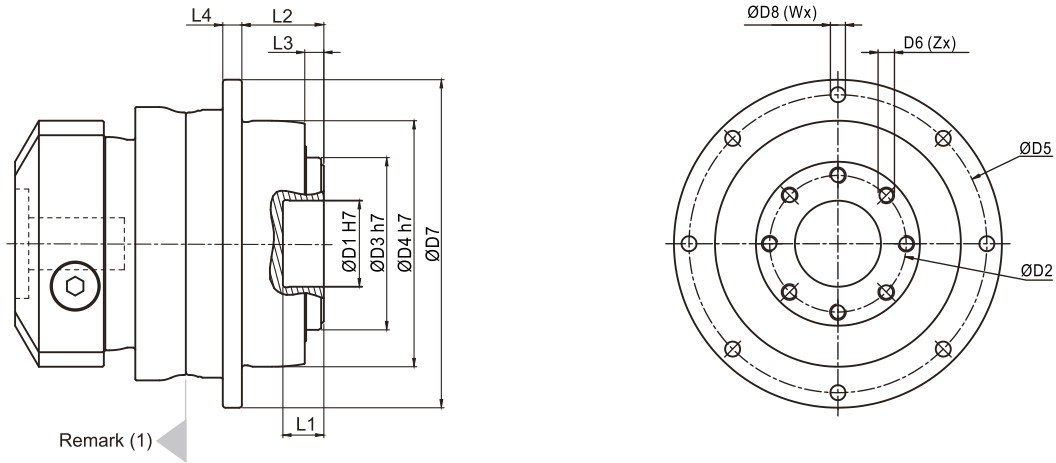
Dimension		AH064	AH090	AH110	AH140	AH200	AH255	AH285	AH355	AH450
D1	H7	20	31.5	40	50	80	100	100	120	155
D2		31.5	50	63	80	125	140	160	200	250
D3	h7	40	63	80	100	160	180	200	250	315
D4	h7	64	90	110	140	200	255	285	355	450
D5		79	109	135	168	233	280	310	385	490
D6 x Pitch x Deep		M5x0.8Px8	M6x1Px10	M6x1Px11	M8x1.25Px15	M10x1.5Px20	M16x2Px25	M20x2.5Px31	M24x3Px32	M30x3.5Px40
D7		88	120	147	180	249.5	302	332	415	530
D8		4.5	5.5	5.5	6.6	9	13.5	13.5	17.5	22
L1		8	15	15	15	16	16	16	35	24
L2		19.5	30	29	38	50	66	75	80	85
L3		4	7	7	7.5	8.5	13.5	16.5	20	20
L4		5	7	8	10	12	18	20	45	60
X in Degree		45	45	22.5	30	30	24	24	22.5	30
Y in Degree		45	45	22.5	30	30	24	24	22.5	30
Z		8	8	12	12	12	12	12	16	12
U in Degree		45	45	45	30	30	22.5	22.5	30	30
V in Degree		45	45	45	30	30	22.5	22.5	30	30
W		8	8	8	12	12	16	16	12	12

Note: Dimensions are related to motor interface. Please contact APEX for details.

AHK Gearbox

AHK Structure

(I)

AH

K

AHK
2 Stage

(II)

K

AHKA
3 Stage

(III)

K

AHKB
3 Stage

(IV)

K

AHK
4 Stage
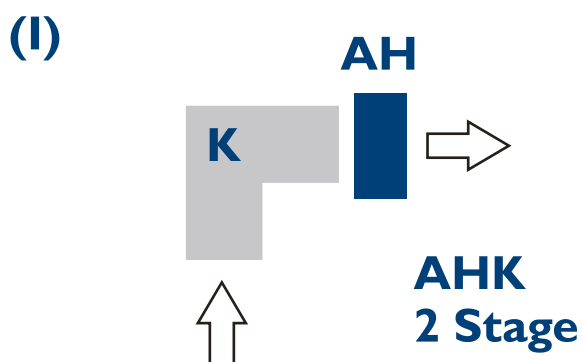
Performance - AHK (2 Stage) Gearbox

Model No.		Stage	Ratio[1]	AHK064	AHK090	AHK110	AHK140	AHK200	AHK255	AHK285	AHK355
Nominal Output Torque T_{2N}	Nm	2	12	95	195	360	615	1,315	–	–	–
			15	–	–	–	–	–	1,770	3,330	5,595
			16	95	200	360	615	1,320	–	–	–
			20	95	200	360	615	1,320	1,775	3,335	5,605
			25	80	170	310	535	1,165	1,775	3,335	5,610
			28	92	200	360	615	1,325	–	–	–
			35	80	170	310	535	1,170	1,775	3,340	5,615
			40	60	160	340	615	1,325	–	–	–
			49	60	130	250	440	990	1,510	2,550	4,820
			50	50	170	310	535	1,170	1,775	3,000	5,500
			70	60	130	250	440	990	1,510	2,550	4,820
			100	24	55	160	290	655	1,005	1,685	3,315
Emergency Stop Torque T_{2NOT}	Nm	2	12~100	2 times T_{2N}							
Max. Acceleration Torque T_{2B}	Nm	2	12~100	1.5 times T_{2N}							
No Load Running Torque[3]	Nm	2	12~100	1	1.3	2	3.1	6	13	16	20
Backlash[2]	arcmin	2	12~100	≦ 3	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2
Torsional Rigidity	Nm/arcmin	2	12~100	12	27	56	112	389	642	1,275	2,500
Nominal Input Speed n_{IN}	rpm	2	12~100	3,000	3,000	2,800	2,700	2,200	2,100	2,000	1,600
Max. Input Speed n_{IB}	rpm	2	12~100	6,000	6,000	6,000	4,500	4,500	4,000	3,000	2,500
Max. Axial Load F_{2a}[4]	N	2	12~100	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500
Max. Tilting Moment M_{2K}[4]	Nm	2	12~100	120	280	480	1,310	3,530	5,920	9,230	29,100
Operating Temp	° C	2	12~100	-10° C~ 90° C							
Degree of Gearbox Protection		2	12~100	IP65							
Lubrication		2	12~100	Synthetic lubrication grease							
Mounting Position		2	12~100	All directions							
Running Noise[3]	dB(A)	2	12~100	≦ 64	≦ 66	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74
Efficiency η	%	2	12~100	≧ 94%							

(1) Ratio (i = N_{in} / N_{out}) .

(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(3) The dB values are measured by gearbox with ratio 100 (2-stage), no loading at 3,000 RPM
   or at the respective Nominal Input Speed by bigger model size.
   By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

(4) Applied to the output flange center at 100 rpm.

(5) Continuous operation is not recommended.

Inertia - AHK (2 Stage) Gearbox

Model No. / Input Shaft (C3) ∅[A]		AHK064	AHK090	AHK110	AHK140	AHK200	AHK255	AHK285	AHK355
8		0.1	–	–	–	–	–	–	–
11		0.17	0.18	–	–	–	–	–	–
14		0.21	0.5	0.52	–	–	–	–	–
19		–	0.65	1.69	1.71	–	–	–	–
24		–	–	4.89	5.05	6.92	–	–	–
28		–	–	–	6.55	6.98	–	–	–
32	kg.cm²	–	–	–	9.47	10.18	10.18	–	–
35		–	–	–	14.91	15.21	15.21	15.68	–
38		–	–	–	20.69	20.7	20.7	21.69	23.46
42		–	–	–	–	22.83	22.83	23.59	25.28
48		–	–	–	–	58.45	58.45	59.3	61.61
55		–	–	–	–	–	–	–	89.67

(A) ∅ = Input shaft diameter.

Dimension AHK (2 Stage) Gearbox （Ratio i＝12~100）

Remark (1)

Remark (2)
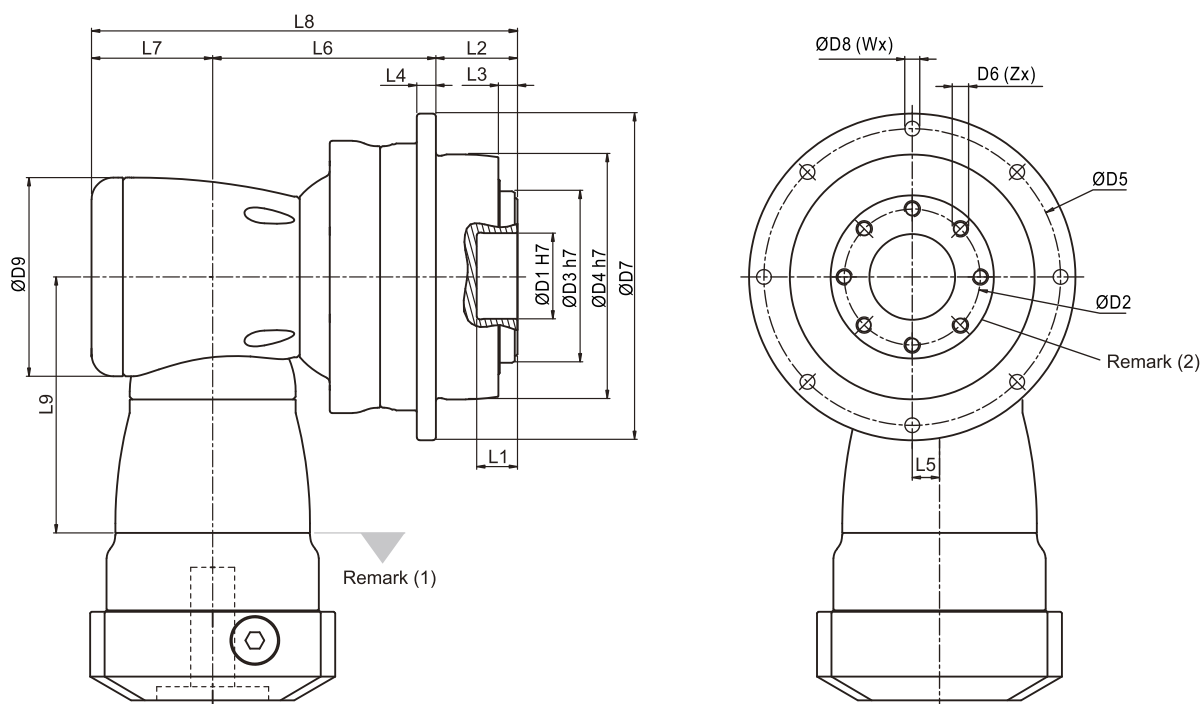
Dimension		AHK064	AHK090	AHK110	AHK140	AHK200	AHK255	AHK285	AHK355
D1	H7	20	31.5	40	50	80	100	100	120
D2		31.5	50	63	80	125	140	160	200
D3	h7	40	63	80	100	160	180	200	250
D4	h7	64	90	110	140	200	255	285	355
D5		79	109	135	168	233	280	310	385
D6 x Pitch x Deep		M5x0.8Px8	M6x1Px10	M6x1Px11	M8x1.25Px15	M10x1.5Px20	M16x2Px25	M20x2.5Px31	M24x3Px32
D7		88	120	147	180	249.5	302	332	415
D8		4.5	5.5	5.5	6.6	9	13.5	13.5	17.5
D9		73	94	116	163	210	210	255	300
L1		8	15	15	15	16	16	16	35
L2		19.5	30	29	38	50	66	75	80
L3		4	7	7	7.5	8.5	13.5	16.5	20
L4		5	7	8	10	12	18	20	45
L5		10	13	17	25	31	31	36	43
L6		87	90.5	114	147.5	175	191.5	249.5	290
L7		44.5	53	68.3	89	115	115	131	165
L8		151	173.5	211.3	274.5	340	372.5	455.5	535
L9		94	114.5	129	173.5	228	228	265.5	294.5
X in Degree		45	45	22.5	30	30	24	24	22.5
Y in Degree		45	45	22.5	30	30	24	24	22.5
Z		8	8	12	12	12	12	12	16
U in Degree		45	45	45	30	30	22.5	22.5	30
V in Degree		45	45	45	30	30	22.5	22.5	30
W		8	8	8	12	12	16	16	12

(1) Dimensions are related to motor interface. Please contact APEX for details.
(2) Refer to the AH series(Page 05) for flange interface.

Performance - AHKA（3 Stage）Gearbox

Model No.		Stage	Ratio[1]	AHKA285	AHKA355	AHKA450
Nominal Output Torque T_{2N}	Nm	3	100	3,345	5,620	10,965
			125	3,345	5,625	10,970
			140	3,345	5,625	10,970
			175	3,345	5,625	10,970
			200	3,345	5,625	10,975
			250	3,345	5,625	10,975
			350	3,345	5,630	10,975
			500	3,345	5,350	9,050
			700	2,555	4,825	9,600
			1,000	1,650	3,250	6,785
Emergency Stop Torque T_{2NOT}	Nm	3	100~1,000	2 times T_{2N}		
Max. Acceleration Torque T_{2B}	Nm	3	100~1,000	1.5 times T_{2N}		
No Load Running Torque[3]	Nm	3	100~1,000	6	6	13
Backlash[2]	arcmin	3	100~1,000	$\leqq 2$	$\leqq 2$	$\leqq 2$
Torsional Rigidity	Nm/arcmin	3	100~1,000	1,275	2,500	5,100
Nominal Input Speed n_{IN}	rpm	3	100~1,000	2,100	2,100	2,000
Max. Input Speed n_{IB}	rpm	3	100~1,000	4,000	4,000	3,000
Max. Axial Load F_{2a}[4]	N	3	100~1,000	39,200	101,500	143,700
Max. Tilting Moment M_{2K}[4]	Nm	3	100~1,000	9,230	29,100	63,300
Operating Temp	°C	3	100~1,000	-10°C~ 90°C		
Degree of Gearbox Protection		3	100~1,000	IP65		
Lubrication		3	100~1,000	Synthetic lubrication grease		
Mounting Position		3	100~1,000	All directions		
Running Noise[3]	dB(A)	3	100~1,000	$\leqq 72$	$\leqq 74$	$\leqq 76$
Efficiency η	%	3	100~1,000	$\geqq 92\%$		

(1) Ratio ($i = N_{in} / N_{out}$) .

(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(3) The dB values are measured by gearbox with ratio 1,000 (3-stage), no loading at 3,000 RPM
    or at the respective Nominal Input Speed by bigger model size.
    By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

(4) Applied to the output flange center at 100 rpm.

(5) Continuous operation is not recommended.

Inertia - AHKA（3 Stage）Gearbox

Input Shaft (C3) Ø[A] / Model No.		AHKA285	AHKA355	AHKA450
32	kg.cm²	10.18	10.18	–
35		15.21	15.21	15.68
38		20.7	20.7	21.69
42		22.83	22.83	23.59
48		58.45	58.45	59.3
55		–	–	86.95

(A) Ø = Input shaft diameter.

Dimension AHKA（3 Stage）Gearbox （Ratio i＝100~1,000）

Remark (1)

ØD8 (Wx) D6 (Zx) ØD5 Remark (2) ØD2 L5
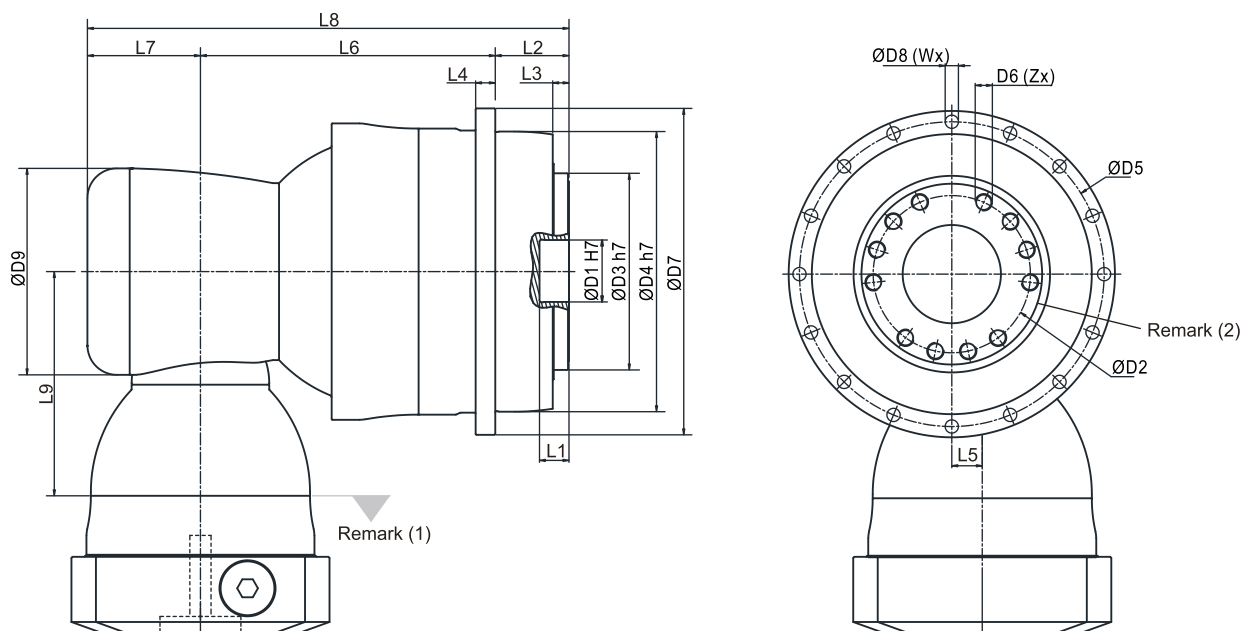
Dimension		AHKA285	AHKA355	AHKA450
D1	H7	100	120	155
D2		160	200	250
D3	h7	200	250	315
D4	h7	285	355	450
D5		310	385	490
D6 x Pitch x Deep		M20x2.5Px31	M24x3Px32	M30x3.5Px40
D7		332	415	530
D8		13.5	17.5	22
D9		210	210	255
L1		16	35	24
L2		75	80	85
L3		16.5	20	20
L4		20	45	60
L5		31	31	36
L6		300	332	447.5
L7		115	115	131
L8		490	527	663.5
L9		228	228	265.5
X in Degree		24	22.5	30
Y in Degree		24	22.5	30
Z		12	16	12
U in Degree		22.5	30	30
V in Degree		22.5	30	30
W		16	12	12

(1) Dimensions are related to motor interface. Please contact APEX for details.
(2) Refer to the AH series(Page 05) for flange interface.

Performance - AHKB (3 Stage) Gearbox

Model No.		Stage	Ratio[1]	AHKB090	AHKB110	AHKB140	AHKB200	AHKB255	AHKB285	AHKB355
Nominal Output Torque T_{2N}	Nm	3	64	200	360	615	1,325	-	-	-
			84	200	360	620	1,325	-	-	-
			100	200	360	620	1,330	1,780	3,345	5,620
			125	170	310	535	1,170	1,780	3,345	5,625
			140	200	360	620	1,330	1,780	3,345	5,625
			175	170	310	535	1,170	1,780	3,345	5,625
			200	200	360	620	1,330	1,780	3,345	5,625
			250	170	310	535	1,170	1,780	3,345	5,625
			280	200	360	620	1,330	1,510	-	-
			350	170	310	535	1,170	1,775	3,345	5,630
			400	160	340	620	1,330	-	-	-
			500	170	310	535	1,170	1,780	3,000	5,500
			700	130	250	440	990	1,510	2,555	4,825
			1,000	55	160	290	640	980	1,655	3,250
Emergency Stop Torque T_{2NOT}	Nm	3	64~1,000	2 times T_{2N}						
Max. Acceleration Torque T_{2B}	Nm	3	64~1,000	1.5 times T_{2N}						
No Load Running Torque[3]	Nm	3	64~1,000	0.2	0.2	0.3	0.4	1	1.2	1.5
Backlash[2]	arcmin	3	64~1,000	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2
Torsional Rigidity	Nm/arcmin	3	64~1,000	27	56	112	389	642	1,275	2,500
Nominal Input Speed n_{1N}	rpm	3	64~1,000	5,500	4,600	4,600	4,000	3,700	3,400	3,100
Max. Input Speed n_{1B}	rpm	3	64~1,000	7,000	7,000	7,000	6,000	5,500	5,000	4,500
Max. Axial Load F_{2a}[4]	N	3	64~1,000	2,220	4,070	8,530	17,000	26,900	39,200	101,500
Max. Tilting Moment M_{2K}[4]	Nm	3	64~1,000	280	480	1,310	3,530	5,920	9,230	29,100
Operating Temp	° C	3	64~1,000	-10° C~ 90° C						
Degree of Gearbox Protection		3	64~1,000	IP65						
Lubrication		3	64~1,000	Synthetic lubrication grease						
Mounting Position		3	64~1,000	All directions						
Running Noise[3]	dB(A)	3	64~1,000	≦ 66	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74
Efficiency η	%	3	64~1,000	≧ 92%						

(1) Ratio (i = N_{in} / N_{out}) .

(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(3) The dB values are measured by gearbox with ratio 1,000 (3-stage), no loading at 3,000 RPM

    or at the respective Nominal Input Speed by bigger model size.

    By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

(4) Applied to the output flange center at 100 rpm.

(5) Continuous operation is not recommended.

Inertia - AHKB (3 Stage) Gearbox

Model No. Input Shaft (C3) Ø[A]		AHKB090	AHKB110	AHKB140	AHKB200	AHKB255	AHKB285	AHKB355
8	kg.cm²	0.17	-	-	-	-	-	-
11		0.17	0.52	-	-	-	-	-
14		0.21	0.53	1.83	-	-	-	-
19		-	0.68	1.83	5.6	-	-	-
24		-	-	5.04	5.63	5.63	-	-
28		-	-	-	7.18	7.18	-	-
32		-	-	-	10.1	10.1	12.63	-
35		-	-	-	15.54	15.54	17.75	17.35
38		-	-	-	21.32	21.32	23.26	23.61
42		-	-	-	-	23.2	25.4	25.5
48		-	-	-	-	56.07	61.02	61.22

(A) Ø = Input shaft diameter.

Dimension AHKB（3 Stage）Gearbox （Ratio i＝64~1,000）

Remark (1)

Remark (2)
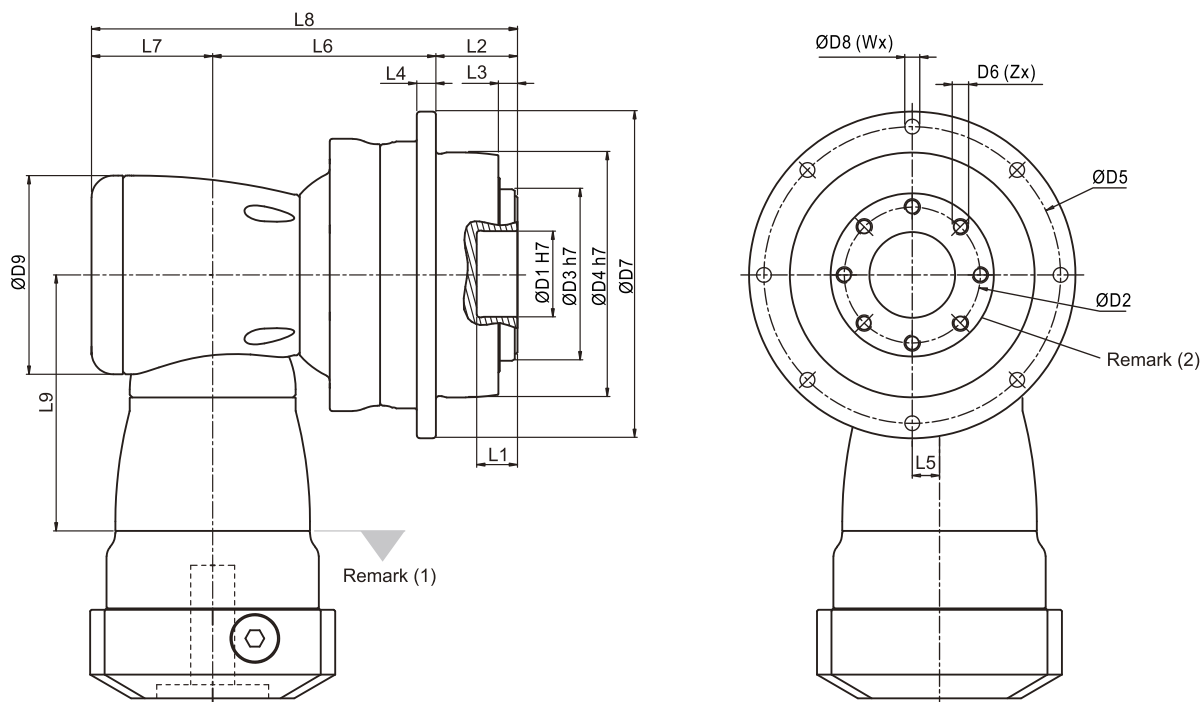
Dimension		AHKB090	AHKB110	AHKB140	AHKB200	AHKB255	AHKB285	AHKB355
D1	H7	31.5	40	50	80	100	100	120
D2		50	63	80	125	140	160	200
D3	h7	63	80	100	160	180	200	250
D4	h7	90	110	140	200	255	285	355
D5		109	135	168	233	280	310	385
D6 x Pitch x Deep		M6x1Px10	M6x1Px11	M8x1.25Px15	M10x1.5Px20	M16x2Px25	M20x2.5Px31	M24x3Px32
D7		120	147	180	249.5	302	332	415
D8		5.5	5.5	6.6	9	13.5	13.5	17.5
D9		94	116	163	210	210	255	300
L1		15	15	15	16	16	16	35
L2		30	29	38	50	66	75	80
L3		7	7	7.5	8.5	13.5	16.5	20
L4		7	8	10	12	18	20	45
L5		13	17	25	31	31	36	43
L6		90.5	114	147.5	175	191.5	249.5	290
L7		53	68.3	89	115	115	131	165
L8		173.5	211.3	274.5	340	372.5	455.5	535
L9		114.5	129	173.5	228	228	265.5	294.5
X in Degree		45	22.5	30	30	24	24	22.5
Y in Degree		45	22.5	30	30	24	24	22.5
Z		8	12	12	12	12	12	16
U in Degree		45	45	30	30	22.5	22.5	30
V in Degree		45	45	30	30	22.5	22.5	30
W		8	8	12	12	16	16	12

(1) Dimensions are related to motor interface. Please contact APEX for details.
(2) Refer to the AH series(Page 05) for flange interface.

Performance - AHK (4 Stage) Gearbox

Model No.		Stage	Ratio[1]	AHK285	AHK355	AHK450
Nominal Output Torque T_{2N}	Nm	4	1,225	3,350	5,630	10,980
			1,400	3,350	5,630	10,980
			1,750	3,350	5,630	10,980
			2,000	3,350	5,630	10,980
			2,800	2,555	4,825	9,600
			3,500	3,350	5,630	10,980
			5,000	3,350	5,350	9,050
			7,000	2,625	4,960	10,115
			10,000	1,975	3,870	8,325
Emergency Stop Torque T_{2NOT}	Nm	4	1,225~10,000	2 times T_{2N}		
Max. Acceleration Torque T_{2B}	Nm	4	1,225~10,000	1.5 times T_{2N}		
No Load Running Torque[3]	Nm	4	1,225~10,000	0.4	0.4	1
Backlash[2]	arcmin	4	1,225~10,000	≦ 2	≦ 2	≦ 2
Torsional Rigidity	Nm/arcmin	4	1,225~10,000	1,275	2,500	5,100
Nominal Input Speed n_{IN}	rpm	4	1,225~10,000	3,700	3,700	3,400
Max. Input Speed n_{IB}	rpm	4	1,225~10,000	5,500	5,500	5,000
Max. Axial Load F_{2a}[4]	N	4	1,225~10,000	39,200	101,500	143,700
Max. Tilting Moment M_{2K}[4]	Nm	4	1,225~10,000	9,230	29,100	63,300
Operating Temp	°C	4	1,225~10,000	-10° C~ 90° C		
Degree of Gearbox Protection		4	1,225~10,000	IP65		
Lubrication		4	1,225~10,000	Synthetic lubrication grease		
Mounting Position		4	1,225~10,000	All directions		
Running Noise[3]	dB(A)	4	1,225~10,000	≦ 72	≦ 74	≦ 76
Efficiency η	%	4	1,225~10,000	≧ 90%		

(1) Ratio ($i = N_{in} / N_{out}$) .

(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(3) The dB values are measured by gearbox with ratio 10,000 (4-stage), no loading at 3,000 RPM
   or at the respective Nominal Input Speed by bigger model size.
   By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

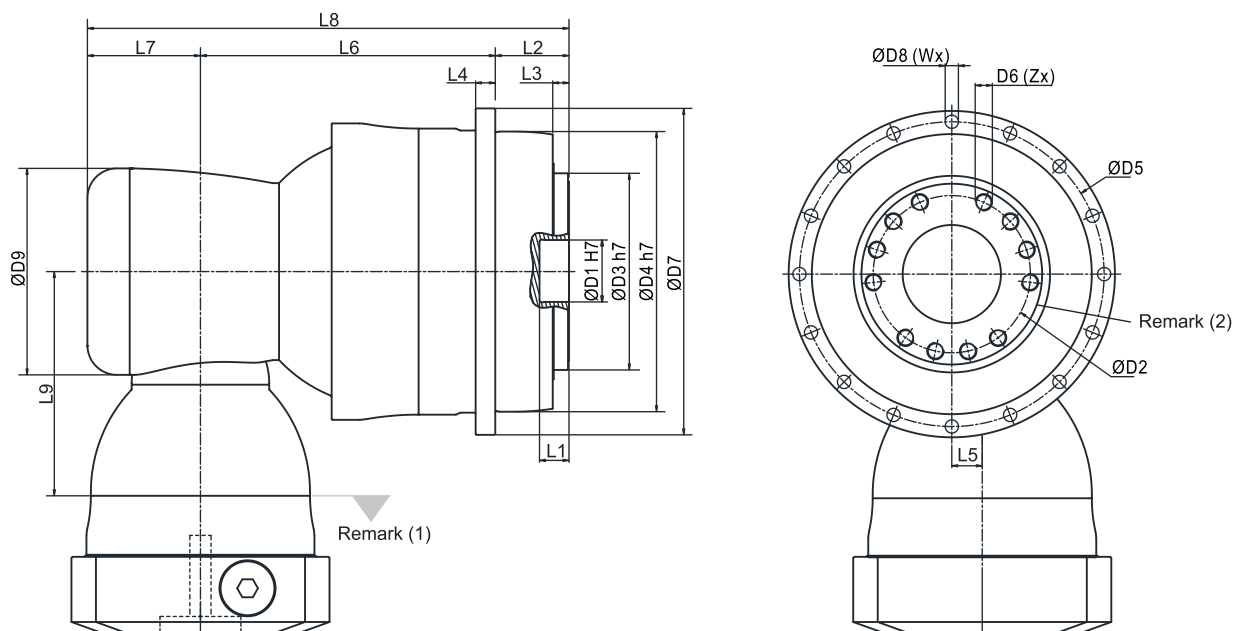(4) Applied to the output flange center at 100 rpm.

(5) Continuous operation is not recommended.

Inertia - AHK (4 Stage) Gearbox

Model No. / Input Shaft (C3) Ø[A]		AHK285	AHK355	AHK450
24	kg.cm²	5.63	5.63	-
28		7.18	7.18	-
32		10.1	10.1	12.63
35		15.54	15.54	17.75
38		21.32	21.32	23.26

(A) Ø = Input shaft diameter.

Dimension AHK（4 Stage）Gearbox（Ratio i＝1,225~10,000）

Remark (1)

ØD8 (Wx) D6 (Zx) ØD5 Remark (2) ØD2

Dimension		AHK285	AHK355	AHK450
D1	H7	100	120	155
D2		160	200	250
D3	h7	200	250	315
D4	h7	285	355	450
D5		310	385	490
D6 x Pitch x Deep		M20x2.5Px31	M24x3Px32	M30x3.5Px40
D7		332	415	530
D8		13.5	17.5	22
D9		210	210	255
L1		16	35	24
L2		75	80	85
L3		16.5	20	20
L4		20	45	60
L5		31	31	36
L6		300	332	447.5
L7		115	115	131
L8		490	527	663.5
L9		228	228	265.5
X in Degree		24	22.5	30
Y in Degree		24	22.5	30
Z		12	16	12
U in Degree		22.5	30	30
V in Degree		22.5	30	30
W		16	12	12

(1) Dimensions are related to motor interface. Please contact APEX for details.
(2) Refer to the AH series(Page 05) for flange interface.

Performance AHKC Gearbox

Model No.		Stage	Ratio[1]	AHKC064	AHKC090	AHKC110	AHKC140	AHKC200	AHKC255	AHKC285	AHKC355	AHKC450
Nominal Output Torque T_{2N}	Nm	2	4	95	195	355	605	1,300	–	–	–	–
			5	80	165	305	525	1,150	1,755	3,305	–	–
			7	60	130	250	440	985	1,500	2,535	–	–
			8	95	195	360	610	1,315	–	–	–	–
			10	80	165	310	530	1,160	1,765	3,325	–	–
		3	21	–	165	310	535	1,165	1,510	3,335	5,600	10,930
			31	–	130	250	440	990	1,775	2,550	4,815	9,580
			46	–	55	160	295	665	1,015	1,715	3,380	7,055
			61	–	130	250	440	990	1,775	2,550	4,820	9,590
			91	–	55	160	295	660	1,000	1,690	3,330	6,950
Emergency Stop Torque T_{2NOT}	Nm	2,3	4~91	2 times T_{2N}								
Max. Acceleration Torque T_{2B}	Nm	2,3	4~91	1.5 times T_{2N}								
No Load Running Torque[3]	Nm	2	4~10	2	2.5	5.8	12	25	48	95	–	–
		3	21~91	1	1.5	2.5	4	9	18.5	35	75	148
Backlash[2]	arcmin	2	4~10	$\leqq 3$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	–	–
		3	21~91	–	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$	$\leqq 2$
Torsional Rigidity	Nm/arcmin	2,3	4~91	12	27	56	112	389	642	1,275	2,500	5,100
Nominal Input Speed n_{IN}	rpm	2	4~10	5,000	3,600	3,000	2,300	1,800	1,500	1,100	–	–
		3	21~91	–	4,600	4,000	3,000	2,300	1,800	1,500	1,500	1,100
Max. Input Speed n_{IB}	rpm	2	4~10	7,000	6,000	5,500	4,500	3,500	3,000	2,200	–	–
		3	21~91	–	7,000	6,500	5,500	4,500	3,500	3,000	3,000	2,200
Max. Axial Load F_{2a}[4]	N	2,3	4~91	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500	143,700
Max. Tilting Moment M_{2K}[4]	Nm	2,3	4~91	120	280	480	1,310	3,530	5,920	9,230	29,100	63,300
Operating Temp	°C	2,3	4~91	-10°C~ 90°C								
Degree of Gearbox Protection		2,3	4~91	IP65								
Lubrication		2,3	4~91	Synthetic lubrication grease								
Mounting Position		2,3	4~91	All directions								
Running Noise[3]	dB(A)	2	4~10	$\leqq 68$	$\leqq 68$	$\leqq 68$	$\leqq 70$	$\leqq 70$	$\leqq 72$	$\leqq 74$	–	–
		3	21~91	–	$\leqq 68$	$\leqq 68$	$\leqq 70$	$\leqq 70$	$\leqq 72$	$\leqq 74$	$\leqq 74$	$\leqq 76$
Efficiency η	%	2	4~10	$\geqq 95\%$								
		3	21~91	$\geqq 93\%$								

(1) Ratio (i = N_{in} / N_{out}) .
(2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .
(3) The dB values are measured by gearbox with ratio 10 (2-stage) or ratio 91 (3-stage), no loading at 3,000 RPM
    or at the respective Nominal Input Speed by bigger model size.
    By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.
(4) Applied to the output flange center at 100 rpm.
(5) Continuous operation is not recommended.

Inertia AHKC Gearbox（Ratio i＝4~10 / 21~91）

Model No.		AHKC064	AHKC090		AHKC110		AHKC140		AHKC200		AHKC255		AHKC285		AHKC355	AHKC450
Ø[A] (C3)		2-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	3-st.	3-st.
8	kg.cm²	0.1	–	0.1	–	–	–	–	–	–	–	–	–	–	–	–
11		0.17	0.52	0.17	–	–	–	–	–	–	–	–	–	–	–	–
14		0.21	0.52	0.21	–	0.52	–	–	–	–	–	–	–	–	–	–
19		0.62	1.69	0.62	1.71	1.69	–	1.71	–	–	–	–	–	–	–	–
24		–	4.89	–	5.05	4.89	6.92	5.05	–	6.92	–	–	–	–	–	–
28		–	–	–	6.55	–	6.98	6.55	–	6.98	–	–	–	–	–	–
32		–	–	–	9.47	–	10.18	9.47	10.18	10.18	–	10.18	–	–	–	–
35		–	–	–	14.91	–	15.21	14.91	15.21	15.21	15.68	15.21	23.46	15.68	–	–
38		–	–	–	20.69	–	20.7	20.69	20.7	20.7	21.69	20.7	23.46	21.69	21.69	–
42		–	–	–	–	–	22.83	–	22.83	22.83	23.59	22.83	25.28	23.59	23.59	25.28
48		–	–	–	–	–	58.45	–	58.45	58.45	59.3	58.45	61.61	59.3	59.3	61.61
55		–	–	–	–	–	–	–	–	–	86.95	–	89.67	–	86.95	89.67
60		–	–	–	–	–	–	–	–	–	–	–	112.49	–	–	112.49

(A) Ø = Input shaft diameter.

Dimension AHKC Gearbox （Ratio i＝4~10 / 21~91）

Remark (1)

Remark (2)
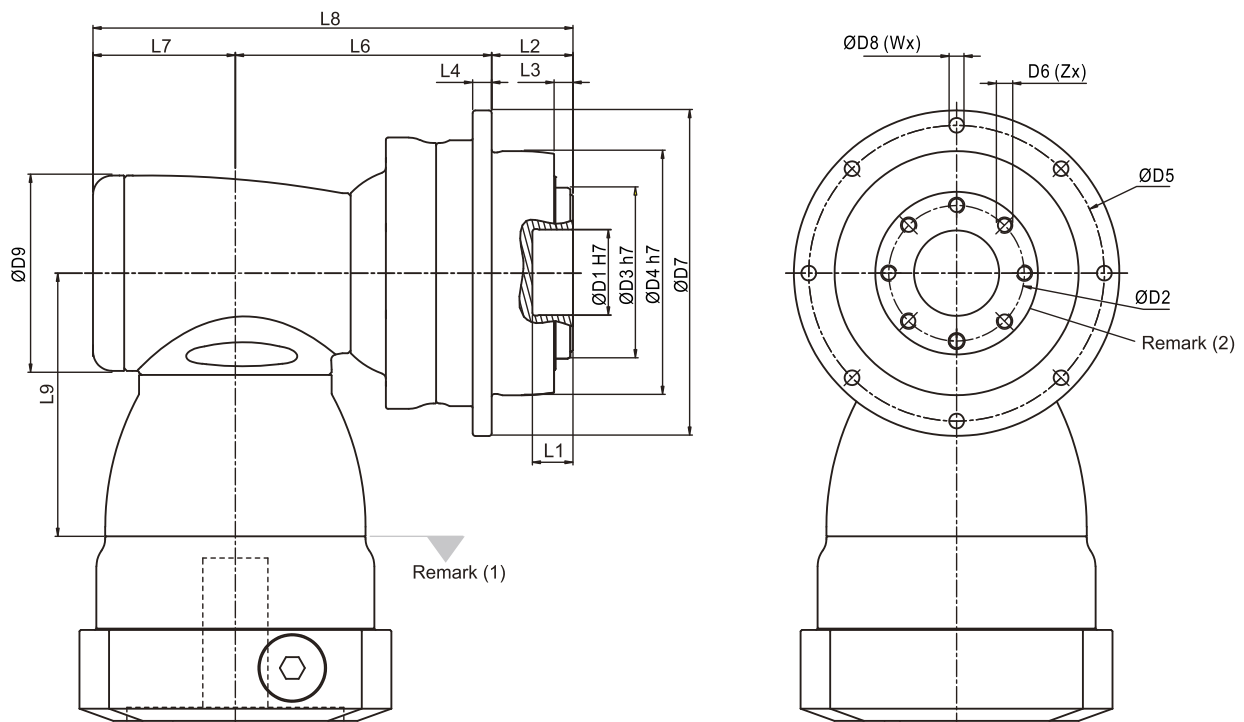
Dimension		AHKC064	AHKC090		AHKC110		AHKC140		AHKC200		AHKC255		AHKC285		AHKC355	AHKC450
		2-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	3-st.	3-st.
D1	H7	20	31.5		40		50		80		100		100		120	155
D2		31.5	50		63		80		125		140		160		200	250
D3	h7	40	63		80		100		160		180		200		250	315
D4	h7	64	90		110		140		200		255		285		355	450
D5		79	109		135		168		233		280		310		385	490
D6 x Pitch x Deep		M5x0.8Px8	M6x1Px10		M6x1Px11		M8x1.25Px15		M10x1.5Px20		M16x2Px25		M20x2.5Px31		M24x3Px32	M30x3.5Px40
D7		88	120		147		180		249.5		302		332		415	530
D8		4.5	5.5		5.5		6.6		9		13.5		13.5		17.5	22
D9		64	92	64	116	92	156	116	156	156	195	156	240	195	195	240
L1		8	15		15		15		16		16		16		35	24
L2		19.5	30		29		38		50		66		75		80	85
L3		4	7		7		7.5		8.5		13.5		16.5		20	20
L4		5	7		8		10		12		18		20		45	60
L6		92	100.5	121.5	124.5	142	175.5	174.5	185	244.5	199	264.5	265.5	307.5	339.5	463.5
L7		46.5	61.5	46.5	76	61.5	97.5	76	97.5	97.5	105.5	97.5	141	105.5	105.5	141
L8		158	192	198	229.5	232.5	311	288.5	332.5	392	370.5	428	481.5	488	525	689.5
L9		81.5	113.5	81.5	147.5	113.5	196.5	147.5	196.5	196.5	229	196.5	260	229	229	260
X in Degree		45	45		22.5		30		30		24		24		22.5	30
Y in Degree		45	45		22.5		30		30		24		24		22.5	30
Z		8	8		12		12		12		12		12		16	12
U in Degree		45	45		45		30		30		22.5		22.5		30	30
V in Degree		45	45		45		30		30		22.5		22.5		30	30
W		8	8		8		12		12		16		16		12	12

(1) Dimensions are related to motor interface. Please contact APEX for details.
(2) Refer to the AH series(Page 05) for flange interface.

Selection of the optimum gearbox

Selection Start

S5
Cyclic Operation

S1
Continuous Operation

$ED<60\%$
$t_{work}<20mins$
(Eq.1)

YES ← → **NO**

Calculate Ratio i **(Eq.2)** | Calculate Ratio i **(Eq.2)**

Calculate the Mean Output Torque T_{2m} **(Eq.3)** | Calculate the Mean Output Torque T_{2m} **(Eq.3)**

Calculate the Max. Acceleration Torque T_{2max} **(Eq.4)**

Select a Larger Gearbox ← **NO** ← $T_{2max}<T_{2B}$ $T_{2m}<T_{2N}$ → **YES**

$T_{2m}<T_{2N}$ → **NO** → Select a Larger Gearbox

YES

Calculate the Mean Output Speed n_{2m} and the Nominal Output Speed n_{2N} of Gearbox **(Eq.5)** ← **YES**

Select a Smaller Ratio i in Larger Motor If Needed ← **NO** ← $n_{2m}<n_{2N}$

YES

Calculate the Mean Radial F_{2rm} and Axial Loads F_{2am} on Output Shaft of Gearbox **(Eq.6)**

Calculate the Permitted Radial F_{2rB} and Axial Loads F_{2aB} on Output Shaft of Gearbox

$F_{2rm}<F_{2rB}$ $F_{2am}<F_{2aB}$ → **NO** → Select a Larger Gearbox

YES

Select the Required Backlash and Shaft Option

Order your APEX Gearbox

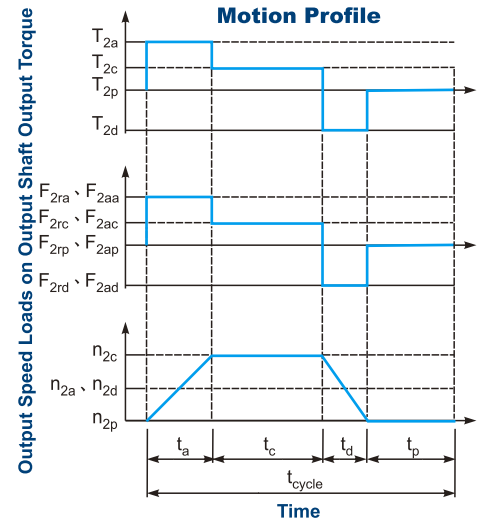**Recommended (for S5 Cycle Operation)**

The general design is given for

$$\frac{J_L}{i^2} \le 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

J_L Load Inertia
J_m Motor Inertia

Motion Profile

Output Speed Loads on Output Shaft Output Torque

T_{2a}, T_{2c}, T_{2p}, T_{2d}

F_{2ra}、F_{2aa}
F_{2rc}、F_{2ac}
F_{2rp}、F_{2ap}
F_{2rd}、F_{2ad}

n_{2c}
n_{2a}、n_{2d}
n_{2p}

t_a t_c t_d t_p
t_{cycle}

Time

1. $ED = \dfrac{t_a + t_c + t_d}{t_{cycle}}$ x 100%, $t_{work} = t_a + t_c + t_d$

Index : a. Acceleration, c. Constant,
   d. Deceleration, p. Pause   **(Eq.1)**

2. $i \cong \dfrac{n_m}{n_{work}}$

n_m Output Speed of the Motor

n_{work} Working Speed   **(Eq.2)**

3. $T_{2m} = \sqrt[3]{\dfrac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$

   (Eq.3)

4. $T_{2max} = T_{mB} \times i \times K_s \times \eta$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2.000 ~ 3,000
1.8	3.000 ~ 5,000

T_{mB} Max. Output Torque of the Motor

η Efficency of the Gearbox   **(Eq.4)**

5. $n_{2a} = n_{2d} = \dfrac{1}{2} \times n_{2c}$

$n_{2m} = \dfrac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$

$n_{2N} = \dfrac{n_{1N}}{i}$ **(Eq.5)**

6. $F_{2rm} = \sqrt[3]{\dfrac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$

$F_{2am} = \sqrt[3]{\dfrac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$

   (Eq.6)

Glossary

Emergency Stop Torque T_{2NOT}	Nm	The Emergency Stop Torque is the maximum permitted torque at the output of gearbox. This may happen only occasionally and may not exceed 1,000 times during the whole service life.
Max. Acceleration Torque T_{2B}	Nm	Under the Cyclic Operation (S5), the Max. Acceleration Torque is the maximum torque which can be transmitted only briefly to the output of gearbox up to 1,000 cycles/hr.
No Load Running Torque	Nm	The No Load Running Torque is the min. torque to overcome the internal friction of a gearbox without loading*.
Nominal Input Speed n_{1N}	rpm	The Nominal Input Speed is the permitted input speed of gearbox by the Continuous Operation (S1) while the housing temperature does not exceed 90°C. This value is measured at environment temperature 25°C.
Max. Input Speed n_{1B}	rpm	The Max. Input Speed is the max. permitted input speed of gearbox by the Cyclic operation (S5). This value is measured at environment temperature 25°C and serves as the absolute limit of the gearbox.
Backlash	arcmin	The Backlash is the maximum angular measurement between two teeth of gears when the transverse operation occurs (refer to Diagram 1). The arcmin is the measurement unit for the backlash. One arcmin equals 1/ 60 degree, symbolized as 1'. Operating pitch circles — Diagram 1 — Backlash (transverse operation)
Torsional Rigidity	Nm/arcmin	Torsional Rigidity is the quotient ($\triangle$T / $\triangle\emptyset$) between the applied torque and resulting torsion angle. This value indicates how much torque is needed on the gearbox to rotate the output shaft for 1 arcmin. The Torsional Rigidity can be determined by Hysteresis Curve. Hysteresis Curve When the input shaft is locked, increase torque at the output slowly up to T_{2B} in both directions and then release the torque gradually. According to the measured torque and torsion angle, a closed curve will be acquired as in the Diagram 2. Backlash (defined) — $\emptyset$(arcmin) — $\triangle\emptyset$ — $\triangle$T — 50% — 100% T(Nm) — -T(Nm) — Test torque — $-\emptyset$(arcmin) — Diagram 2
Radial Load And Axial Load	N	The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings. For more information, please refer to APEX website. L — X — F_{2r} — F_{2a} — F_{2r} Radial Load — F_{2a} Axial Load
Efficiency η	%	The transmission efficiency of the gears inside a gearbox (without friction).
Operating Temperature	º C	The Operating Temperature indicates the temperature of gearbox housing.
Degree of Protection		IP code stands for International Protection standard. The IP65 as example: the first IP number stands for protection degree against dust; the second IP number stands for protection against liquid.
Lubrication		APEX uses synthetic lubrication grease. Alternate greases are available, please contact APEX.
Running Noise	dB(A)	The Running Noise is measured depends on gearbox size, the ratio and the speed*. Higher speed usually induces higher noise level, while higher ratio induces lower noise level.
Moment of Inertia J_1	kg.cm²	The Moment of Inertia J1 is a measurement of the effort applied to an object to maintain its momentary condition at rest or rotating.
Breakaway Torque	Nm	The Breakaway Torque is the minimum torque to start the rotation from the input side of gearbox. A smaller size or a higher ratio gearbox requests less Breakaway Torque.
Back Driving Torque	Nm	The Back Driving Torque is the minimum torque to start the rotation from the output side of gearbox. A larger size or a higher ratio gearbox requires greater Back Driving Torque.

* This value is measured at environment temperature 25°C and the input speed 3,000 rpm. If the Nominal Input Speed n_{1N} of gearbox is lower than 3,000 rpm, this value is measured by that specific Nominal Input Speed.