

User Guide

GR10-1616ETNE



EtherCAT Slave I/O Module

19011282 A02

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Overview

Thank you for purchasing the GR10-1616ETNE EtherCAT communication slave I/O module developed and manufactured independently by Inovance.

This DC24V-powered product is used for EtherCAT communication, coming with 16-point digital NPN output and 16-point digital input.

This guide describes the specifications, characteristics and using methods of the product. Please read this guide carefully before using to ensure safe usage. Visit our website (www.inovance.com) for the latest version of the guide.

Safety Instructions

Safety Disclaimers

- Before installing, using, and maintaining this equipment, read the safety information and precautions thoroughly, and comply with them during operations.
- To ensure the safety of humans and equipment, follow the signs on the equipment and all the safety instructions in this user guide.
- The "CAUTION", "WARNING" and "DANGER" signs are only supplements to the safety instructions.
- Use this equipment according to the designated environment requirements. Damage caused by improper usage is not covered by warranty.
- Inovance shall take no responsibility for any personal injuries or property damage caused by improper usage.

Safety Levels and Definitions

WARNING : Indicates that failure to comply with the notice may result in severe personal injuries or even death.

CAUTION : The "CAUTION" sign indicates that failure to comply with the notice may result in minor or moderate personal injury or damage to the equipment.

Please keep this guide well so that it can be read when necessary and forward this guide to the end user.

During control system design

- Provide a safety circuit outside the PLC so that the control system can still work safely once external power failure or PLC fault occurs.
- Add a fuse or circuit breaker because the module may smoke or catch fire due to long-time overcurrent caused by operation above rated current or load short-circuit.

- An emergency stop circuit, a protection circuit, a forward/reverse operation interlocked circuit, and a upper position limit and lower position limit interlocked circuit must be set in the external circuits of PLC to prevent damage to the machine.
- To ensure safe operation, for the output signals that may cause critical accidents, design external protection circuit and safety mechanism;
- Once PLC CPU detects abnormality in the system, all outputs may be closed; however, when a fault occurs in the controller circuit, the output may not be under control. Therefore, it is necessary to design an appropriate external control circuit to ensure normal operation;
- If the PLC output units such as relays or transistors are damaged, the output may fail to switch between ON and OFF states according to the commands;
- The PLC is designed to be used in indoor electrical environment (overvoltage category II). The power supply must have a system-level lightning protection device, assuring that overvoltage due to lightning shock cannot be applied to the PLC power supply input terminals, signal input terminals and output terminals and so forth, so as to avoid damage to the equipment.

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Installation

- WARNING**
 - Installation must be carried out by the specialists who have received the necessary electrical training and understood enough electrical knowledge.
 - Disconnect all external power supplies of the system before removing/installing the module. Failure to do so may result in electric shock, module fault or malfunction.
 - Do not use the PLC where there are dust, oil smoke, conductive dust, corrosive or combustible gases, or exposed to high temperature, condensation, wind & rain, or subject to vibration and impact. Electric shock, fire and malfunction may also result in damage or deterioration to the product.
 - The PLC is open-type equipment that must be installed in a control cabinet with lock (cabinet housing protection >IP20). Only the personnel who have received the necessary electrical training and understood enough electrical knowledge can open the cabinet.

- CAUTION**
 - Prevent metal filings and wire ends from dropping into ventilation holes of the PLC during installation. Failure to comply may result in fire, fault and malfunction.
 - Ensure there are no foreign matters on ventilation surface. Failure to comply may result in poor ventilation, which may cause fire, fault and malfunction.
 - Ensure the module is connected to the respective connector securely and hook the module firmly. Improper installation may result in malfunction, fault or fall-off.

Wiring

- WARNING**
 - Wiring must be carried out by personnel who have received the necessary electrical training and understood enough electrical knowledge.
 - Disconnect all external power supplies of the system before wiring. Failure to comply may result in electric shock, module fault or malfunction.
 - Install the terminal cover attached to the product before power-on or operation after wiring is completed. Failure to comply may result in electric shock
 - Perform good insulation on terminals so that insulation distance between cables will not reduce after cables are connected to terminals. Failure to comply may result in electric shock or damage to the equipment.

- CAUTION**
 - Prevent dropping metal filings and wire ends drop into ventilation holes of the PLC at wiring. Failure to comply may result in fire, fault and malfunction.
 - The external wiring specification and installation method must comply with local regulations. For details, see the wiring section in this guide.
 - To ensure safety of equipment and operator, use cables with sufficient diameter and connect the cables to ground reliably.
 - Ensure that all cables are connected to the correct interface. Failure to comply may result in module and external equipment fault.
 - Tighten bolts on the terminal block in the specified torque range. If the terminal is not tight, short-circuit, fire or malfunction may be caused. If the terminal is too tight, fall-off, short-circuit, fire or malfunction may be caused.
 - If the connector is used to connect with external equipment, perform correct crimping or welding with the tool specified by manufacturer. If connection is in poor contact, short-circuit, fire or malfunction may be caused.
 - A label on the top of the module is to prevent foreign matters entering the module. Do not remove the label during wiring. Remember to remove it before system operation, facilitating ventilation.
 - Do not bundle control wires, communication wires and power cables together. They must be run with distance of more than 100 mm. Otherwise, noise may result in malfunction.
 - Select shielded cable for high-frequency signal input/output in applications with serious interference so as to enhance system anti-interference ability.

Operation and Maintenance

- WARNING**
 - Maintenance & inspection must be carried out by personnel who have the necessary electrical training and experience.
 - Do not touch the terminals while the power is on. Failure to comply may result in electric shock or malfunction.
 - Disconnect all external power supplies of the system before cleaning the module or re-tightening screws on the terminal block or screws of the connector. Failure to comply may result in electric shock.
 - Disconnect all external power supplies of the system before removing the module or connecting/removing the communication wirings. Failure to comply may result in electric shock or malfunction.

- CAUTION**
 - Get with the guide and ensure safety before online modification, forcible output, and RUN/STOP operation.
 - Disconnect the power supply before installing/removing the extension card.

Disposal

- CAUTION**
 - Treat scrapped module as industrial waste. Dispose the battery according to local laws and regulations.

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Product Information

Model Number and Nameplate

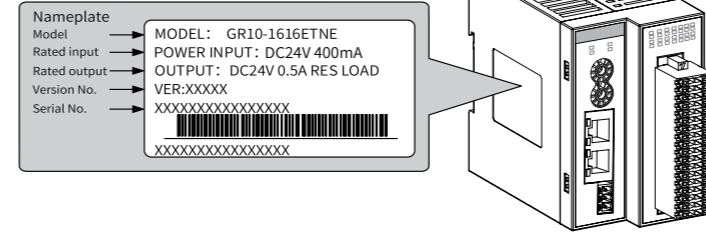
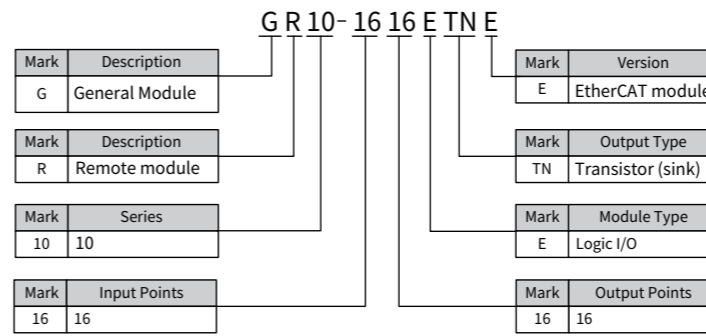


Figure 1 Description of model number and nameplate

Model	Category	Description
GR10-1616ETNE	EtherCAT communication slave module	16-Point DO, transistor output (sink); 16-point DI (source and sink)

External Interface

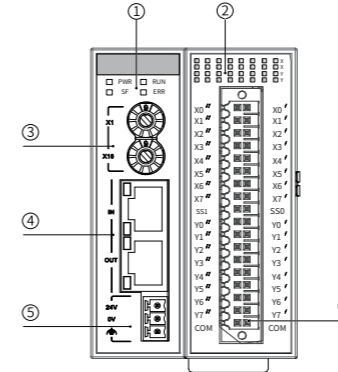


Figure 2 Diagram of module interfaces

Interface Name	Function
① Signal indicator	PWR Power indicator Green ON when power supply is switched on
	RUN Running status indicator Green ON when the module is in normal operation
	SF Fault indicator Red Is ON when the module is faulty
	ERR State machine error indicator Red Is ON when an error occurs in the state machine
② I/O signal indicator	For input and output signals ON: signal active OFF: signal inactive
③ Address DIP switch	Slave address setting switch: ADDR1/ADDR0: address DIP switch, address is set in hexadecimal, slave decimal address = ADDR1*16+ADDR0*1 1-255
④ EtherCAT communication interface	X1 IN: EtherCAT input X2 OUT: EtherCAT output for connecting back-end EtherCAT slaves
⑤ 24 V power input	For module power supply input
⑥ User output	See "Electrical Design Reference" for details

General Specifications

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Item	Specifications
Power supply specifications	24 VDC (20.4 VDC-28.8 VDC) (-15% to +20%)
Communication protocol	EtherCAT industrial real-time bus protocol
Max. communication speed	100 Mbps
Network port/network cable	Standard network port with Cat 5e network cables below 100 meters
Station number range	1 to 255 if set by a DIP switch, or automatically allocated by a network bus

The specific performance indicators are as follows:

Item	Specifications
Communication protocol	EtherCAT protocol
Service supported	CoE (PDO, SDO), FoE
Min. synchronization period of the 6-axis cam	1250 us (TYP)
Synchronization mode	Input and output synchronization or DC-distributed clock
Physical layer	100BASE-TX
Baud rate	100 Mbit/s (100Base-TX)
Duplex mode	Full duplex
Topological structure	Linear topological structure
Transmission medium	Network cables, see the Wiring section
Transmission distance	Less than 100 m between two nodes
EtherCAT frame length	44-1,498 bytes
Process data	Max. 1486 bytes per frame
Synchronization jitter of two slave stations	< 1us
Update time	30 us for 1,000 digital inputs and outputs; 100 us for 32 servo axes

Output specification

Item	Specifications	
Output channels	16	
Output connection method	Leaf spring terminal	
Output type	Transistor, low-side output	
Power supply voltage	24 VDC (-15% to +20%)	
Output voltage class	24 VDC (-15% to +20%)	
Max. leakage current at OFF	Less than 0.5 mA	
Response time when the module is turned ON	Less than 0.5 ms (for hardware)	
Response time when the module is turned OFF	Less than 0.5 ms (for hardware)	
Max. load	Resistive load	0.5 A/point, 2 A/common terminal ^[1]
	Inductive load	12 W/24 VDC (total)
	Lamp load	2 W/24 VDC (total)
Isolation mode	Opto-couplers isolation	
Output action display	Output indicator ON when optocoupler drive is activated	
Short circuit-proof output	Yes	

NOTE [1]: The COM and 0V Power Supply terminal need to be short connected additionally when the output Current is overloaded (> 1A).

Input specification

Item	Specifications
Input channels	16
Input connection method	Leaf spring terminal
Input type	Digital input
Input mode	SINK/SOURCE
Input voltage class	24 VDC (max.: 30 V)
Input current (typical)	4 mA
On voltage	> 15 VDC
Off voltage	< 5 VDC

Item	Specifications
Port hardware filter time constant	10 ms
Input resistance	4.3 K
Input signal form	DC voltage input, supporting SINK/SOURCE input
Isolation mode	Opto-couplers isolation
Input action display	Input indicator ON when the input is in the driving state

Mechanical Design Reference

Mounting Dimensions

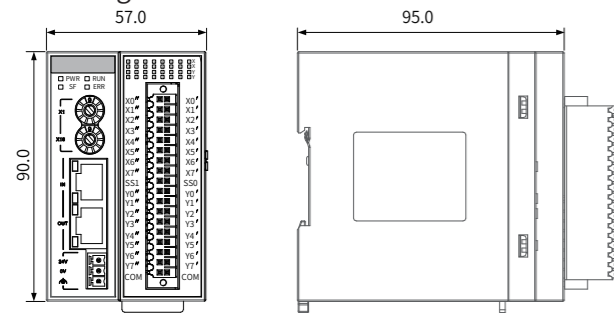
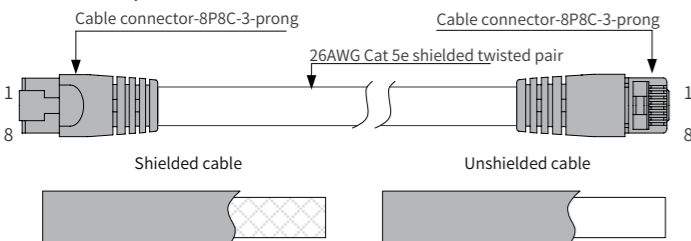


Figure 3 Mounting dimensions (in mm)

Electrical Design Reference

EtherCAT Cable Selection

Cable Preparation



* Use Cat 5e shielded twisted pair (STP) cables, with injection molded and iron shelled connector.

Signal pins

Pin	Signal	Signal Direction	Signal Description	Pin	Signal	Signal Direction	Signal Description
1	TD+	Output	Data transmission+	5	--	--	Not used
2	TD-	Output	Data transmission-	6	RD-	Input	Data reception-
3	RD+	Input	Data reception+	7	--	--	Not used
4	--	--	Not used	8	--	--	Not used

Length requirements:

According to FastEthernet technology, when an EtherCAT bus is used, the length of the cable between the devices must not exceed 100 meters. Exceeding this length will attenuate the signal and affect communication.

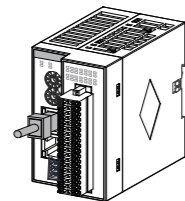
Technical requirements:

100% continuity test, no short circuit, open circuit, misalignment and poor contact; use a shielded cable as the EtherCAT bus for network data transmission, with the following recommended specifications:

Item	Specifications
Cable type	Flexible crossover cable, S-FTP, Cat 5e
Complied standards:	EIA/TIA568A, EN50173, ISO/IEC11801 EIA/TI Abulletin TSB, EIA/TIA SB40-A&TSB36
Conductor type	Twisted pair
Pair	4

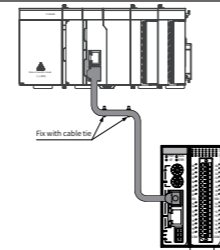
Communication Wiring

Insert the cable into the EtherCAT port of the communication module until you hear a click sound.



Requirements for securing communication cable

To protect the communication cable from any tension and to ensure communication stability, fix the cable end which is near the device before EtherCAT communication, as shown on the right:



Fault Indication and Troubleshooting for EtherCAT Slave Station Module

LED indicator	Indication	Solution
RUN	OFF	EtherCAT master and slaves are initialized
	Blinking	EtherCAT slave is in a state other than OP
ERR	Blinking	Communication error between EtherCAT master and slave
SF	Steady ON	Output channel is faulty

Connection of User Output Terminals

Cable Selection

Material Name	Model	Applicable Cable		Manufacturer	Crimping Tool
		MM ²	AWG		
Tubular lug	GTVE07512	0.75	21	Suzhou Yuanli	YAC-5

Those cable lugs are applicable to this module, and the cable rated temperature is required to be above 75°C.

Cable Preparing Procedures

- Remove the insulation of the cable so that a length of 11-14 mm of the conductor is exposed, and put the cable through a cable marking sleeve.
- Insert the exposed end into the hole of the cable lug, and then crimp it with recommended crimping tool.

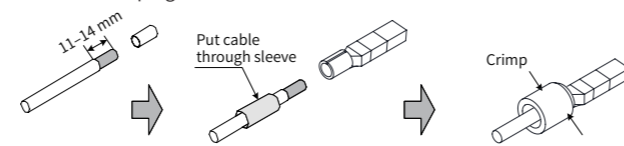


Figure 4 Diagram of cable preparing

Terminal Layout

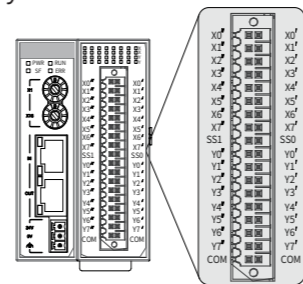
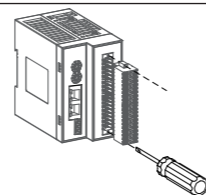


Figure 5 Terminal layout

External Wiring

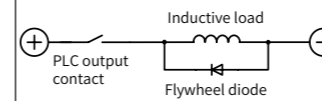
Precautions

After the IO terminal block is mounted to CNS, fix it with a torque of 0.2-0.25 N m, as shown in the figure.



Contact protection in the case of inductive load:

when the inductive load is applied, large back EMF will be produced between contacts and arc discharge is also caused when the inductive load stops. This may result in contact failure or contact sag, shortening the contact lifetime. Therefore, you can use a parallel flywheel diode with the load to extend the lifetime of the product. The freewheel diode must satisfy: ① reverse voltage is 5 to 10 times of load voltage; ② forward current is larger than load current.

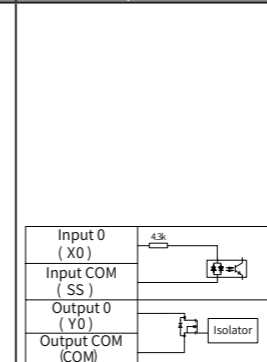


- Do not bundle the terminal connection cables together with power cables (high voltage, large current) which produce strong interference signals. Separate it from other cables and avoid cabling in parallel.
- Use recommended cables and adapter boards. It is recommended to use shielded cables as terminal cables for increased anti-interference ability.

External Wiring

Ext. Wiring	Signal Name	Terminal No.	Signal Name	Terminal No.	Ext. Wiring
	CHI input 0 (CHI-X0)	2	CHO input 0 (CHO-X0)	1	
	CHI input 1 (CHI-X1)	4	CHO input 1 (CHO-X1)	3	
	CHI input 2 (CHI-X2)	6	CHO input 2 (CHO-X2)	5	
	CHI input 3 (CHI-X3)	8	CHO input 3 (CHO-X3)	7	
	CHI input 4 (CHI-X4)	10	CHO input 4 (CHO-X4)	9	
	CHI input 5 (CHI-X5)	12	CHO input 5 (CHO-X5)	11	
	CHI input 6 (CHI-X6)	14	CHO input 6 (CHO-X6)	13	
	CHI input 7 (CHI-X7)	16	CHO input 7 (CHO-X7)	15	
	CHI COM (SS1)	18	CHO COM (SS0)	17	
Load	CHI output 0 (CHI-Y0)	20	CHO output 0 (CHO-Y0)	19	Load
Load	CHI output 1 (CHI-Y1)	22	CHO output 1 (CHO-Y1)	21	Load
Load	CHI output 2 (CHI-Y2)	24	CHO output 2 (CHO-Y2)	23	Load
Load	CHI output 3 (CHI-Y3)	26	CHO output 3 (CHO-Y3)	25	Load
Load	CHI output 4 (CHI-Y4)	28	CHO output 4 (CHO-Y4)	27	Load
Load	CHI output 5 (CHI-Y5)	30	CHO output 5 (CHO-Y5)	29	Load
Load	CHI output 6 (CHI-Y6)	32	CHO output 6 (CHO-Y6)	31	Load
Load	CHI output 7 (CHI-Y7)	34	CHO output 7 (CHO-Y7)	33	Load
24VDC	CHI COM (COM)	36	CHO COM (COM)	35	24VDC

Internal Equivalent Circuit



INOVANCE Warranty Agreement

The warranty period of the product is 18 months (The period is subject to the date information indicated by the barcode on the product, or the terms and conditions of the purchase contract if otherwise specified). During the warranty period, if the product fails or is damaged under the condition of normal use by following the instructions, Inovance will be responsible for free maintenance.

Within the warranty period, maintenance will be charged for the damages due to the following causes:

- Improper use or uninstallation/repair/modification without prior permission
- Fire, flood, abnormal voltage, other disasters, and secondary disasters
- Hardware damage caused by dropping or transportation after procurement
- Failure to operate the product by observing the User Guide provided by Inovance
- Faults and damages caused by factors outside of the product (such as peripheral devices)

If there is any failure or damage to the product, correctly fill out the Product Warranty Card.

The maintenance fee is charged as the latest Maintenance Price List of Inovance.

The Product Warranty Card is not re-issued. Keep the card and present it to the maintenance personnel when seeking maintenance.

If there is any problem during the service, contact us or our agent directly.

You are assumed to agree on terms and conditions of this warranty agreement by purchase of the product. This agreement shall be interpreted by Inovance.